BQ27426 System-Side Impedance Track™ Fuel Gauge

1 Features

- Single-cell Li-ion battery fuel gauge
  - Resides on system board
  - Supports embedded or removable batteries
  - Powers directly from the battery with integrated LDO
  - Supports a low-value external sense resistor (10 mΩ)
- Ultra low 9 µA operating current when the load is below 10 mA, set by *Sleep Current* threshold.
- Battery fuel gauging based on patented Impedance Track™ technology
  - Provides three selectable preprogrammed profiles for 4.2-V, 4.35-V, and 4.4-V cells
  - Reports remaining capacity and state-of-charge (SOC) with smoothing filter
  - Adjusts automatically for battery aging, self-discharge, temperature, and rate changes
  - Estimates battery state-of-health (aging)
- Microcontroller peripheral interface supports:
  - 400-kHz I^{2}C serial interface
  - Configurable SOC interrupt or battery low digital output warning
  - Internal temperature sensor or host reported temperature or external thermistor

2 Applications

- Smartphones, feature phones, and tablets
- Wearables
- Building automation
- Portable medical/industrial handsets
- Portable audio
- Gaming

3 Description

The Texas Instruments BQ27426 battery fuel gauge is a single-cell gauge that requires minimal user-configuration and system microcontroller firmware development, leading to quick system bring-up.

Three chemistry profiles are preprogrammed to enable minimum user-configuration, and to help manage customer inventory across projects with different battery chemistries. The BQ27426 battery fuel gauge has very low sleep power consumption leading to longer battery run time. Configurable interrupts help save system power and free up the host from continuous polling. Accurate temperature sensing is supported via an external thermistor.
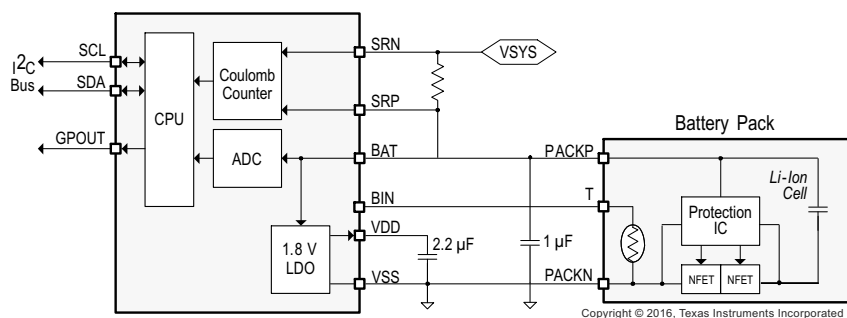
The BQ27426 battery fuel gauge uses the patented Impedance Track™ algorithm for fuel gauging, and provides information such as remaining battery capacity (mAh), state-of-charge (%), and battery voltage (mV).

Battery fuel gauging with the BQ27426 fuel gauge requires connections only to PACK+ (P+) and PACK– (P–) for a removable battery pack or embedded battery circuit. The tiny, 9-ball, 1.62 mm × 1.58 mm, 0.5 mm pitch NanoFree™ chip scale package (DSBGA) is ideal for space-constrained applications.

Device Information

PART NUMBER	PACKAGE	BODY SIZE (NOM)
BQ27426	YZF (9)[1]	1.62 mm × 1.58 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision F (July 2019) to Revision G (April 2023)   **Page**
- Clarified SLEEP mode current...1
- Clarified SLEEP mode current...6
- Added detailed descriptions of power modes..12

Changes from Revision E (May 2019) to Revision F (July 2019)   **Page**
- Added Section 7.3.1.2 11
- Changed Figure 8-2 15

Changes from Revision D (May 2016) to Revision E (May 2019)   **Page**
- Added the low-side current sense resistor...15
- Updated Typical Applications 15

5 Pin Configuration and Functions
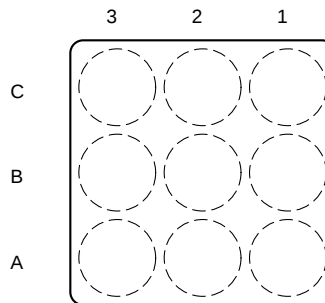
Figure 5-1. Top View
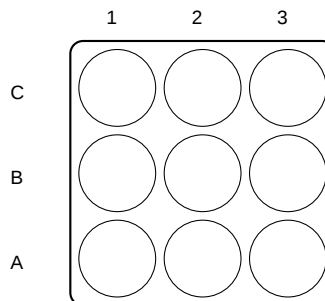
Figure 5-2. Bottom View

Table 5-1. Pin Functions

PIN		TYPE[1]	DESCRIPTION
NAME	NUMBER		
BAT	C3	PI, AI	LDO regulator input and battery voltage measurement input. Kelvin sense connect to positive battery terminal (PACKP). Connect a capacitor (1 µF) between BAT and V_{SS}. Place the capacitor close to the gauge.
BIN	B1	DI	Battery insertion detection input. If *OpConfig [BI_PU_EN]* = 1 (default), a logic low on the pin is detected as battery insertion. For a removable pack, the BIN pin can be connected to V_{SS} through a pulldown resistor on the pack, typically the 10-kΩ thermistor; the system board should use a 1.8-MΩ pullup resistor to V_{DD} to ensure the BIN pin is high when a battery is removed. If the battery is embedded in the system, it is recommended to leave *[BI_PU_EN]* = 1 and use a 10-kΩ pulldown resistor from BIN to V_{SS}. If *[BI_PU_EN]* = 0, then the host must inform the gauge of battery insertion and removal with the *BAT_INSERT* and *BAT_REMOVE* subcommands. A 10-kΩ pulldown resistor should be placed between BIN and V_{SS}, even if this pin is unused. **NOTE:** The BIN pin must not be shorted directly to V_{CC} or V_{SS} and any pullup resistor on the BIN pin must be connected only to V_{DD} and not an external voltage rail. If an external thermistor is used for temperature input, the thermistor should be connected between this pin and V_{SS}.
GPOUT	A1	DO	This open-drain output can be configured to indicate BAT_LOW when the *OpConfig [BATLOWEN]* bit is set. By default *[BATLOWEN]* is cleared and this pin performs an interrupt function (SOC_INT) by pulsing for specific events, such as a change in state-of-charge. Signal polarity for these functions is controlled by the *[GPIOPOL]* configuration bit. This pin should not be left floating, even if unused; therefore, a 10-kΩ pullup resistor is recommended. If the device is in SHUTDOWN mode, toggling GPOUT causes the gauge exit SHUTDOWN. Connect GPOUT to a GPIO of the host MCU so that in case of any inadvertent shutdown condition, the gauge can be commanded to come out of SHUTDOWN.

Product Folder Links: *BQ27426*

Table 5-1. Pin Functions (continued)

PIN		TYPE[1]	DESCRIPTION
NAME	NUMBER		
SCL	A3	DIO	Slave I²C serial bus for communication with system (Master). Open-drain pins. Use with external 10-kΩ pullup resistors (typical) for each pin. If the external pullup resistors will be disconnected from these pins during normal operation, use an external 1-MΩ pulldown resistors to V_{SS} at each pin to avoid floating inputs.
SDA	A2	DIO	
SRN	C2	AI	Coulomb counter differential inputs expecting an external 10 mΩ, 1% sense resistor in the high-side current path. Kelvin sense connect SRP to the positive battery terminal (PACKP) side of the external sense resistor. Kelvin sense connect SRN to the other side of the external sense resistor, the positive connection to the system (VSYS). No calibration is required. The fuel gauge is precalibrated for a standard 10 mΩ, 1% sense resistor.
SRP	C1	AI	Low-side current sensing can be enabled. For more information, see *Typical Applications*.
V_{DD}	B3	PO	1.8-V regulator output. Decouple with 2.2-µF ceramic capacitor to V_{SS}. This pin is not intended to provide power for other devices in the system.
V_{SS}	B2	PI	Ground pin

(1)   IO = Digital input-output, AI = Analog input, P = Power connection

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)[1]

		MIN	MAX	UNIT
V_{BAT}	BAT pin input voltage range	−0.3	6	V
V_{SR}	SRP and SRN pins input voltage range	−0.3	V_{BAT} + 0.3	V
	Differential voltage across SRP and SRN. ABS(SRP − SRN)		2	V
V_{DD}	V_{DD} pin supply voltage range (LDO output)	−0.3	2	V
V_{IOD}	Open-drain IO pins (SDA, SCL)	−0.3	6	V
V_{IOPP}	Push-pull IO pins (BIN)	−0.3	V_{DD} + 0.3	V
T_A	Operating free-air temperature range	−40	85	°C
Storage temperature, T_{stg}		−65	150	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001[1]	±1500	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101[2]	±250	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

T_A = 30°C and V_{REGIN} = V_{BAT} = 3.6 V (unless otherwise noted)

			MIN	NOM	MAX	UNIT
C_{BAT} [1]	External input capacitor for internal LDO between BAT and V_{SS}	Nominal capacitor values specified. Recommend a 5% ceramic X5R-type capacitor located close to the device.		0.1		µF
C_{LDO18} [1]	External output capacitor for internal LDO between V_{DD} and V_{SS}			2.2		µF
V_{PU} [1]	External pullup voltage for open-drain pins (SDA, SCL, GPOUT)		1.62		3.6	V

(1) Specified by design. Not production tested.

