

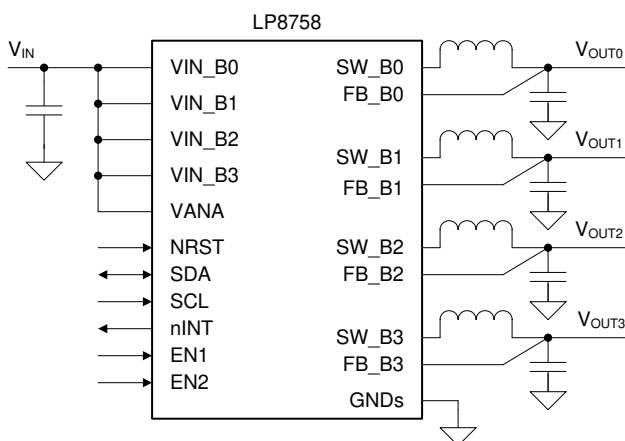
# LP8758-EA 4 つの 4A 出力同期整流降圧 DC/DC コンバータ

## 1 特長

- 完全に統合されたクワッド降圧コンバータ、降圧コンバータコアごとに最大 4A の最大出力電流をプログラム可能
  - PWM-PFM 自動切り換えおよび強制 PWM 動作
  - 出力電圧スルー・レートを 30mV/μs~0.5mV/μs の範囲でプログラム可能
  - 入力電圧範囲: 2.5V~5.5V
  - V<sub>OUT</sub> 範囲: DVS により 0.5V~3.36V
- プログラム可能なスタートアップ/シャットダウン・シーケンス (イネーブル信号に同期)
- I<sup>2</sup>C 互換インターフェイスの Standard (100kHz)、Fast (400kHz)、Fast+ (1MHz)、High-Speed (3.4MHz) モードをサポート
- マスクをプログラム可能な割り込み機能
- 負荷電流測定
- 出力短絡および過負荷保護
- 拡散スペクトラム・モードによる EMI 低減
- 4 つの降圧コアは互いに 90° 異なる位相で動作するため、入力リップル電流が減少
- 過熱警告および保護
- 低電圧誤動作防止 (UVLO)

## 2 アプリケーション

- 光モジュール
- ドローン・システム
- スマートフォン、電子書籍、タブレット
- ソリッドステート・ドライブ



概略回路図

## 3 概要

LP8758-EA デバイスは、携帯電話やネットワーク・カードなどのアプリケーションで使用される低消費電力プロセッサの電力管理要件を満たすよう設計されています。このデバイスには、4 つの降圧 DC-DC コンバータ・コアが内蔵されており、4 つの出力電圧レールを供給します。このデバイスは、I<sup>2</sup>C 互換のシリアル・インターフェイスにより制御されます。

PWM-PFM の自動切り換え (AUTO モード) 動作により、広い出力電流範囲にわたって効率を最大化します。

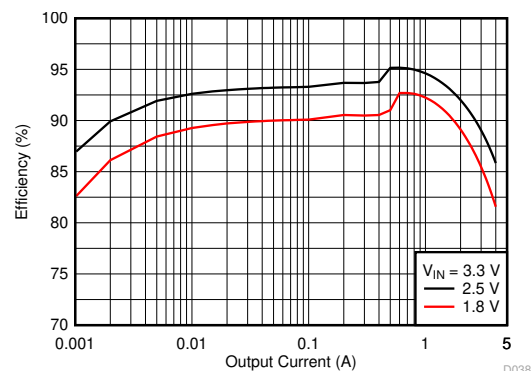
LP8758-EA は、ハードウェアのイネーブル入力信号に同期したプログラム可能なスタートアップおよびシャットダウン・シーケンスをサポートしています。

保護機能として、短絡保護、電流制限、入力電源 UVLO、温度警告およびシャットダウン機能が搭載されています。デバイスのステータス情報のための複数のエラー・フラグが用意されています。さらに、LP8758-EA デバイスは、外付けの電流検出抵抗を追加しないで負荷電流を測定できます。スタートアップ中および電圧変化時に、このデバイスは出力スルー・レートを制御し、出力電圧のオーバーシュートと突入電流を最小化します。

### デバイス情報<sup>(1)</sup>

部品番号	デフォルト出力電圧	
LP8758-EA	V <sub>OUT0</sub>	800mV
	V <sub>OUT1</sub>	800mV
	V <sub>OUT2</sub>	800mV
	V <sub>OUT3</sub>	800mV

- (1) 利用可能なパッケージについては、このデータシートの末尾にある注文情報を参照してください。



V<sub>OUT</sub> 設定 = 1.8V および 2.5V

効率と出力電流との関係



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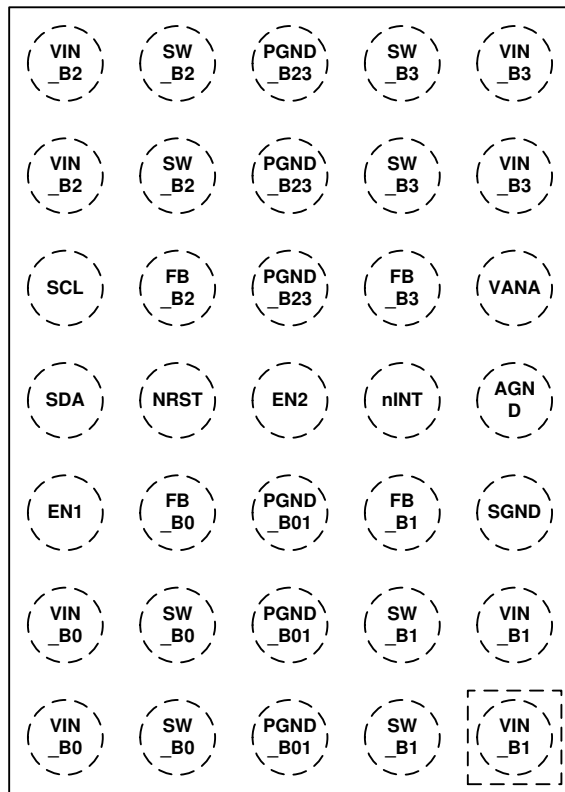
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## 4 Revision History

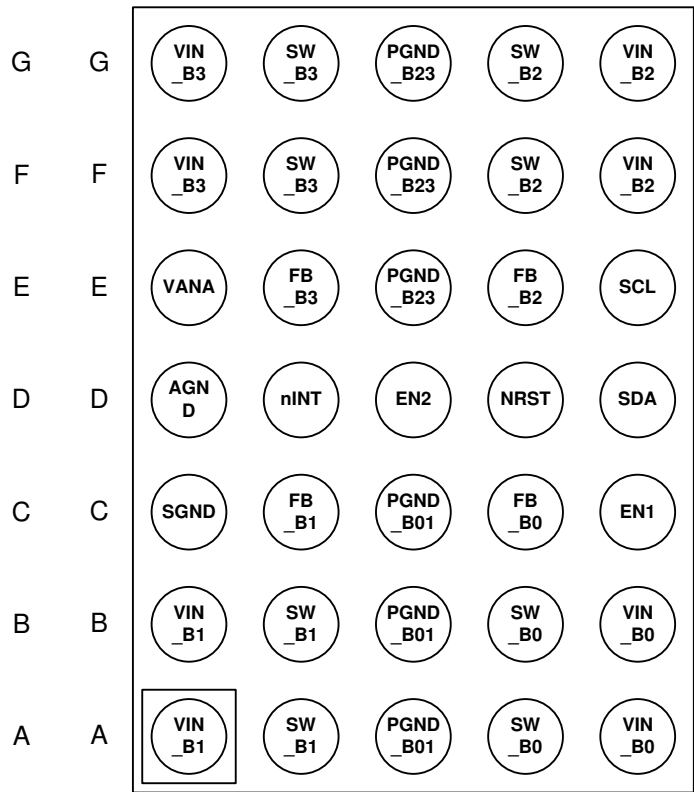
資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。