6.4 Thermal Information

	THERMAL METRIC[1]	BQ27426 YZF (DSBGA) 9 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	64.1	°C/W
$R_{\theta JCtop}$	Junction-to-case (top) thermal resistance	59.8	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	52.7	°C/W
ψ_{JT}	Junction-to-top characterization parameter	0.3	°C/W
ψ_{JB}	Junction-to-board characterization parameter	28.3	°C/W
$R_{\theta JCbot}$	Junction-to-case (bottom) thermal resistance	2.4	°C/W

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics Application Report*, SPRA953.

6.5 Supply Current

T_A = 30°C and V_{REGIN} = V_{BAT} = 3.6 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_{CC} [1]	NORMAL mode current	I_{LOAD} > *Sleep Current* [2] (10mA typical)		50		µA
I_{SLP} [1]	SLEEP mode current (data measurement every 20-sec)	I_{LOAD} < *Sleep Current* [2] (10mA typical)		9		µA
I_{SD} [1]	SHUTDOWN mode current	Fuel gauge in host commanded SHUTDOWN mode. (LDO regulator output disabled)		0.6		µA

(1)   Specified by design. Not production tested.
(2)   Wake Comparator Disabled.

6.6 Digital Input and Output DC Characteristics

T_A = –40°C to 85°C, typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH(OD)}$	Input voltage, high[2]	External pullup resistor to V_{PU}	V_{PU} × 0.7			V
$V_{IH(PP)}$	Input voltage, high [3]		1.4			V
V_{IL}	Input voltage, low[2] [3]				0.6	V
V_{OL}	Output voltage, low[2]				0.6	V
I_{OH}	Output source current, high[2]				0.5	mA
$I_{OL(OD)}$	Output sink current, low[2]				–3	mA
C_{IN} [1]	Input capacitance[2] [3]				5	pF
I_{lkg}	Input Leakage Current (SCL, SDA, BIN, GPOUT)				1	µA

(1)   Specified by design. Not production tested.
(2)   Open Drain pins: (SCL, SDA, GPOUT)
(3)   Push-Pull pin: (BIN)

6.7 LDO Regulator, Wake-up, and Auto-Shutdown DC Characteristics

T_A = –40°C to 85°C, typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{BAT}	BAT pin regulator input		2.45		4.5	V
V_{DD}	Regulator output voltage			1.85		V
$UVLO_{IT+}$	V_{BAT} undervoltage lock-out LDO wake-up rising threshold			2		V
$UVLO_{IT–}$	V_{BAT} undervoltage lock-out LDO auto-shutdown falling threshold			1.95		V
V_{WU+} [1]	GPOUT (input) LDO Wake-up rising edge threshold[2]	LDO Wake-up from SHUTDOWN mode	1.2			V

(1)   Specified by design. Not production tested.
(2)   If the device is commanded to SHUTDOWN via I²C with V_{BAT} > $UVLO_{IT+}$, a wake-up rising edge trigger is required on GPOUT.

6.8 LDO Regulator, Wake-up, and Auto-Shutdown AC Characteristics

T_A = –40°C to 85°C, typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_{SHDN} [1]	SHUTDOWN entry time	Time delay from SHUTDOWN command to LDO output disable.			250	ms
t_{SHUP} [1]	SHUTDOWN GPOUT low time	Minimum low time of GPOUT (input) in SHUTDOWN before WAKEUP	10			µs
t_{VDD} [1]	Initial V_{DD} output delay			13		ms

6.8 LDO Regulator, Wake-up, and Auto-Shutdown AC Characteristics (continued)

T_A = –40°C to 85°C, typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_{WUVDD} [1]	Wake-up V_{DD} output delay	Time delay from rising edge of GPOUT (input) to nominal V_{DD} output		8		ms
t_{PUCD}	Power-up communication delay	Time delay from rising edge of REGIN to the Active state. Includes firmware initialization time		250		ms

(1) Specified by design. Not production tested.

6.9 ADC (Temperature and Cell Measurement) Characteristics

T_A = –40°C to 85°C; typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)[1]

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IN(BAT)}$	BAT pin voltage measurement range	Voltage divider enabled	2.45		4.5	V
t_{ADC_CONV}	Conversion time			125		ms
	Effective resolution			15		bits

(1) Specified by design. Not tested in production.

6.10 Integrating ADC (Coulomb Counter) Characteristics

T_A = –40°C to 85°C; typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)[1]

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{SR}	Input voltage range from BAT to SRP/SRN pins			BAT ± 25		mV
t_{SR_CONV}	Conversion time	Single conversion		1		s
	Effective Resolution	Single conversion		16		bits

(1) Specified by design. Not tested in production.

6.11 I²C-Compatible Interface Communication Timing Characteristics

T_A = –40°C to 85°C; typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)[1]

			MIN	NOM	MAX	UNIT
Standard Mode (100 kHz)						
$t_{d(STA)}$	Start to first falling edge of SCL		4			µs
$t_{w(L)}$	SCL pulse duration (low)		4.7			µs
$t_{w(H)}$	SCL pulse duration (high)		4			µs
$t_{su(STA)}$	Setup for repeated start		4.7			µs
$t_{su(DAT)}$	Data setup time	Host drives SDA	250			ns
$t_{h(DAT)}$	Data hold time	Host drives SDA	0			ns
$t_{su(STOP)}$	Setup time for stop		4			µs
$t_{(BUF)}$	Bus free time between stop and start	Includes Command Waiting Time	66			µs
t_f	SCL or SDA fall time[1]				300	ns
t_r	SCL or SDA rise time[1]				300	ns
f_{SCL}	Clock frequency[2]				100	kHz
Fast Mode (400 kHz)						
$t_{d(STA)}$	Start to first falling edge of SCL		600			ns
$t_{w(L)}$	SCL pulse duration (low)		1300			ns
$t_{w(H)}$	SCL pulse duration (high)		600			ns
$t_{su(STA)}$	Setup for repeated start		600			ns
$t_{su(DAT)}$	Data setup time	Host drives SDA	100			ns

Product Folder Links: BQ27426

6.11 I²C-Compatible Interface Communication Timing Characteristics (continued)

T_A = –40°C to 85°C; typical values at T_A = 30°C and V_{REGIN} = 3.6 V (unless otherwise noted)[1]

			MIN	NOM	MAX	UNIT
$t_{h(DAT)}$	Data hold time	Host drives SDA	0			ns
$t_{su(STOP)}$	Setup time for stop		600			ns
$t_{(BUF)}$	Bus free time between stop and start	Includes Command Waiting Time	66			µs
t_f	SCL or SDA fall time[1]				300	ns
t_r	SCL or SDA rise time[1]				300	ns
f_{SCL}	Clock frequency[2]				400	kHz

(1) Specified by design. Not production tested.
(2) If the clock frequency (f_{SCL}) is > 100 kHz, use 1-byte write commands for proper operation. All other transactions types are supported at 400 kHz. (See Section 7.3.1.1 and Section 7.3.1.3.)
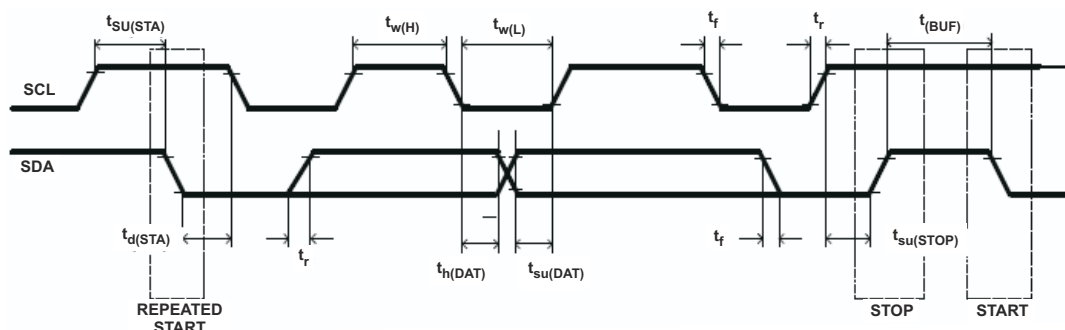

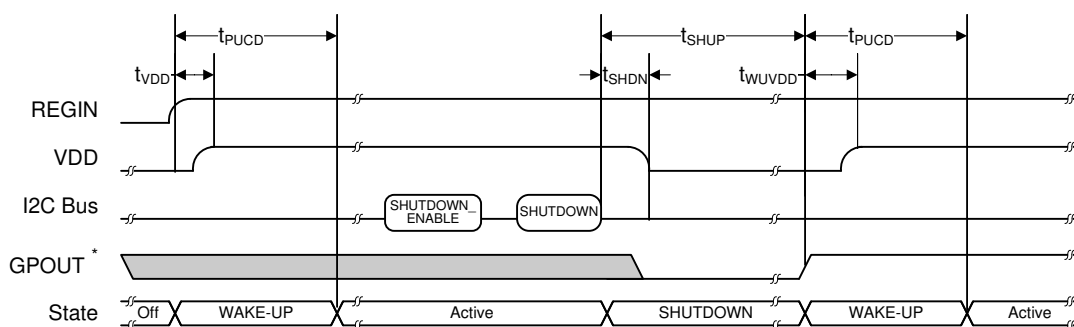**Figure 6-1. I²C-Compatible Interface Timing Diagrams**

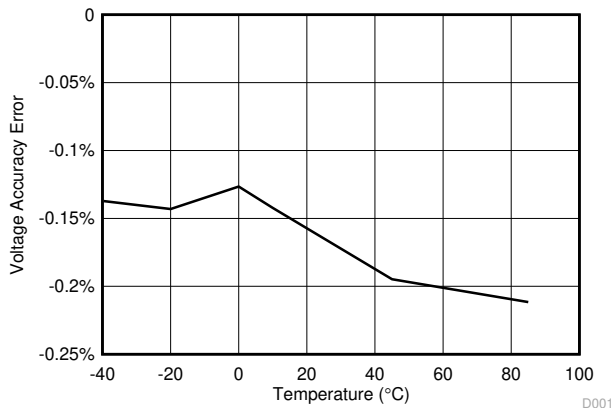## 6.12 SHUTDOWN and WAKE-UP Timing

* GPOUT is configured as an input for wake-up signaling.
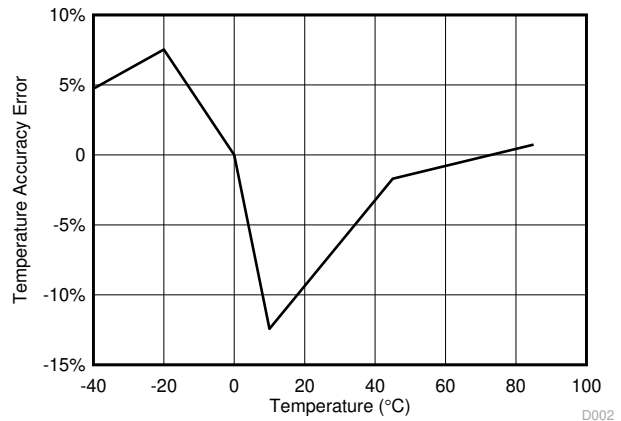
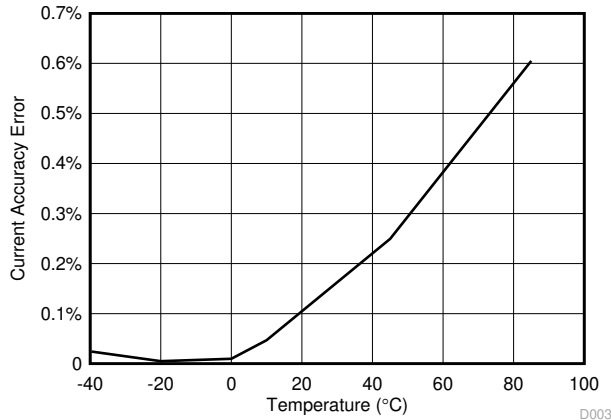**Figure 6-2. SHUTDOWN and WAKE-UP Timing Diagram**

6.13 Typical Characteristics

Figure 6-3. Voltage Accuracy Error

Figure 6-4. Internal Temperature Accuracy Error

Figure 6-5. Current Accuracy Error

7 Detailed Description

7.1 Overview

The BQ27426 fuel gauge accurately predicts the battery capacity and other operational characteristics of a single Li-based rechargeable cell. It can be interrogated by a system processor to provide cell information, such as state-of-charge (SOC).

Note

The following formatting conventions are used in this document:

**Commands**: *italics* with parentheses() and no breaking spaces, for example, *Control()*.

Data flash: *italics*, **bold**, and breaking spaces, for example, ***Design Capacity***.

Register bits and flags: *italics* with brackets [ ], for example, *[TDA]*

Data flash bits: *italics*, **bold**, and brackets [ ], for example, ***[LED1]***

Modes and states: ALL CAPITALS, for example, UNSEALED mode

7.2 Functional Block Diagram

Copyright © 2016, Texas Instruments Incorporated
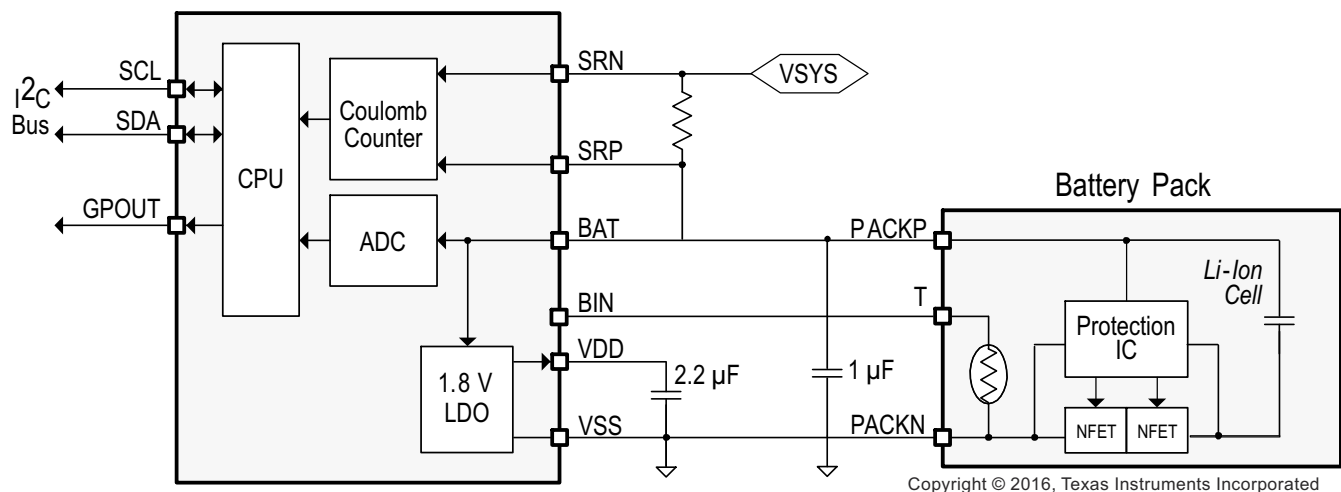
7.3 Feature Description

Information is accessed through a series of commands, called *Standard Commands*. Further capabilities are provided by the additional *Extended Commands* set. Both sets of commands, indicated by the general format *Command)*, are used to read and write information contained within the control and status registers, as well as its data locations. Commands are sent from system to gauge using the I^{2}C serial communications engine, and can be executed during application development, system manufacture, or end-equipment operation.

The key to the high-accuracy gas gauging prediction is Texas Instruments proprietary Impedance Track™ algorithm. This algorithm uses cell measurements, characteristics, and properties to create state-of-charge predictions that can achieve high accuracy across a wide variety of operating conditions and over the lifetime of the battery.

The fuel gauge measures the charging and discharging of the battery by monitoring the voltage across a small-value sense resistor. When a cell is attached to the fuel gauge, cell impedance is computed based on cell current, cell open-circuit voltage (OCV), and cell voltage under loading conditions.

The fuel gauge uses an integrated temperature sensor for estimating cell temperature. Alternatively, the host processor can provide temperature data for the fuel gauge.

For more details, see the *BQ27426 Technical Reference Manual*.

7.3.1 Communications

7.3.1.1 I^2C Interface

The fuel gauge supports the standard I^2C read, incremental read, quick read, one-byte write, and incremental write functions. The 7-bit device address (ADDR) is the most significant 7 bits of the hex address and is fixed as 1010101. The first 8 bits of the I^2C protocol are, therefore, 0xAA or 0xAB for write or read, respectively.
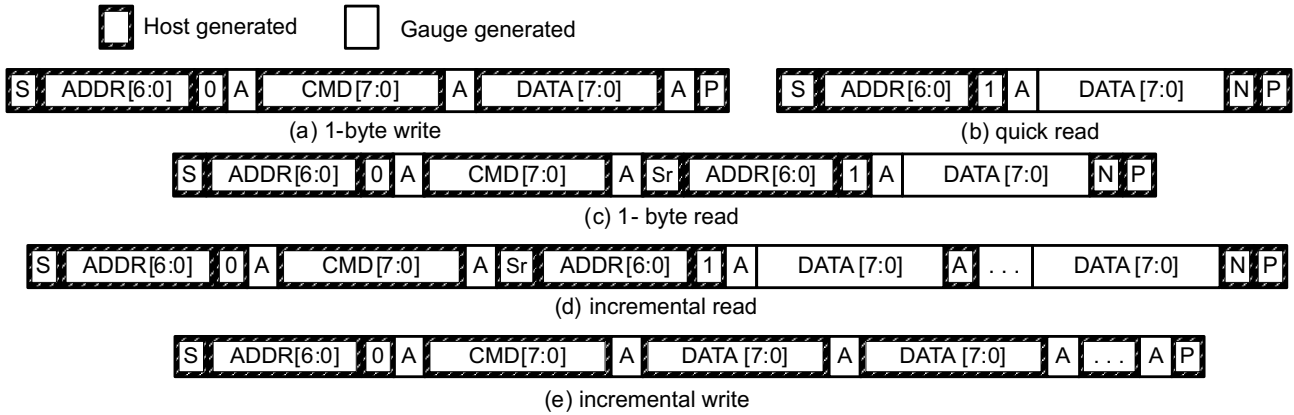
Figure 7-1. I^2C Interface

The quick read returns data at the address indicated by the address pointer. The address pointer, a register internal to the I^2C communication engine, increments whenever data is acknowledged by the fuel gauge or the I^2C master. "Quick writes" function in the same manner and are a convenient means of sending multiple bytes to consecutive command locations (such as two-byte commands that require two bytes of data).