DATE	REVISION	NOTES
April 2021	*	Initial Release

## 5 Pin Configuration and Functions



5 4 3 2 1  
 **5-1. YFF Package 35-Pin DSBGA Top View**



1 2 3 4 5  
 **5-2. YFF Package 35-Pin DSBGA Bottom View**

**表 5-1. Pin Functions**

PIN		TYPE	DESCRIPTION
NO.	NAME		
A1, B1	VIN_B1	P	Input for Buck1. The separate power pins VIN_Bx are not connected together internally – VIN_Bx pins must be connected together in the application and be locally bypassed.
A2, B2	SW_B1	A	Buck1 switch node.
A3, B3, C3	PGND_B01	G	Power Ground for Buck0 and Buck1.
A4, B4	SW_B0	A	Buck0 switch node.
A5, B5	VIN_B0	P	Input for Buck0. The separate power pins VIN_Bx are not connected together internally – VIN_Bx pins must be connected together in the application and be locally bypassed.
C1	SGND	G	Substrate Ground.
C2	FB_B1	A	Output voltage feedback for Buck1.
C4	FB_B0	A	Output voltage feedback for Buck0.
C5	EN1	D/I	Programmable Enable signal for Buck converter core or cores. Can be also configured to switch between two output voltage levels.
D1	AGND	G	Ground.
D2	nINT	D/O	Open-drain interrupt output. Active LOW.
D3	EN2	D/I	Programmable Enable signal for Buck converter one or more cores. Can be also configured to switch between two output voltage levels.
D4	NRST	D/I	Reset signal for the device. Can be also used to enable the regulator.
D5	SDA	D//O	Serial interface data input and output for system access. Connect a pullup resistor.

表 5-1. Pin Functions (continued)

PIN		TYPE	DESCRIPTION
NO.	NAME		
E1	VANA	P	Supply voltage for Analog and Digital blocks.
E2	FB_B3	A	Output voltage feedback for Buck3.
E4	FB_B2	A	Output voltage feedback for Buck2.
E5	SCL	D/I	Serial interface clock input for system access. Connect a pullup resistor.
F1, G1	VIN_B3	P	Input for Buck3. The separate power pins VIN_Bx are not connected together internally – VIN_Bx pins must be connected together in the application and be locally bypassed.
F2, G2	SW_B3	A	Buck3 switch node.
E3, F3, G3	PGND_B23	G	Power Ground for Buck2 and Buck3.
F4, G4	SW_B2	A	Buck2 switch node.
F5, G5	VIN_B2	P	Input for Buck2. The separate power pins VIN_Bx are not connected together internally - VIN_Bx pins must be connected together in the application and be locally bypassed.

A: Analog Pin, D: Digital Pin, G: Ground Pin, P: Power Pin, I: Input Pin, O: Output Pin

## 6 Specifications

### 6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted).<sup>(1) (2)</sup>

		MIN	MAX	UNIT
<b>INPUT VOLTAGE</b>				
VIN_Bx, VANA	Voltage on power connections	-0.3	6	V
SW_Bx	Voltage on buck switch nodes	-0.3	(VIN_Bx + 0.3 V) with 6 V maximum	V
FB_Bx	Voltage on buck voltage sense nodes	-0.3	(VANA + 0.3 V) with 6 V maximum	V
NRST	Voltage on NRST input	-0.3	3.6	V
ENx, SDA, SCL, nINT	Voltage on logic pins (input or output pins)	-0.3	3.6	V
<b>CURRENT</b>				
VIN_Bx, SW_Bx, PGND_Bx	Current on power pins (average current over 100k hour lifetime, T <sub>J</sub> = 125°C)		0.62	A/pin
<b>TEMPERATURE</b>				
T <sub>J-MAX</sub>	Junction temperature	-40	150	°C
Maximum lead temperature (soldering, 10 seconds) <sup>(3)</sup>			260	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under [セクション 6.3](#). Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to network ground.
- (3) For detailed soldering specifications and information, please refer to [DSBGA Wafer Level Chip Scale Package](#).

### 6.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted).

		MIN	MAX	UNIT
<b>INPUT VOLTAGE</b>				
VIN_Bx, VANA	Voltage on power connections	2.5	5.5	V
NRST	Voltage on NRST	0	VANA with 3.6 V maximum	V
ENx, nINT	Voltage on logic pins (input or output pins)	0	VANA with 3.6 V maximum	V
SCL, SDA	Voltage on I <sup>2</sup> C interface, standard (100 kHz), fast (400 kHz), fast+ (1 MHz), and high-speed (3.4 MHz) modes	0	1.95	V
	Voltage on I <sup>2</sup> C interface, standard (100 kHz), fast (400 kHz), and fast+ (1 MHz) modes	0	VANA with 3.6 V maximum	V
<b>TEMPERATURE</b>				
T <sub>J</sub>	Junction temperature	-40	125	°C
T <sub>A</sub>	Ambient temperature	-40	85	°C

## 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		LP8758	UNIT
		YFF (DSBGA)	
		35 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	56.1	°C/W
R <sub>θJCTop</sub>	Junction-to-case (top) thermal resistance	0.2	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	8.5	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.9	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	8.4	°C/W
R <sub>θJCbott</sub>	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics application report](#).

## 6.5 Electrical Characteristics

Limits apply over the junction temperature range  $-40^{\circ}\text{C} \leq T_J \leq +125^{\circ}\text{C}$ , specified  $V_{(VANA)}$ ,  $V_{IN}$ ,  $V_{(NRST)}$ ,  $V_{OUT}$  and  $I_{OUT}$  range, unless otherwise noted. Typical values are at  $T_J = 25^{\circ}\text{C}$ ,  $f_{SW} = 3\text{ MHz}$ ,  $V_{(VANA)} = V_{IN} = 3.7\text{ V}$  and  $V_{OUT} = 1\text{ V}$ , unless otherwise noted.<sup>(1) (2)</sup>