The following command sequences are not supported:
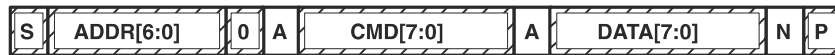
Figure 7-2. Attempt To Write a Read-only Address (NACK After Data Sent By Master)

Figure 7-3. Attempt To Read an Address Above 0x6B (NACK Command)

7.3.1.2 I^2C Time Out

The I^2C engine releases SDA and SCL if the I^2C bus is held low for two seconds. If the fuel gauge is holding the lines, releasing them frees them for the master to drive the lines. If an external condition is holding either of the lines low, the I^2C engine enters the low-power SLEEP mode.

7.3.1.3 I^2C Command Waiting Time

To ensure proper operation at 400 kHz, a $t_{(BUF)} \geq 66$ µs bus-free waiting time must be inserted between all packets addressed to the fuel gauge. In addition, if the SCL clock frequency (f_{SCL}) is > 100 kHz, use individual 1-byte write commands for proper data flow control. The following diagram shows the standard waiting time required between issuing the control subcommand the reading the status result. For read-write standard command, a minimum of 2 seconds is required to get the result updated. For read-only standard commands, there is no waiting time required, but the host must not issue any standard command more than two times per second. Otherwise, the gauge could result in a reset issue due to the expiration of the watchdog timer.

| S | ADDR [6:0] | 0 | A | CMD [7:0] | A | DATA [7:0] | A | P | 66μs |

| S | ADDR [6:0] | 0 | A | CMD [7:0] | A | DATA [7:0] | A | P | 66μs |

| S | ADDR [6:0] | 0 | A | CMD [7:0] | A | Sr | ADDR [6:0] | 1 | A | DATA [7:0] | A | DATA [7:0] | N | P | 66μs |

Waiting time inserted between two 1-byte write packets for a subcommand and reading results
(required for 100 kHz < f$_{SCL}$ ≤ 400 kHz)

| S | ADDR [6:0] | 0 | A | CMD [7:0] | A | DATA [7:0] | A | DATA [7:0] | A | P | 66μs |

| S | ADDR [6:0] | 0 | A | CMD [7:0] | A | Sr | ADDR [6:0] | 1 | A | DATA [7:0] | A | DATA [7:0] | N | P | 66μs |

Waiting time inserted between incremental 2-byte write packet for a subcommand and reading results
(acceptable for f$_{SCL}$ ≤ 100 kHz)

| S | ADDR [6:0] | 0 | A | CMD [7:0] | A | Sr | ADDR [6:0] | 1 | A | DATA [7:0] | A | DATA [7:0] | A |
| DATA [7:0] | A | DATA [7:0] | N | P | 66μs |

Waiting time inserted after incremental read

Figure 7-4. I^{2}C Command Waiting Time

7.3.1.4 I^{2}C Clock Stretching

A clock stretch can occur during all modes of fuel gauge operation. In SLEEP mode, a short ≤ 100-μs clock stretch occurs on all I^{2}C traffic as the device must wake-up to process the packet. In the other modes (INITIALIZATION, NORMAL), a ≤ 4-ms clock stretching period may occur within packets addressed for the fuel gauge as the I^{2}C interface performs normal data flow control.

7.4 Device Functional Modes

The fuel gauge has different operating modes: POR, INITIALIZATION, NORMAL, CONFIG UPDATE, and SLEEP. Upon powering up from OFF or SHUTDOWN, a power-on reset (POR) occurs and the fuel gauge begins INITIALIZATION. In NORMAL mode, the fuel gauge is fully powered and can execute any allowable task. Configuration data in RAM can be updated by the host using the CONFIG UPDATE mode. In SLEEP mode, the fuel gauge turns off the high-frequency oscillator clock to enter a reduced-power state, periodically taking measurements and performing calculations.

The fuel gauge passes automatically between these modes, depending upon the occurrence of specific events, though a system processor can initiate some of these modes directly. For more details, see the *BQ27426 Technical Reference Manual*.

7.4.1 SHUTDOWN Mode

In SHUTDOWN mode, the LDO output is disabled so internal power and all RAM-based volatile data are lost. The host can command the gauge to immediately enter SHUTDOWN mode by first unsealing the gauge and then enabling the mode with a *SHUTDOWN_ENABLE* subcommand (SHUTDOWN_ENABLE: 0x001B) followed by the *SHUTDOWN* subcommand (SHUTDOWN: 0x001C). To exit SHUTDOWN mode, the GPOUT pin must be raised from logic low to logic high for at least 200 μs.

7.4.2 POR and INITIALIZATION Modes

Upon a POR, the fuel gauge copies ROM-based configuration defaults to RAM and begins INITIALIZATION mode where essential data is initialized. The occurrence of a POR or a *Control() RESET* subcommand will set the *Flags() [ITPOR]* status bit to indicate that RAM has returned to ROM default data. When battery insertion is detected, a series of initialization activities begin including an OCV measurement. In addition, *CONTROL_STATUS [QMAX_UP]* and *[RES_UP]* bits are cleared to allow unfiltered learning of Qmax and impedance. Completion of INITIALIZATION mode is indicated by the *CONTROL_STATUS [INITCOMP]* bit.

7.4.3 CONFIG UPDATE Mode

If the application requires different configuration data for the fuel gauge, the system processor can update RAM-based data memory parameters using the *Control() SET_CFGUPDATE* subcommand to enter the CONFIG UPDATE mode. Operation in this mode is indicated by the *Flags() [CFGUPMODE]* status bit. In this mode, fuel gauging is suspended while the host uses the extended data commands to modify the configuration data blocks. To resume fuel gauging, the host must send a *Control() SOFT_RESET* subcommand to exit the CONFIG UPDATE mode which clears both *Flags() [ITPOR]* and *[CFGUPMODE]* bits. After a timeout of approximately 240 seconds (4 minutes), the gauge will automatically exit the CONFIG UPDATE mode if it has not received a *SOFT_RESET* subcommand from the host.

7.4.4 NORMAL Mode

The fuel gauge is in NORMAL mode when not in any other power mode. During this mode, *AverageCurrent()*, *Voltage()*, and *Temperature()* measurements are taken once per second, and the interface data set is updated. Decisions to change states are also made. This mode is exited by activating a different power mode.

Because the gauge consumes the most power in NORMAL mode, the Impedance Track algorithm minimizes the time the fuel gauge remains in this mode.

7.4.5 SLEEP Mode

SLEEP mode is an ultra low power operating mode. It is entered automatically if the feature is enabled (*OpConfig [SLEEP]* = 1) and *AverageCurrent()* is below the programmable level **Sleep Current** (default = 10 mA). Once entry into SLEEP mode has been qualified, but prior to entering it, the fuel gauge may perform an ADC autocalibration to minimize the offset.

During SLEEP mode, the fuel gauge remains in a very-low-power state and automatically takes data measurements every 20 seconds.

After taking the measurements on the 20-second interval, the fuel gauge will exit SLEEP mode when *AverageCurrent()* rises above **Sleep Current** (default = 10 mA). Alternatively, an early data measurement before the 20-second internal is possible if the instantaneous current detected by an internal hardware comparator is above an approximate threshold of ±30 mA.
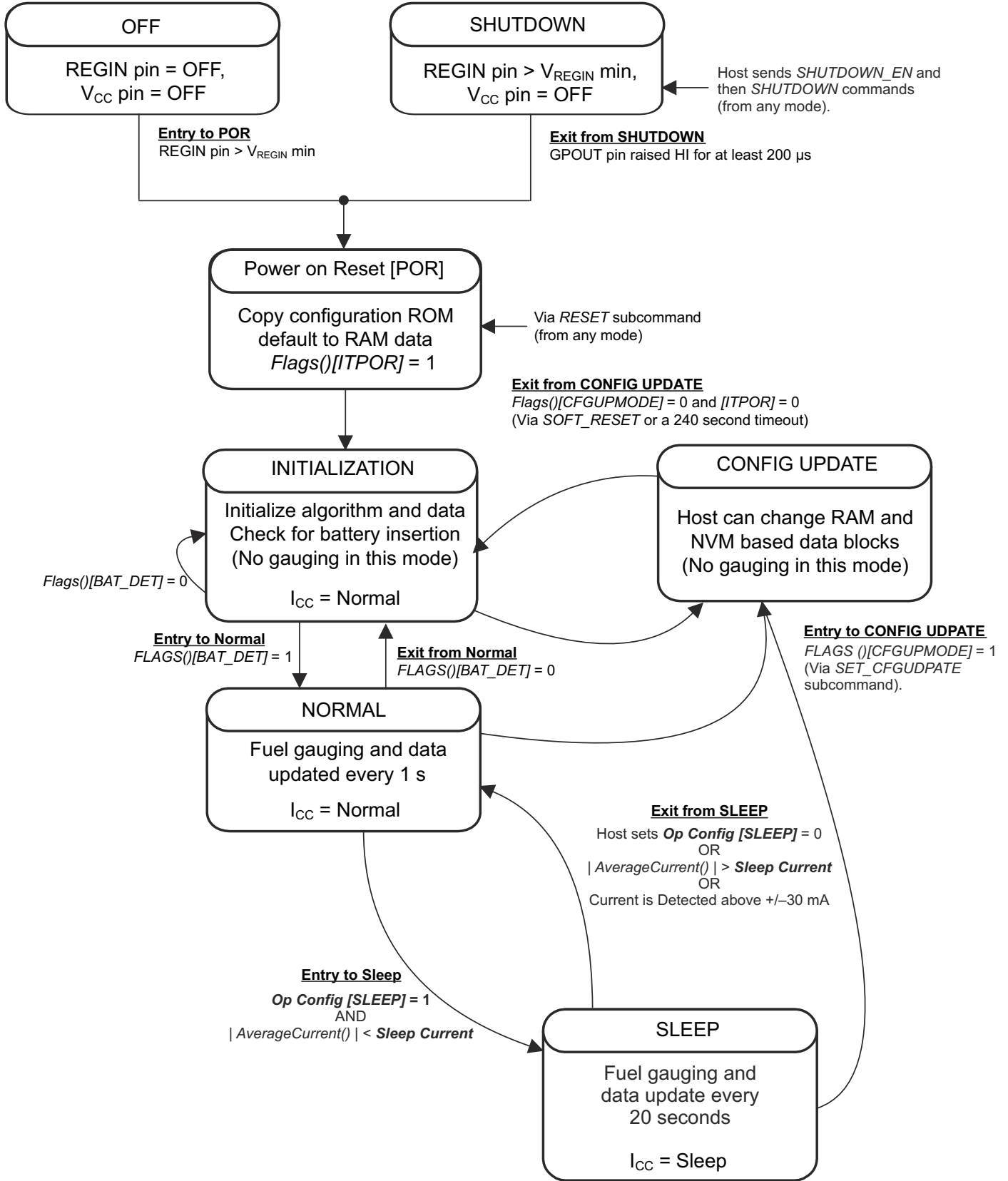
```
┌─────────────────────────┐              ┌─────────────────────────┐
│          OFF            │              │       SHUTDOWN          │
│                         │              │                         │       Host sends SHUTDOWN_EN and
│   REGIN pin = OFF,      │              │  REGIN pin > VREGIN min, │ ◄──── then SHUTDOWN commands
│   VCC pin = OFF         │              │  VCC pin = OFF           │       (from any mode).
└─────────────────────────┘              └─────────────────────────┘
```

Entry to POR
REGIN pin > V_REGIN min

Exit from SHUTDOWN
GPOUT pin raised HI for at least 200 µs

Power on Reset [POR]

Copy configuration ROM
default to RAM data
Flags()[ITPOR] = 1

Via *RESET* subcommand
(from any mode)

Exit from CONFIG UPDATE
Flags()[CFGUPMODE] = 0 and *[ITPOR]* = 0
(Via *SOFT_RESET* or a 240 second timeout)

INITIALIZATION

Initialize algorithm and data
Check for battery insertion
(No gauging in this mode)

I_{CC} = Normal

CONFIG UPDATE

Host can change RAM and
NVM based data blocks
(No gauging in this mode)

Flags()[BAT_DET] = 0

Entry to Normal
FLAGS()[BAT_DET] = 1

Exit from Normal
FLAGS()[BAT_DET] = 0

Entry to CONFIG UDPATE
FLAGS ()[CFGUPMODE] = 1
(Via *SET_CFGUDPATE*
subcommand).

NORMAL

Fuel gauging and data
updated every 1 s

I_{CC} = Normal

Exit from SLEEP
Host sets *Op Config [SLEEP]* = 0
OR
| *AverageCurrent()* | > *Sleep Current*
OR
Current is Detected above +/–30 mA

Entry to Sleep

Op Config [SLEEP] = 1
AND
| *AverageCurrent()* | < *Sleep Current*

SLEEP

Fuel gauging and
data update every
20 seconds

I_{CC} = Sleep

Figure 7-5. Power Mode Diagram

8 Application and Implementation

> **Note**
>
> Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The BQ27426 fuel gauge is a microcontroller peripheral that provides system-side fuel gauging for single-cell Li-Ion batteries. Battery fuel gauging with the fuel gauge requires connections only to PACK+ and PACK– for a removable battery pack or embedded battery circuit. To allow for optimal performance in the end application, special considerations must be taken to ensure minimization of measurement error through proper printed circuit board (PCB) board layout. Such requirements are detailed in *Section 8.2.1*.

8.2 Typical Applications

The BQ27426 device can be used with a high-side current sense resistor (as shown in Figure 8-1) or a low-side current sense resistor (as shown in Figure 8-2).
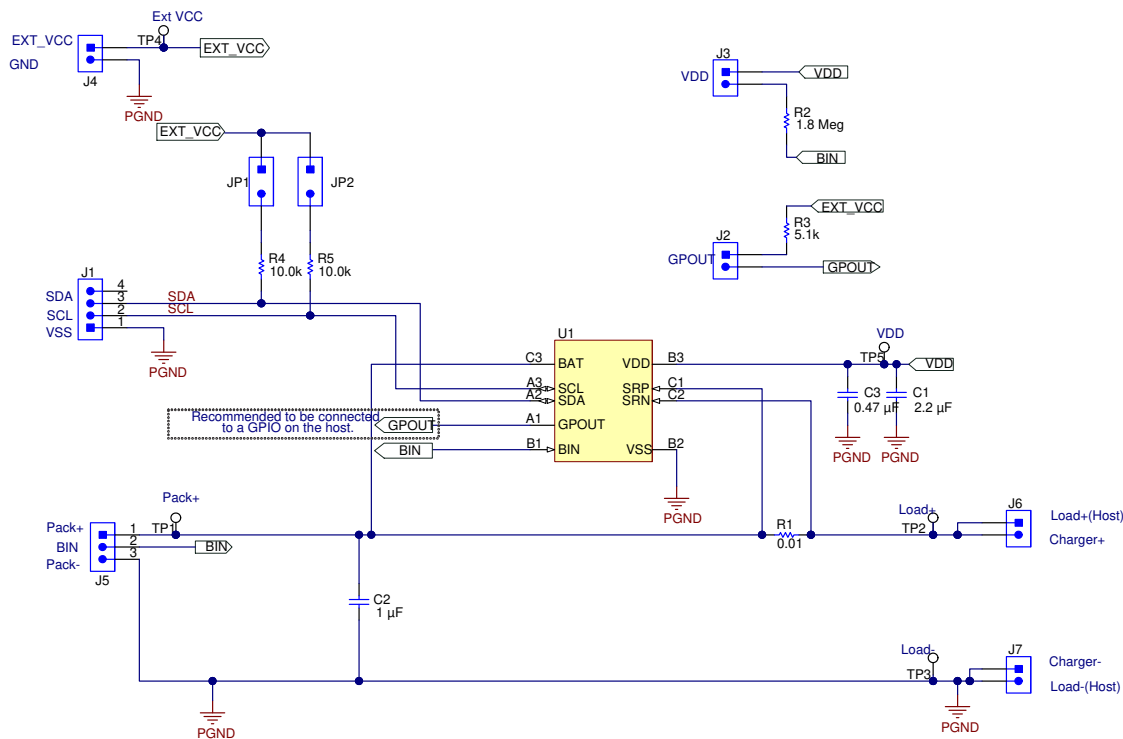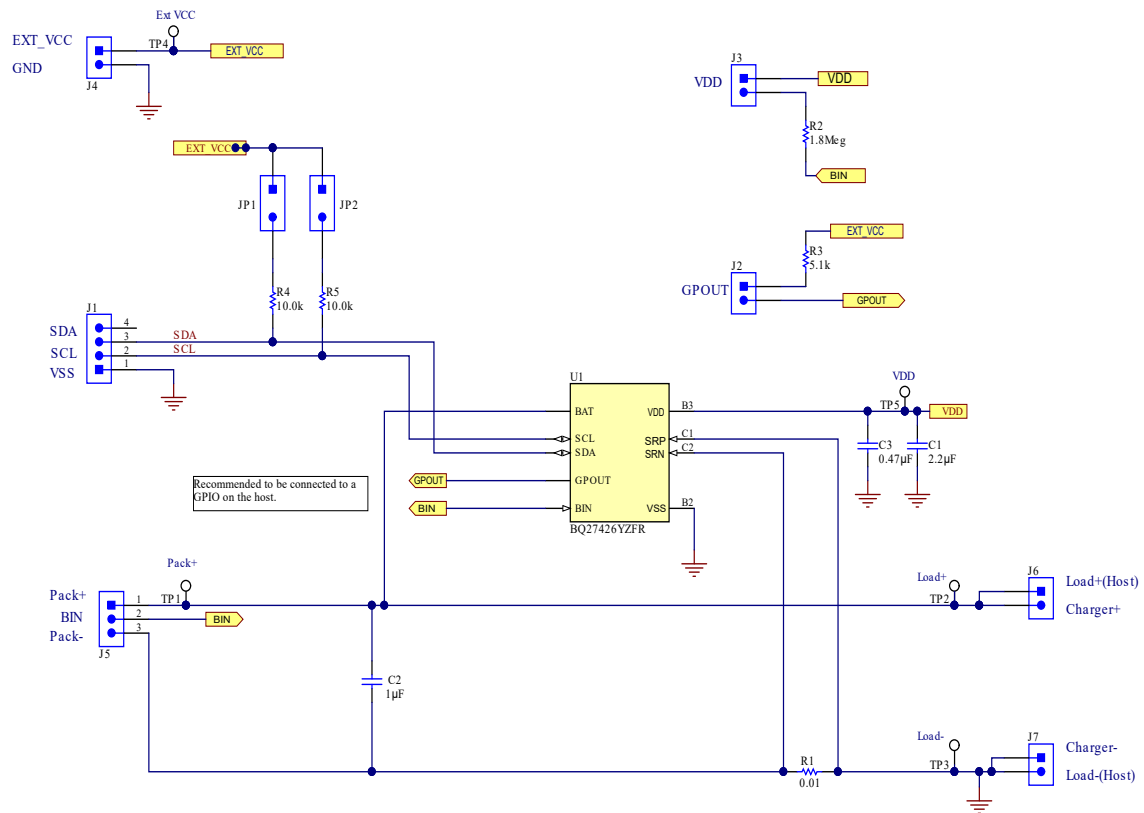