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
EXTERNAL COMPONENTS							
C <sub>IN</sub>	Input filtering capacitance	Connected from VIN_Bx to PGND_Bx		1.9	10	μF	
C <sub>OUT</sub>	Output filtering capacitance, local	Capacitance per output voltage rail		10	22	μF	
C <sub>OUT-TOTAL</sub>	Output capacitance, total (local and remote)	Total output capacitance			50	μF	
ESR <sub>C</sub>	Input and output capacitor ESR	[1-10] MHz			2	10	mΩ
L	Inductor	Inductance of the inductor			0.47		μH
				-30%		30%	
DCR <sub>L</sub>	Inductor DCR	TDK, VLS252010HBX-R47M			29		mΩ
BUCK REGULATORS							
V <sub>IN</sub>	Input voltage range	Voltage between VIN_Bx and ground terminals. VANA must be connected to the same supply as VIN_Bx.		2.5	3.7	5.5	V
V <sub>OUT</sub>	Output voltage	Programmable voltage range		0.5	1	3.36	V
		Step size, $0.5\text{ V} \leq V_{OUT} < 0.73\text{ V}$			10		mV
		Step size, $0.73\text{ V} \leq V_{OUT} < 1.4\text{ V}$			5		
		Step size, $1.4\text{ V} \leq V_{OUT} \leq 3.36\text{ V}$			20		
I <sub>OUT</sub>	Output current	Output current, $V_{IN} \leq 3\text{ V}$ I <sub>LIM FWD</sub> programmed to 5 A per phase.				3 <sup>(3)</sup>	A
		Output current, $V_{IN} > 3\text{ V}$ , $V_{OUT} \leq 2\text{ V}$ I <sub>LIM FWD</sub> programmed to 5 A per phase.				4 <sup>(3)</sup>	
		Output current, $V_{IN} > 3\text{ V}$ , $V_{OUT} > 2\text{ V}$ I <sub>LIM FWD</sub> programmed to 5 A per phase.				3.5 <sup>(3)</sup>	
	Dropout voltage	V <sub>IN</sub> - V <sub>OUT</sub>		0.7			V
	DC output voltage accuracy, includes voltage reference, DC load and line regulations, process and temperature	Force PWM mode		min (-2%, -20 mV)		max (2%, 20 mV)	
		PFM mode, the average output voltage level is increased by a maximum of 20 mV.		min (-2%, -20 mV)		max (2%, 20 mV) + 20 mV	
Ripple		PWM mode, L = 0.47 μH			10		mV <sub>p-p</sub>
		PFM mode, L = 0.47 μH			20		

## 6.5 Electrical Characteristics (continued)

Limits apply over the junction temperature range  $-40^{\circ}\text{C} \leq T_J \leq +125^{\circ}\text{C}$ , specified  $V_{(VANA)}$ ,  $V_{IN}$ ,  $V_{(NRST)}$ ,  $V_{OUT}$  and  $I_{OUT}$  range, unless otherwise noted. Typical values are at  $T_J = 25^{\circ}\text{C}$ ,  $f_{SW} = 3\text{ MHz}$ ,  $V_{(VANA)} = V_{IN} = 3.7\text{ V}$  and  $V_{OUT} = 1\text{ V}$ , unless otherwise noted.<sup>(1) (2)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DC <sub>LNR</sub>	DC line regulation	$I_{OUT} = 1\text{ A}$		±0.05		%/V
DC <sub>LDR</sub>	DC load regulation in PWM mode	$I_{OUT}$ from 0 to $I_{OUT(max)}$		0.3%		
T <sub>LDSR</sub>	Transient load step response	$I_{OUT} = 0\text{ A}$ to $2\text{ A}$ , $T_R = T_F = 400\text{ ns}$ , PWM mode, $C_{OUT} = 44\text{ }\mu\text{F}$ , $L = 0.47\text{ }\mu\text{H}$		±55		mV
T <sub>LNSR</sub>	Transient line response	$V_{IN}$ stepping $3.3\text{ V} \leftrightarrow 3.8\text{ V}$ , $T_R = T_F = 10\text{ }\mu\text{s}$ , $I_{OUT} = I_{OUT(max)}$		±15		mV
I <sub>LIM FWD</sub>	Forward current limit (peak for every switching cycle), per phase	Programmable range	2.5		5	A
		Step size		0.5		
		Accuracy, $3\text{ V} \leq V_{IN} \leq 5.5\text{ V}$ , $I_{LIM FWD} = 5\text{ A}$	-5%	7.5%	20%	
		Accuracy, $2.5\text{ V} \leq V_{IN} \leq 3\text{ V}$ , $I_{LIM FWD} = 5\text{ A}$	-20%	7.5%	20%	
I <sub>LIM NEG</sub>	Negative current limit		1.6	2	2.4	A
R <sub>DS(ON) HS FET</sub>	On-resistance, high-side FET	Between VIN_Bx and SW_Bx pins ( $I = 1\text{ A}$ )		40	90	mΩ
R <sub>DS(ON) LS FET</sub>	On-resistance, low-side FET	Between SW_Bx and PGND_Bx pins ( $I = 1\text{ A}$ )		33	50	mΩ
	Overshoot during start-up	Slew-rate = $10\text{ mV}/\mu\text{s}$		< 50		mV
I <sub>PFM-PWM</sub>	PFM-to-PWM switch - current threshold <sup>(4)</sup>			600		mA
I <sub>PWM-PFM</sub>	PWM-to-PFM switch - current threshold <sup>(4)</sup>			240		mA
	Output pulldown resistance	Regulator disabled	150	250	350	Ω
	Powergood threshold for interrupt BUCKx_INT(BUCKx_SC_INT), difference from final voltage	Rising ramp voltage, enable or voltage change	-23	-17	-10	mV
		Falling ramp, voltage change	10	17	23	
	Powergood threshold for status signal BUCKx_STAT(BUCKx_PG_STAT)	During operation, status signal is forced to 0 during voltage change.	-23	-17	-10	mV
<b>PROTECTION FEATURES</b>						
	Thermal warning	Temperature rising, CONFIG(TDIE_WARN_LEVEL) = 0		125		°C
		Temperature rising, CONFIG(TDIE_WARN_LEVEL) = 1		105		
		Hysteresis		15		
	Thermal shutdown	Temperature rising		150		°C
		Hysteresis		15		
VANA <sub>UVLO</sub>	VANA undervoltage lockout	Voltage falling	2.3	2.4	2.5	V
		Hysteresis		50		mV
<b>LOAD CURRENT MEASUREMENT</b>						
	Current measurement range	Maximum code		20.46		A
	Resolution	LSB		20		mA
	Measurement accuracy	$I_{OUT} \geq 1\text{ A}$		< 10%		
<b>CURRENT CONSUMPTION</b>						

## 6.5 Electrical Characteristics (continued)

Limits apply over the junction temperature range  $-40^{\circ}\text{C} \leq T_J \leq +125^{\circ}\text{C}$ , specified  $V_{(VANA)}$ ,  $V_{IN}$ ,  $V_{(NRST)}$ ,  $V_{OUT}$  and  $I_{OUT}$  range, unless otherwise noted. Typical values are at  $T_J = 25^{\circ}\text{C}$ ,  $f_{SW} = 3\text{ MHz}$ ,  $V_{(VANA)} = V_{IN} = 3.7\text{ V}$  and  $V_{OUT} = 1\text{ V}$ , unless otherwise noted. <sup>(1)</sup> <sup>(2)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Shutdown current consumption		$V_{(NRST)} = 0\text{ V}$		1		$\mu\text{A}$
Standby current consumption, converter cores disabled		$V_{(NRST)} = 1.8\text{ V}$		6		$\mu\text{A}$
Active current consumption during PFM operation, one converter core enabled		$V_{(NRST)} = 1.8\text{ V}$ , $I_{OUT} = 0\text{ mA}$ , not switching		55		$\mu\text{A}$
Active current consumption during PWM operation, per converter core		$V_{(NRST)} = 1.8\text{ V}$ , $I_{OUT} = 0\text{ mA}$ , $L = 0.47\text{ }\mu\text{H}$		14.5		$\text{mA}$
<b>DIGITAL INPUT SIGNALS NRST, ENx, SCL, SDA</b>						
$V_{IL}$	Input low level				0.4	$\text{V}$
$V_{IH}$	Input high level		1.2			$\text{V}$
$V_{HYS}$	Hysteresis of Schmitt trigger inputs (SCL, SDA)		10	80	160	$\text{mV}$
ENx pulldown resistance		$\text{ENx\_PD} = 1$	350	500	720	$\text{k}\Omega$
NRST pulldown resistance		Always present	800	1200	1700	$\text{k}\Omega$
<b>DIGITAL OUTPUT SIGNALS nINT, SDA</b>						
$V_{OL}$	Output low level	$I_{SOURCE} = 2\text{ mA}$ ,			0.4	$\text{V}$
$R_P$	External pullup resistor for nINT	To VIO supply		10		$\text{k}\Omega$
<b>ALL DIGITAL INPUTS</b>						
$I_{LEAK}$	Input current	All logic inputs over pin voltage range	-1		1	$\mu\text{A}$

- (1) All voltage values are with respect to network ground.
- (2) Minimum (MIN) and maximum (MAX) limits are specified by design, test, or statistical analysis. Typical (TYP) numbers are not verified, but do represent the most likely norm.
- (3) The maximum output current can be limited by the forward current limit,  $I_{LIM\ FWD}$ . The maximum output current is available with 5-A forward current limit setting.
- (4) The final PFM-to-PWM and PWM-to-PFM switchover current varies slightly and is dependant on the output voltage, input voltage and the magnitude of inductor's ripple current.