Figure 8-1. Typical Application with High-Side Current Sense Resistor

Figure 8-2. Typical Application with Low-Side Current Sense Resistor

8.2.1 Design Requirements

As shipped from the Texas Instruments factory, the BQ27426 fuel gauge comes with three preprogrammed chemistry profiles and gauging parameters in ROM. Upon device reset, the contents of ROM are copied to associated volatile RAM-based data memory blocks. For proper operation, all parameters in RAM-based data memory require initialization. This can be done by updating data memory parameters in a lab/evaluation situation or by downloading the parameters from a host. The *BQ27426 Technical Reference Manual* shows the default and typically expected values appropriate for most applications.

8.2.2 Detailed Design Procedure

8.2.2.1 BAT Voltage Sense Input

A ceramic capacitor at the input to the BAT pin is used to bypass AC voltage ripple to ground, greatly reducing its influence on battery voltage measurements. It proves most effective in applications with load profiles that exhibit high-frequency current pulses (that is, cell phones) but is recommended for use in all applications to reduce noise on this sensitive high-impedance measurement node.

8.2.2.2 Integrated LDO Capacitor

The fuel gauge has an integrated LDO with an output on the V_{DD} pin of approximately 1.8 V. A capacitor of value at least 2.2 μF should be connected between the V_{DD} pin and V_{SS}. The capacitor must be placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS}. This regulator must not be used to provide power for other devices in the system.

8.2.2.3 Sense Resistor Selection

Any variation encountered in the resistance present between the SRP and SRN pins of the fuel gauge will affect the resulting differential voltage, and derived current, it senses. As such, it is recommended to select a sense
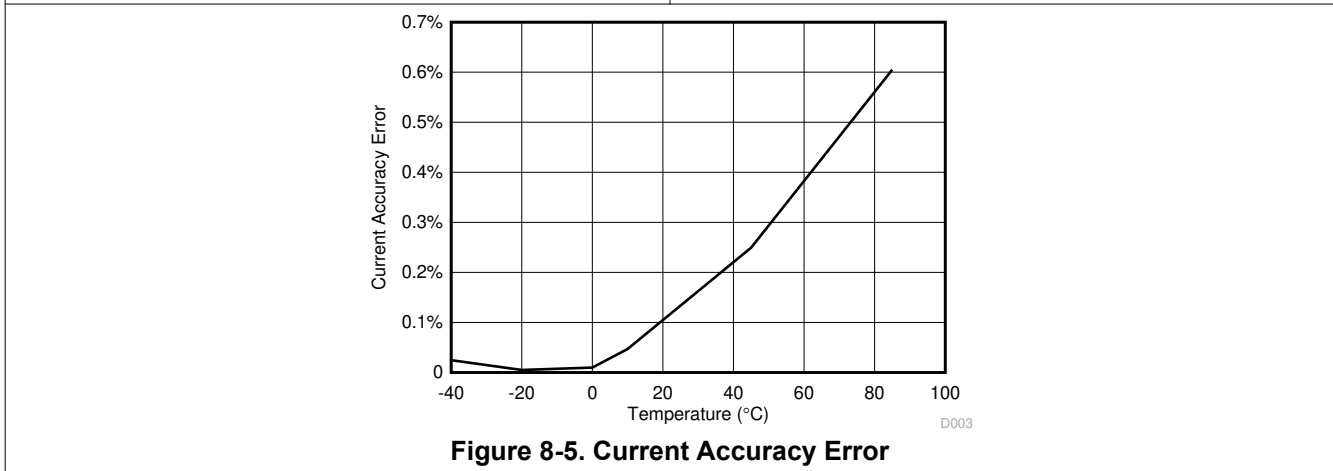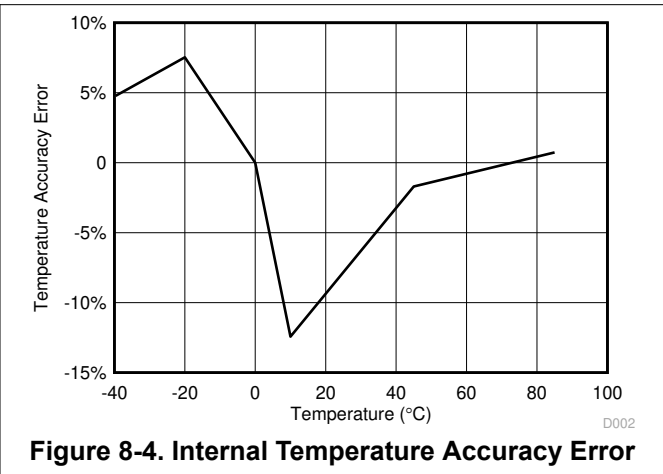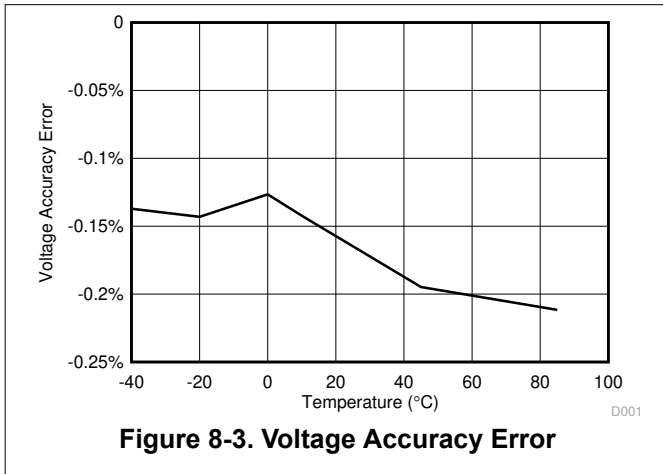
resistor with minimal tolerance and temperature coefficient of resistance (TCR) characteristics. The standard recommendation based on best compromise between performance and price is a 1% tolerance, 50 ppm drift sense resistor with a 1-W power rating.

8.2.3 External Thermistor Support

The fuel gauge temperature sensing circuitry is designed to work with a negative temperature coefficient-type (NTC) thermistor with a characteristic 10-kΩ resistance at room temperature (25°C). The default curve-fitting coefficients configured in the fuel gauge specifically assume a Semitec 103AT type thermistor profile and so that is the default recommendation for thermistor selection purposes. Moving to a separate thermistor resistance profile (for example, JT-2 or others) requires an update to the default thermistor coefficients which can be modified in RAM to ensure highest accuracy temperature measurement performance.