## 6.6 I<sup>2</sup>C Serial Bus Timing Requirements

See table notes. <sup>(1)</sup> <sup>(2)</sup>

		MIN	MAX	UNIT
$f_{SCL}$	Serial clock frequency	Standard mode	100	$\text{kHz}$
		Fast mode	400	$\text{kHz}$
		Fast mode +	1	$\text{MHz}$
		High-speed mode, $C_b = 100\text{ pF}$	3.4	$\text{MHz}$
		High-speed mode, $C_b = 400\text{ pF}$	1.7	$\text{MHz}$
$t_{LOW}$	SCL low time	Standard mode	4.7	$\mu\text{s}$
		Fast mode	1.3	
		Fast mode +	0.5	
		High-speed mode, $C_b = 100\text{ pF}$	160	$\text{ns}$
		High-speed mode, $C_b = 400\text{ pF}$	320	



## 6.6 I<sup>2</sup>C Serial Bus Timing Requirements (continued)

See table notes. <sup>(1)</sup> <sup>(2)</sup>

		MIN	MAX	UNIT	
t <sub>HIGH</sub>	SCL high time	Standard mode	4	μs	
		Fast mode	0.6		
		Fast mode +	0.26		
		High-speed mode, C <sub>b</sub> = 100 pF	60	ns	
		High-speed mode, C <sub>b</sub> = 400 pF	120		
t <sub>SU,DAT</sub>	Data setup time	Standard mode	250	ns	
		Fast mode	100		
		Fast mode +	50		
		High-speed mode	10		
t <sub>HD,DAT</sub>	Data hold time	Standard mode	0	3.45	μs
		Fast mode	0	0.9	
		Fast mode +	0	ns	
		High-speed mode, C <sub>b</sub> = 100 pF	0		70
		High-speed mode, C <sub>b</sub> = 400 pF	0		150
t <sub>SU,STA</sub>	Setup time for a start or a repeated start condition	Standard mode	4.7	μs	
		Fast mode	0.6		
		Fast mode +	0.26	ns	
		High-speed mode	160		
t <sub>HD,STA</sub>	Hold time for a start or a repeated start condition	Standard mode	4	μs	
		Fast mode	0.6		
		Fast mode +	0.26	ns	
		High-speed mode	160		
t <sub>BUF</sub>	Bus free time between a stop and start condition	Standard mode	4.7	μs	
		Fast mode	1.3		
		Fast mode +	0.5		
t <sub>SU,STO</sub>	Setup time for a stop condition	Standard mode	4	μs	
		Fast mode	0.6		
		Fast mode +	0.26	ns	
		High-speed mode	160		
t <sub>rDA</sub>	Rise time of SDA signal	Standard mode		1000	ns
		Fast mode		300	
		Fast mode +		120	
		High-speed mode, C <sub>b</sub> = 100 pF		80	
		High-speed mode, C <sub>b</sub> = 400 pF		160	
t <sub>fDA</sub>	Fall time of SDA signal	Standard mode		250	ns
		Fast mode		250	
		Fast mode +		120	
		High-speed mode, C <sub>b</sub> = 100 pF		80	
		High-speed mode, C <sub>b</sub> = 400 pF		160	
t <sub>rCL</sub>	Rise time of SCL signal	Standard mode		1000	ns
		Fast mode		300	
		Fast mode +		120	
		High-speed Mode, C <sub>b</sub> = 100 pF		40	
		High-speed Mode, C <sub>b</sub> = 400 pF		80	

## 6.6 I<sup>2</sup>C Serial Bus Timing Requirements (continued)

See table notes.<sup>(1) (2)</sup>

		MIN	MAX	UNIT
t <sub>rCL1</sub>	Rise time of SCL signal after a repeated start condition and after an acknowledge bit	Standard mode	1000	ns
		Fast mode	300	
		Fast mode +	120	
		High-speed mode, C <sub>b</sub> = 100 pF	80	
		High-speed mode, C <sub>b</sub> = 400 pF	160	
t <sub>fCL</sub>	Fall time of a SCL signal	Standard mode	300	ns
		Fast mode	300	
		Fast mode +	120	
		High-speed mode, C <sub>b</sub> = 100 pF	40	
		High-speed mode, C <sub>b</sub> = 400 pF	80	
C <sub>b</sub>	Capacitive load for each bus line (SCL and SDA)		400	pF
t <sub>SP</sub>	Pulse width of spike suppressed in SCL and SDA lines (spikes that are less than the indicated width are suppressed)	Fast mode, fast mode +	50	ns
		High-speed mode	10	

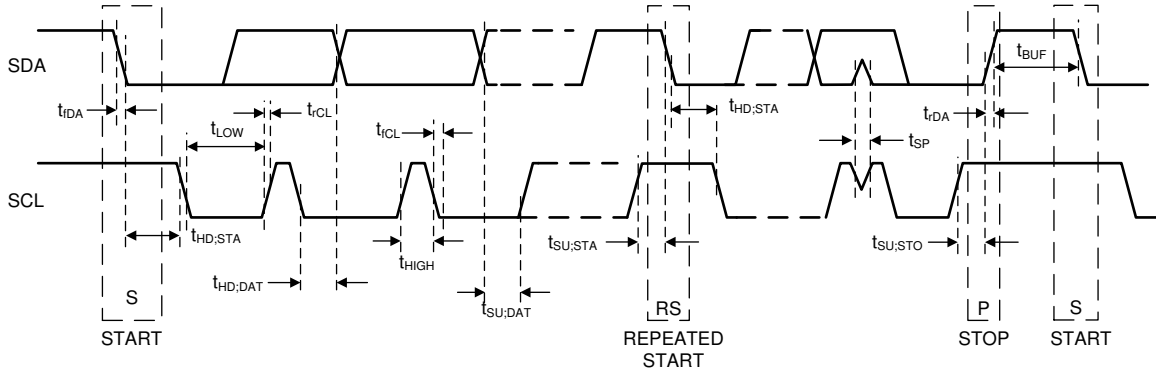
- (1) See [6-1](#) for timing diagram.  
 (2) C<sub>b</sub> refers to the capacitance of one bus line. C<sub>b</sub> is expressed in pF units.

## 6.7 Switching Characteristics

Limits apply over the junction temperature range  $-40^{\circ}\text{C} \leq T_J \leq +125^{\circ}\text{C}$ , specified V<sub>(VANA)</sub>, V<sub>IN</sub>, V<sub>(NRST)</sub>, V<sub>OUT</sub> and I<sub>OUT</sub> range, unless otherwise noted. Typical values are at T<sub>J</sub> = 25°C, f<sub>SW</sub> = 3 MHz, V<sub>(VANA)</sub> = V<sub>IN</sub> = 3.7 V and V<sub>OUT</sub> = 1 V, unless otherwise noted.<sup>(1)</sup>

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
f <sub>sw</sub>	Switching frequency, PWM mode	V <sub>OUT</sub> ≥ 0.6 V	2.7	3	3.3	MHz
		V <sub>OUT</sub> < 0.6 V	1.8	2	2.2	
Start-up time (soft start)	From ENx to V <sub>OUT</sub> = 0.225 V (slew-rate control begins), C <sub>OUT-TOTAL</sub> = 44 μF, no load		140		μs	
Output voltage slew-rate <sup>(2)</sup>	SLEW_RATEx[2:0] = 000, V <sub>OUT</sub> ≥ 0.5 V	-15%	30	15%	mV/μs	
	SLEW_RATEx[2:0] = 001, V <sub>OUT</sub> ≥ 0.5 V	-15%	15	15%		
	SLEW_RATEx[2:0] = 010, V <sub>OUT</sub> ≥ 0.5 V	-15%	10	15%		
	SLEW_RATEx[2:0] = 011, V <sub>OUT</sub> ≥ 0.5 V	-15%	7.5	15%		
	SLEW_RATEx[2:0] = 100, V <sub>OUT</sub> ≥ 0.5 V	-15%	3.8	15%		
	SLEW_RATEx[2:0] = 101, V <sub>OUT</sub> ≥ 0.5 V	-15%	1.9	15%		
	SLEW_RATEx[2:0] = 110, V <sub>OUT</sub> ≥ 0.5 V	-15%	0.94	15%		
	SLEW_RATEx[2:0] = 111, V <sub>OUT</sub> ≥ 0.5 V	-15%	0.4	0.4		15%
Load current measurement time	PFM mode (automatically changing to PWM mode for the measurement)		50		μs	
	PWM mode		4			

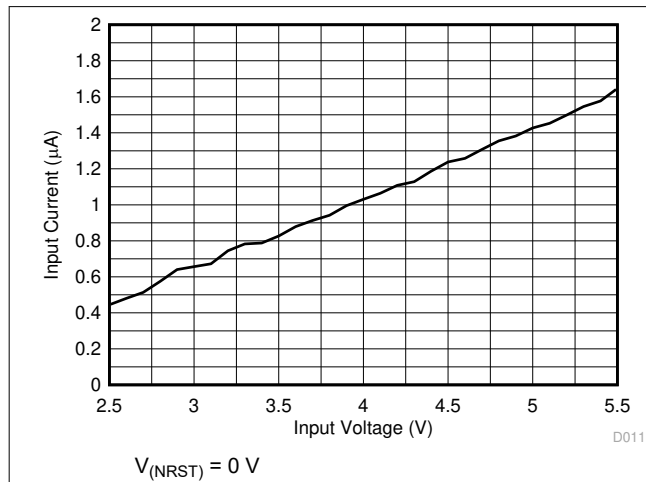
- (1) Minimum (MIN) and maximum (MAX) limits are specified by design, test, or statistical analysis. Typical (TYP) numbers are not verified, but do represent the most likely normal.  
 (2) Specified by design without testing. The slew-rate can be limited by the current limit (forward or negative current limit), output capacitance, and load current.



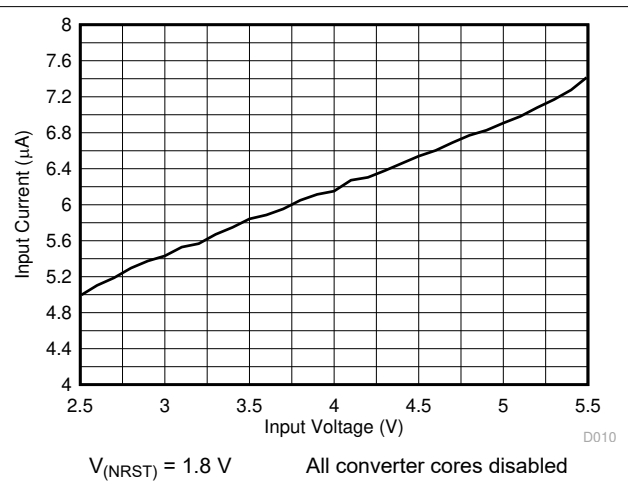
6-1. I<sup>2</sup>C Timing

## 6.8 Typical Characteristics

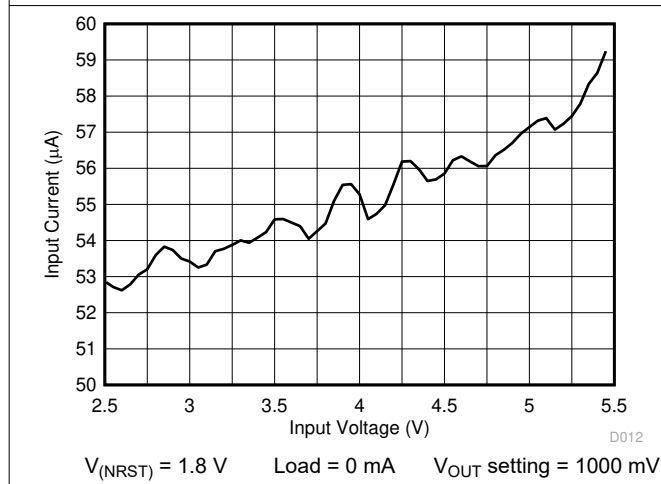
Unless otherwise specified:  $T_A = 25^\circ\text{C}$ ,  $V_{IN} = 3.7\text{ V}$ ,  $f_{SW} = 3\text{ MHz}$ ,  $L = 470\text{ nH}$ .



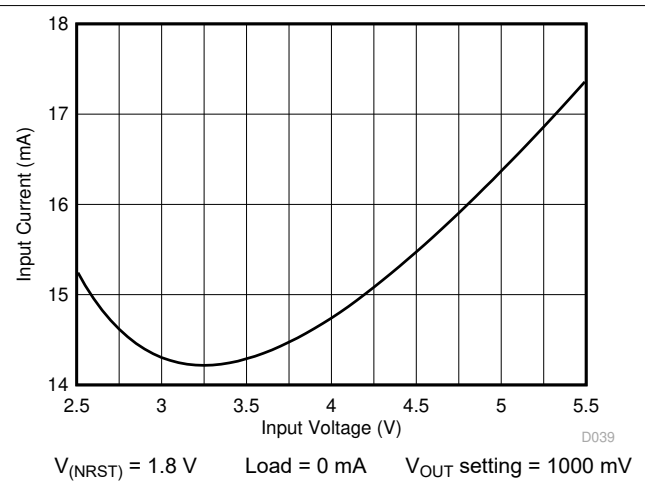
6-2. Shutdown Current Consumption vs Input Voltage



6-3. Standby Current Consumption vs Input Voltage



6-4. PFM Mode Current Consumption vs Input Voltage — One Output Enabled



6-5. PWM Mode Current Consumption vs Input Voltage — One Output Enable

## 7 Detailed Description

### 7.1 Overview

The LP8758-xx devices are a family of configurable step-down DC-DC converters with four converter cores. The LP8758-xx devices are ideally suited for systems powered from 2.5-V to 5.5-V supply voltage. In LP8758-EA the cores are configured for a four single-phase configuration. The LP8758-EA is well suited for space-constrained applications where high efficiency is required at low output voltages. Typical applications include network interface cards, modem cards, smart phones and mobile devices, solid-state drives (SSDs), systems-on-a-chip (SoCs), ASICs, and low power processors.