8.2.4 Application Curves

Figure 8-3. Voltage Accuracy Error

Figure 8-4. Internal Temperature Accuracy Error

Figure 8-5. Current Accuracy Error

9 Power Supply Recommendation

9.1 Power Supply Decoupling

The battery connection on the BAT pin is used for two purposes:

- To supply power to the fuel gauge
- To provide an input for voltage measurement of the battery.

A capacitor of value of at least 1 µF should be connected between BAT and V_{SS}. The capacitor should be placed close to the gauge IC and have short traces to both the BAT pin and V_{SS}.

The fuel gauge has an integrated LDO with an output on the V_{DD} pin of approximately 1.8 V. A capacitor of value at least 2.2 µF should be connected between the V_{DD} pin and V_{SS}. The capacitor should be placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS}. This regulator must not be used to provide power for other devices in the system.

10 Layout

10.1 Layout Guidelines

- A capacitor of a value of at least 2.2 µF is connected between the V_{DD} pin and V_{SS}. The capacitor should be placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS}. This regulator must not be used to provide power for other devices in the system.
- It is required to have a capacitor of at least 1.0 µF connect between the BAT pin and V_{SS} if the connection between the battery pack and the gauge BAT pin has the potential to pick up noise. The capacitor should be placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS}.
- If the external pullup resistors on the SCL and SDA lines will be disconnected from the host during low-power operation, it is recommended to use external 1-MΩ pulldown resistors to V_{SS} to avoid floating inputs to the I²C engine.
- The value of the SCL and SDA pullup resistors should take into consideration the pullup voltage and the bus capacitance. Some recommended values, assuming a bus capacitance of 10 pF, can be seen in Table 10-1.

Table 10-1. Recommended Values for SCL and SDA Pullup Resistors

VPU	1.8 V		3.3 V	
	Range	Typical	Range	Typical
R_{PU}	400 Ω ≤ R_{PU} ≤ 37.6 kΩ	10 kΩ	900 Ω ≤ R_{PU} ≤ 29.2 kΩ	5.1 kΩ

- If the host is not using the GPOUT functionality, then it is recommended that GPOUT be connected to a GPIO of the host so that in cases where the device is in SHUTDOWN, toggling GPOUT can wake the gauge up from the SHUTDOWN state.
- If the battery pack thermistor is not connected to the BIN pin, the BIN pin should be pulled down to V_{SS} with a 10-kΩ resistor.
- The BIN pin should not be shorted directly to V_{DD} or V_{SS}.
- The actual device ground is pin 3 (V_{SS}).
- The SRP and SRN pins should be Kelvin connected to the R_{SENSE} terminals. SRP to the battery pack side of R_{SENSE} and SRN to the system side of the R_{SENSE}.
- Kelvin connects the BAT pin to the battery PACKP terminal.

10.2 Layout Example

Figure 10-1. BQ27426 Board Layout

Product Folder Links: BQ27426
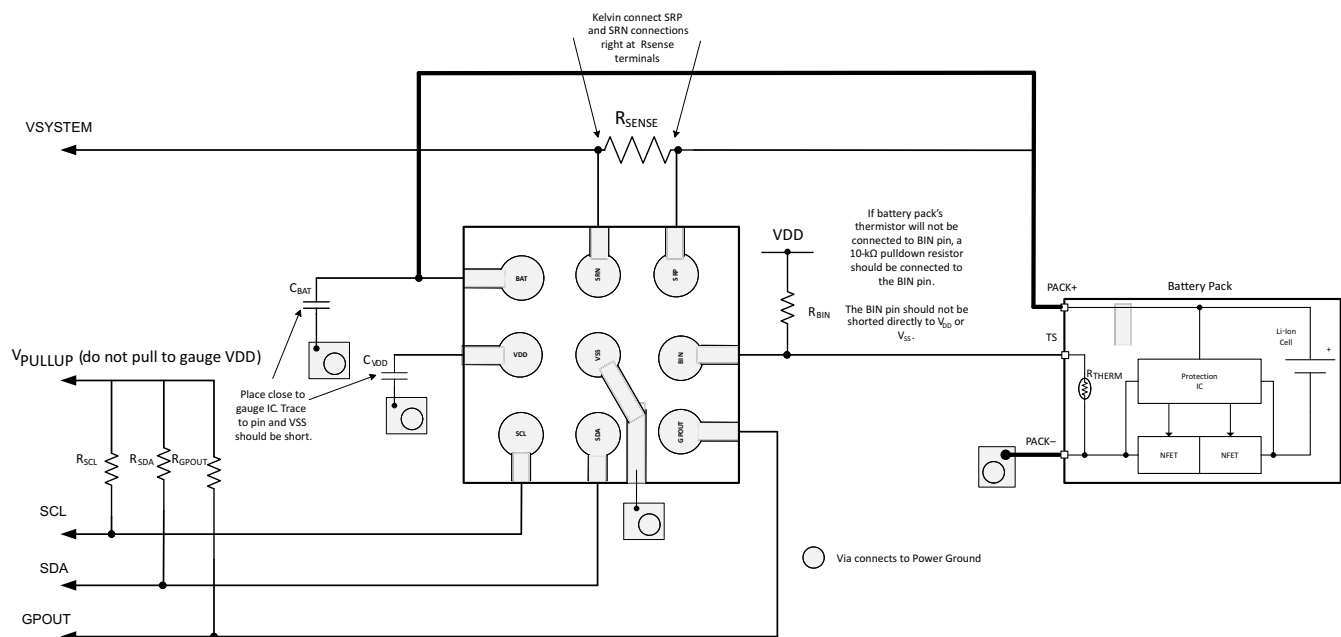
11 Device and Documentation Support

11.1 Documentation Support

11.1.1 Third-Party Products Disclaimer

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11.1.2 Related Documentation

- *BQ27426 Technical Reference Manual*
- *Single Cell Gas Gauge Circuit Design*
- *Single Cell Impedance Track Printed-Circuit Board Layout Guide*
- *ESD and RF Mitigation in Handheld Battery Electronics*

11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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11.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

TI Glossary   This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Product Folder Links: *BQ27426*

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
BQ27426YZFR	ACTIVE	DSBGA	YZF	9	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27426	Samples
BQ27426YZFT	ACTIVE	DSBGA	YZF	9	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27426	Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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![Texas Instruments logo] **TEXAS INSTRUMENTS**

PACKAGE MATERIALS INFORMATION

TAPE AND REEL INFORMATION

REEL DIMENSIONS

TAPE DIMENSIONS

A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ27426YZFR	DSBGA	YZF	9	3000	180.0	8.4	1.78	1.78	0.69	4.0	8.0	Q1
BQ27426YZFT	DSBGA	YZF	9	250	180.0	8.4	1.78	1.78	0.69	4.0	8.0	Q1

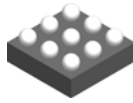# PACKAGE MATERIALS INFORMATION

TAPE AND REEL BOX DIMENSIONS
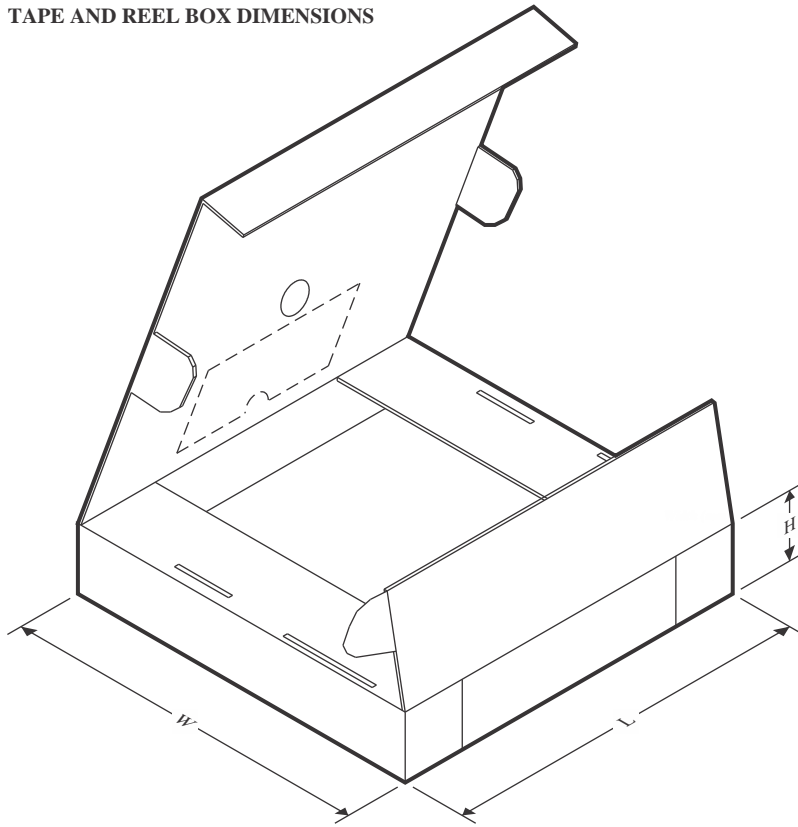
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ27426YZFR	DSBGA	YZF	9	3000	182.0	182.0	20.0
BQ27426YZFT	DSBGA	YZF	9	250	182.0	182.0	20.0