There are two modes of operation for the converter cores, depending on the output current required: pulse-width modulation (PWM) and pulse-frequency modulation (PFM). The cores operate in PWM mode at high load currents of approximately 600 mA or higher. Lighter output current loads cause the converter cores to automatically switch into PFM mode for reduced current consumption and a longer battery life when forced PWM mode is disabled. Additional features include soft-start, undervoltage lockout, overload protection, thermal warning, and thermal shutdown.

#### 7.1.1 Buck Information

The LP8758-EA has four integrated high-efficiency buck converter cores. The cores are designed for flexibility; most of the functions are programmable, thus giving a possibility to optimize the regulator operation for each application.

##### 7.1.1.1 Operating Modes

- OFF: Output is isolated from the input voltage rail in this mode. Output has an optional pulldown resistor.
- PWM: Converter operates in buck configuration with fixed switching frequency.
- PFM: Converter switches only when output voltage decreases below programmed threshold. Inductor current is discontinuous.

##### 7.1.1.2 Programmability

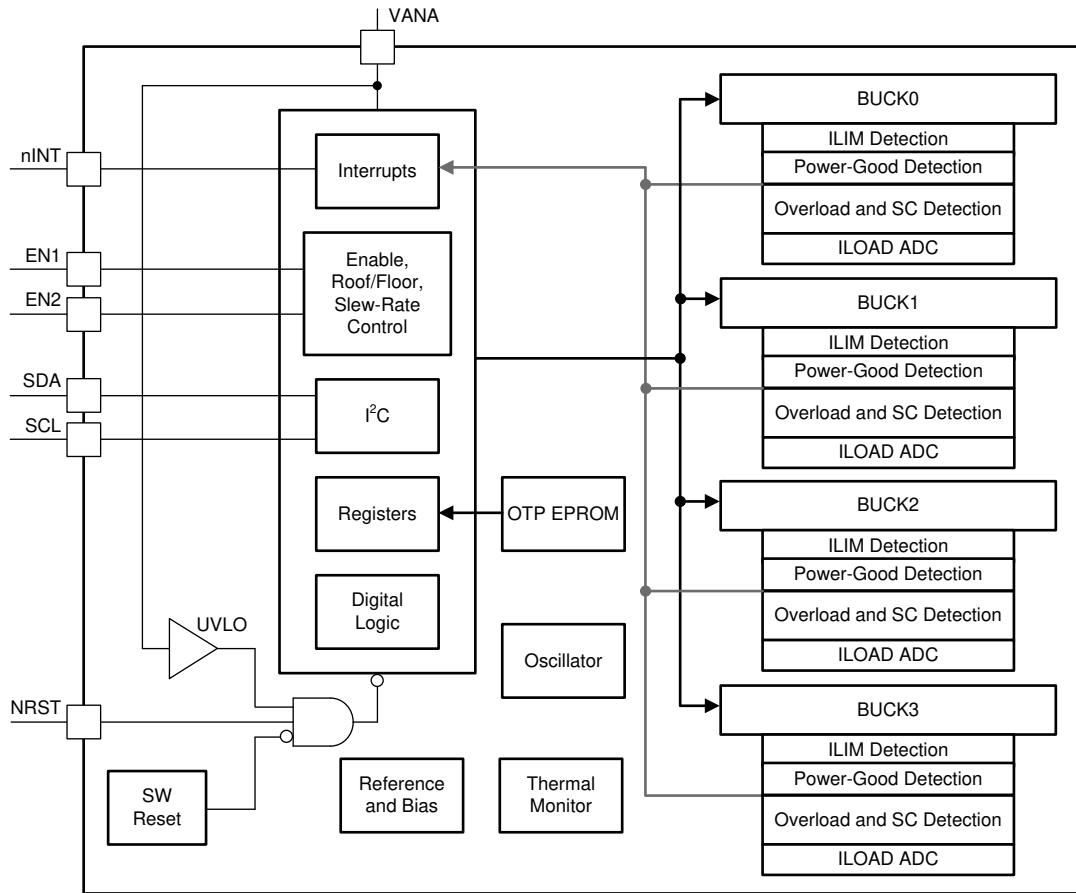
The following parameters can be programmed through registers:

- Output voltage
- Forced PWM operation
- Switch current limit
- Output voltage slew rate
- Enable and disable delays

##### 7.1.1.3 特長

- プログラム可能なスルーレートを備えた動的電圧スケーリング (DVS) のサポート
- 負荷に基づく自動モード制御
- 同期整流
- PI 補償器を使った電流モード・ループ
- オプションのスペクトラム拡散方式により EMI を低減
- ソフト・スタート
- マスク可能割り込みによるパワーグッド・フラグ
- 位相制御により EMI を最適化: 4 つの降圧コアは互いに 90° 異なる位相で動作するため、入力リップル電流が減少
- 平均出力電流センシング (PFM エントリ、負荷電流測定用)
- 負荷ポイントからの電圧センシング

## 7.2 Functional Block Diagram

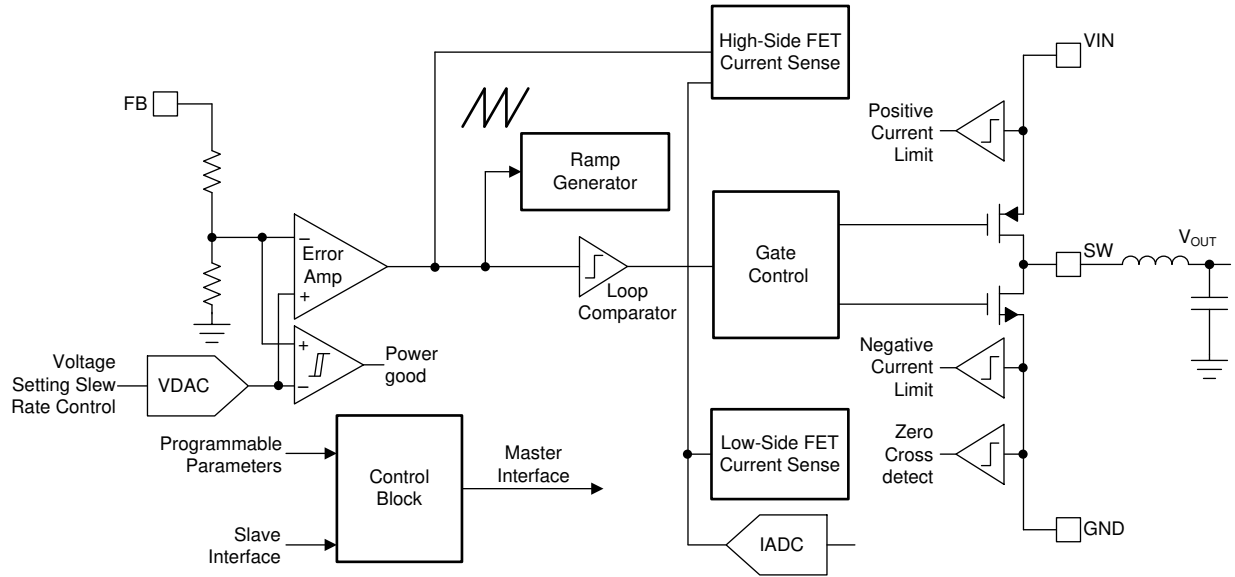


## 7.3 Feature Description

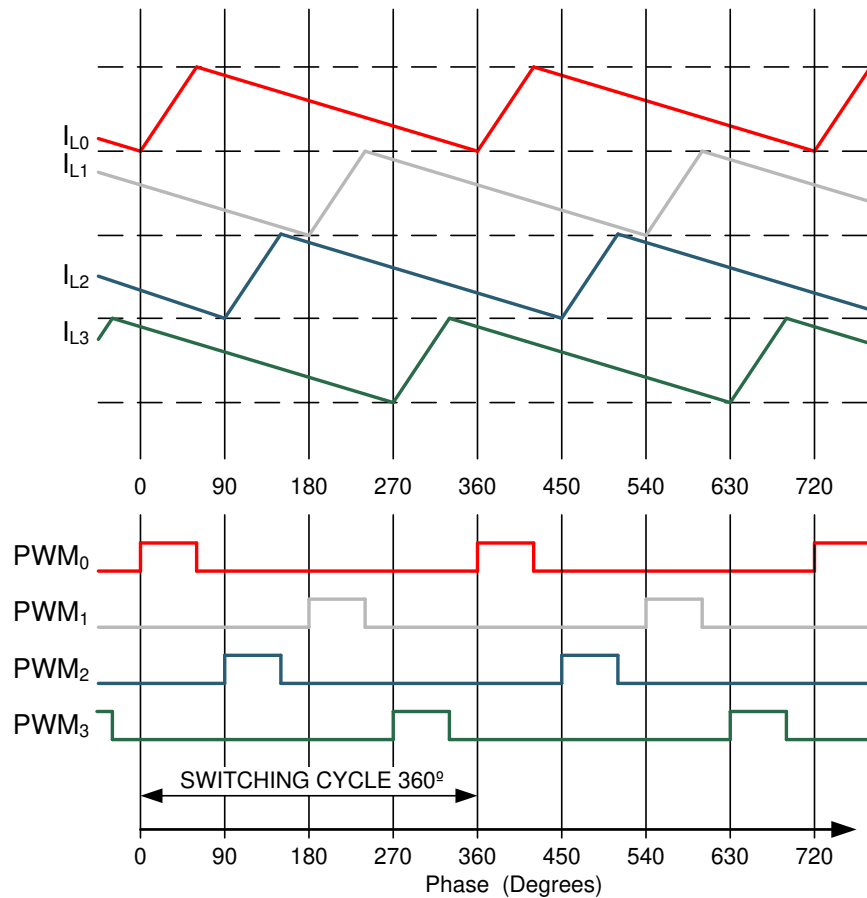
### 7.3.1 Overview

A block diagram of a single core is shown in [Figure 7-1](#).

Interleaving switching action of the converters is illustrated in [Figure 7-2](#). The LP8758-EA regulator switches each core 90° apart, reducing input ripple current.



**7-1. Detailed Block Diagram Showing One Core**



**7-2. PWM Timings and Inductor Current Waveforms <sup>1</sup>**

<sup>1</sup> Graph is not in scale and is for illustrative purposes only.

### 7.3.1.1 Transition Between PWM and PFM Modes

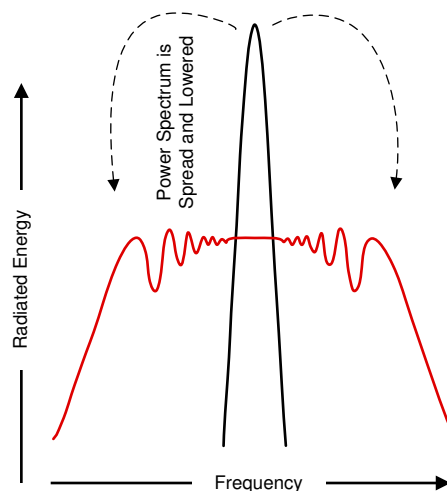
The LP8758-EA converter cores operate in PWM mode at load current of about 600 mA or higher. At lighter load current levels the cores automatically switches into PFM mode for reduced current consumption when Forced PWM mode is disabled (AUTO mode operation). By combining the PFM and the PWM modes a high efficiency is achieved over a wide output-load current range.

### 7.3.1.2 Buck Converter Load Current Measurement

Buck load current can be monitored via I<sup>2</sup>C registers. The monitored buck converter core is selected with the SEL\_I\_LOAD.LOAD\_CURRENT\_BUCK\_SELECT[1:0] register bits. A write to this selection register starts a current measurement sequence. The measurement sequence is typically 50  $\mu$ s long. The LP8758-EA device can be configured to give out an interrupt INT\_TOP.I\_LOAD\_READY after the load current measurement sequence is finished. Load current measurement interrupt can be masked with TOP\_MASK.I\_LOAD\_READY\_MASK bit. The measurement result can be read from registers I\_LOAD\_1 and I\_LOAD\_2. Register I\_LOAD\_1 bits BUCK\_LOAD\_CURRENT[7:0] give out the LSB bits and register I\_LOAD\_2 bits BUCK\_LOAD\_CURRENT[9:8] the MSB bits. The measurement result BUCK\_LOAD\_CURRENT[9:0] LSB is 20 mA, and maximum value of the measurement is 20.46 A.

### 7.3.1.3 Spread-Spectrum Mode

Systems with periodic switching signals may generate a large amount of switching noise in a set of narrowband frequencies (the switching frequency and its harmonics). The usual solution to reduce noise coupling is to add EMI-filters and shields to the boards. The register-selectable spread-spectrum mode of the device minimizes the need for output filters, ferrite beads, or chokes. In spread-spectrum mode, the switching frequency varies randomly by  $\pm 5\%$  about the center frequency, reducing the EMI emissions radiated by the converter and associated passive components and PCB traces (see [Figure 7-3](#)). This feature is enabled with the CONFIG.EN\_SPREAD\_SPEC bit, and it affects all the buck converter cores.



Where a fixed frequency converter exhibits large amounts of spectral energy at the switching frequency, the spread spectrum architecture of the  $v$  spreads that energy over a large bandwidth.

**Figure 7-3. Spread-Spectrum Modulation**

### 7.3.2 Power-Up

The power-up sequence for the LP8758-EA is as follows:

- VANA (and VIN\_Bx) reach minimum recommended levels ( $V_{(VANA)} > VANA_{UVLO}$ ).
- NRST is set to high level. This initiates power-on-reset (POR), OTP reading and enables the system I/O interface. The I<sup>2</sup>C host must allow at least 1.2 ms before writing or reading data to the LP8758-EA.
- The device enters STANDBY mode.
- The host can change the default register setting by I<sup>2</sup>C if needed.

- One or more of the converter cores can be enabled or disabled by one or more of the ENx pins and by the I<sup>2</sup>C interface.

### 7.3.3 Regulator Control

#### 7.3.3.1 Enabling and Disabling

The buck converter cores can be enabled when the device is in STANDBY or ACTIVE state. There are two ways to enable and disable the buck converter cores:

- Using BUCKx\_CTRL1.EN\_BUCKx register bit (when BUCKx\_CTRL1.EN\_PIN\_CTRLx register bit is 0).
- Using EN1/2 control pins (BUCKx\_CTRL1.EN\_BUCKx register bit is 1 *and* BUCKx\_CTRL1.EN\_PIN\_CTRLx register bit is 1).

If the EN1/2 control pins are used for enable and disable, the delay from the control signal rising edge to start-up is set by BUCKx\_DELAY.BUCKx\_STARTUP\_DELAY[3:0] bits and the delay from control signal falling edge to shutdown is set by BUCKx\_DELAY.BUCKx\_SHUTDOWN\_DELAY[3:0] bits. The delays are valid only for EN1/2 signal and not for control with BUCKx\_CTRL1.EN\_BUCKx bit. The delay time implemented by EN1/2 has overall ±10% timing accuracy.