BALL A1 CORNER

E

D

A

B

0.625 MAX

0.35
0.15

BALL TYP

C

SEATING PLANE

$\triangle$ | 0.05 | C

1 | TYP

SYMM

1
TYP

0.5
TYP

SYMM

C

B

A

1   2   3

9X $\varnothing$ | 0.35
0.25

$\oplus$ | 0.015 Ⓜ | C | A | B

0.5 | TYP

D: Max = 1.651 mm, Min = 1.59 mm
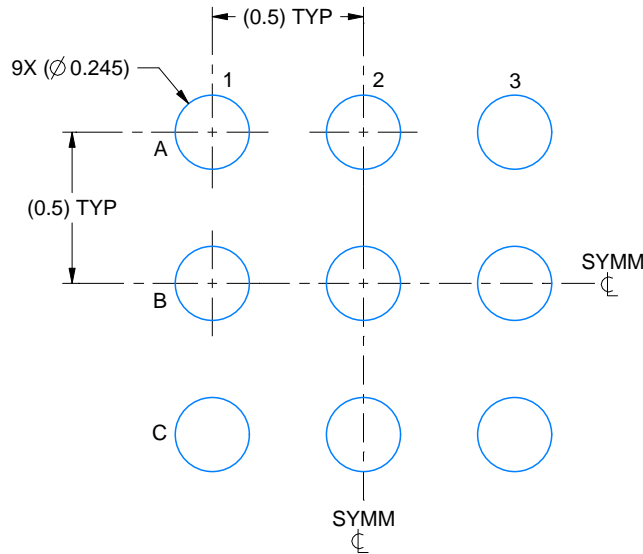
E: Max = 1.61 mm, Min = 1.55 mm

4219558/A   10/2018
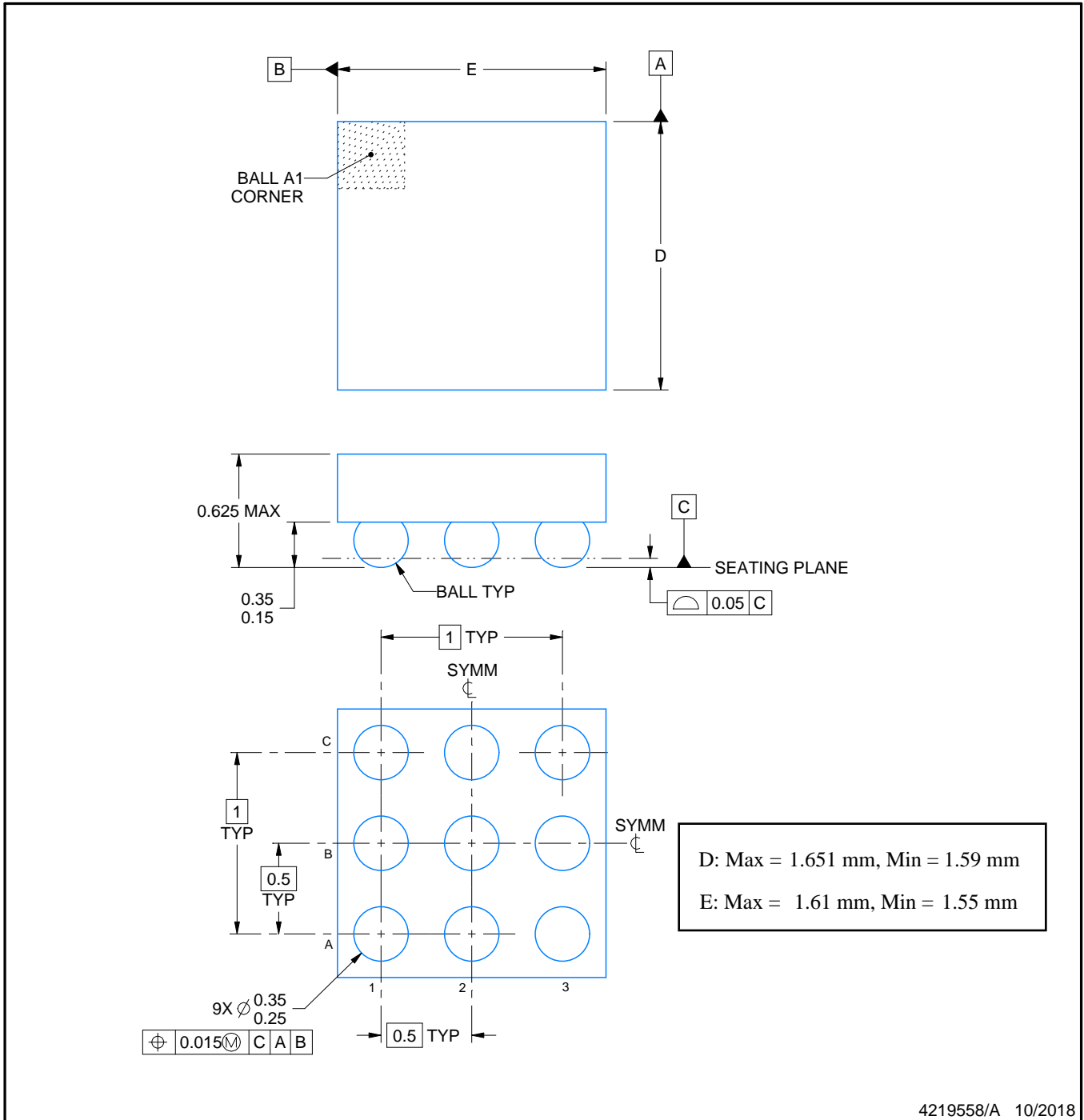
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
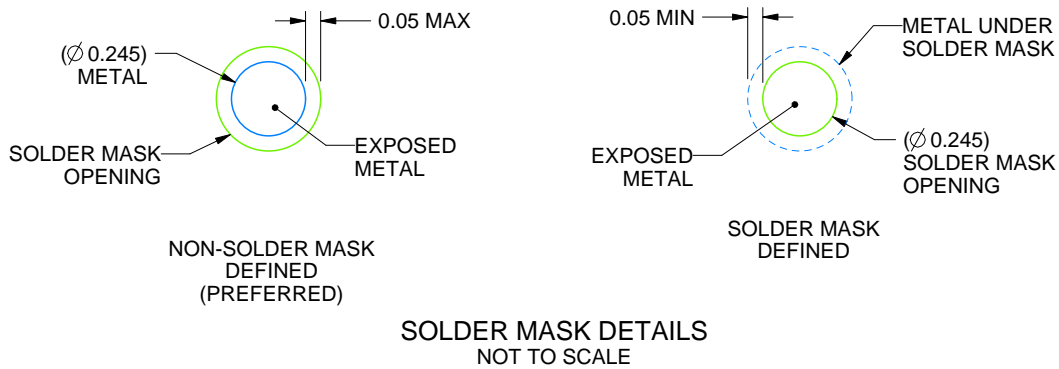2. This drawing is subject to change without notice.

(0.5) TYP

9X (⌀ 0.245)

1   2   3

A

(0.5) TYP

B

SYMM ₵

C

SYMM ₵

LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 40X

0.05 MAX

(⌀ 0.245) METAL

SOLDER MASK OPENING

EXPOSED METAL

NON-SOLDER MASK DEFINED
(PREFERRED)

0.05 MIN

METAL UNDER SOLDER MASK

EXPOSED METAL

(⌀ 0.245) SOLDER MASK OPENING

SOLDER MASK DEFINED

SOLDER MASK DETAILS
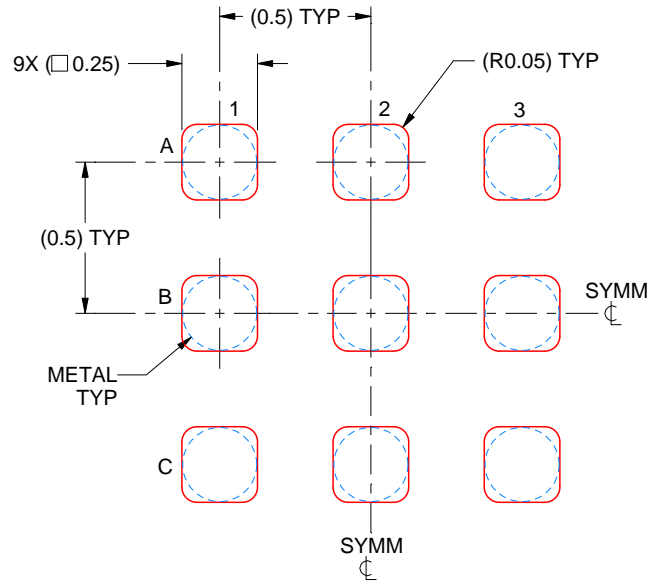NOT TO SCALE

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NOTES: (continued)

3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints.
   See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).

SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE: 40X

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NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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