The control of the converter cores (with 0 ms delays) is shown in [表 7-1](#).

**表 7-1. Regulator Control**

CONTROL METHOD	ROW	EN_BUCKx	BUCKx_CTRL1 EN_PIN_CTRLx	BUCKx_CTRL1 EN_PIN_SELECTx	BUCKx_CTRL1 EN_ROOF_FLOORx	EN1 PIN	EN2 PIN	BUCKx OUTPUT VOLTAGE
Enable or disable control with EN_BUCKx bit	1	0	Don't Care	Don't Care	Don't Care	Don't Care	Don't Care	Disabled
	2	1	0	Don't Care	Don't Care	Don't Care	Don't Care	BUCKx_VOUT.BUCKx_VSET[7:0]
Enable or disable control with EN1 pin	3	1	1	0	0	Low	Don't Care	Disabled
	4	1	1	0	0	High	Don't Care	BUCKx_VOUT.BUCKx_VSET[7:0]
Enable or disable control with EN2 pin	5	1	1	1	0	Don't Care	Low	Disabled
	6	1	1	1	0	Don't Care	High	BUCKx_VOUT.BUCKx_VSET[7:0]
Roof or floor control with EN1 pin	7	1	1	0	1	Low	Don't Care	BUCKx_FLOOR_VOUT.BUCKx_FLOOR_VSET[7:0]
	8	1	1	0	1	High	Don't Care	BUCKx_VOUT.BUCKx_VSET[7:0]
Roof or floor control with EN2 pin	9	1	1	1	1	Don't Care	Low	BUCKx_FLOOR_VOUT.BUCKx_FLOOR_VSET[7:0]
	10	1	1	1	1	Don't Care	High	BUCKx_VOUT.BUCKx_VSET[7:0]

The following buck configuration bit settings allows the device to enable or disable the corresponding buck using the ENx pin:

- BUCKx\_CTRL1.EN\_BUCKx = 1
- BUCKx\_CTRL1.EN\_PIN\_CTRLx = 1
- BUCKx\_CTRL1.EN\_ROOF\_FLOORx = 0
- BUCKx\_VOUT.BUCKx\_VSET[7:0] = Required voltage when the ENx pin is high
- The enable pin for control is selected with BUCKx\_CTRL1.EN\_PIN\_SELECTx

When the ENx pin is low, [表 7-1](#) row 3 (or 5) is valid, and the converter core is disabled. By setting ENx pin high, [表 7-1](#) row 4 (or 6) is valid, and the converter core is enabled with required voltage.

If a converter core is enabled all the time, and the ENx pin controls selection between the two voltage levels, then the following configuration is used:

- BUCKx\_CTRL1.EN\_BUCKx = 1
- BUCKx\_CTRL1.EN\_PIN\_CTRLx = 1
- BUCKx\_CTRL1.EN\_ROOF\_FLOORx = 1
- BUCKx\_VOUT.BUCKx\_VSET[7:0] = Required voltage when the ENx pin is high
- The enable pin for control is selected with BUCKx\_CTRL1.EN\_PIN\_SELECTx

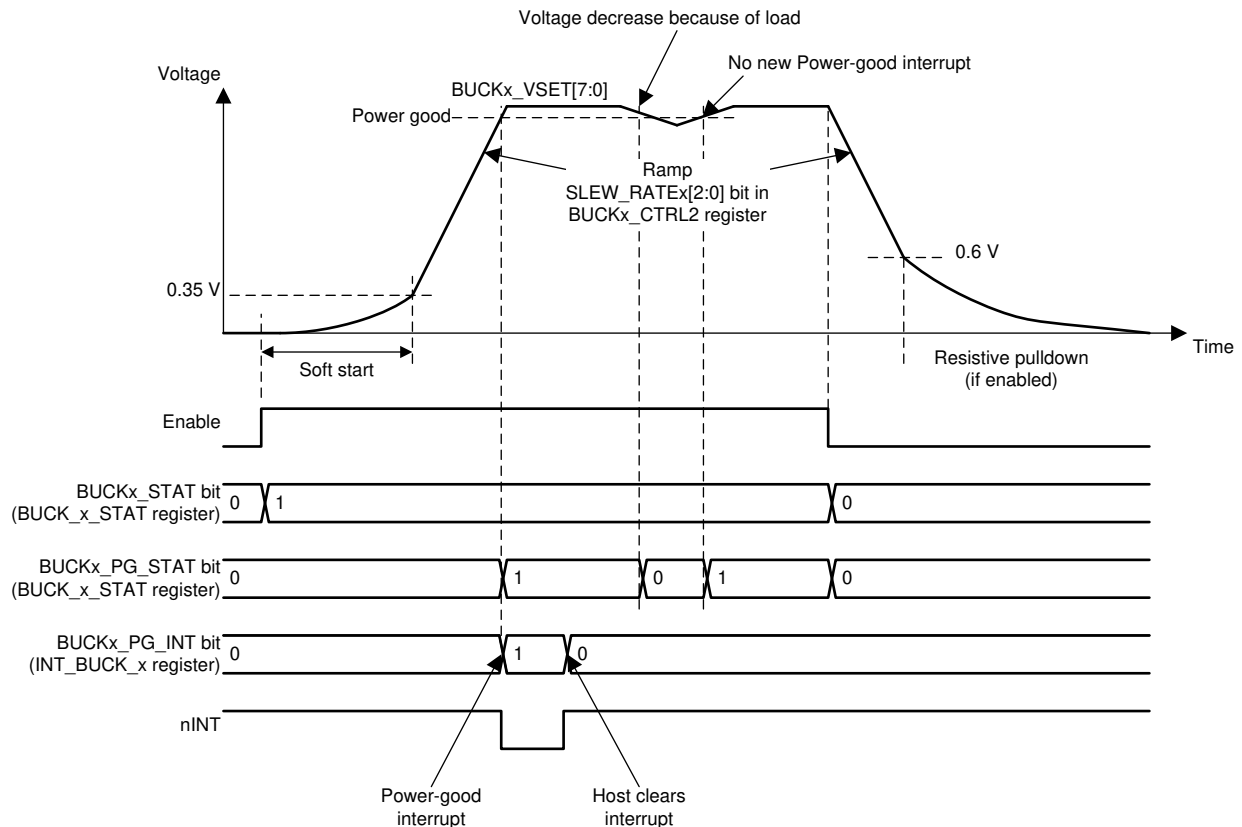
When the ENx pin is low, [表 7-1](#) row 7 (or 9) is valid, and the core is enabled with a voltage defined by BUCKx\_FLOOR\_VOUT.BUCKx\_FLOOR\_VSET[7:0] bits. Setting the ENx pin high, [表 7-1](#) row 8 (or 10) is valid, and the core is enabled with a voltage defined by BUCKx\_VOUT.BUCKx\_VSET[7:0] bits.



If the core is controlled by I<sup>2</sup>C writings, the BUCKx\_CTRL1.EN\_PIN\_CTRLx bit is set to 0. The enable or disable is controlled by the BUCKx\_CTRL1.EN\_BUCKx bit, and when the regulator is enabled, the output voltage is defined by the BUCKx\_VOUT.BUCKx\_VSET[7:0] bits. The 表 7-1 rows 1 and 2 are valid for I<sup>2</sup>C controlled operation (ENx pins are ignored).

The buck converter core is enabled by the ENx pin or by I<sup>2</sup>C writing as shown in 图 7-4. The soft-start circuit limits the in-rush current during start-up. Output voltage increase rate is around 5 mV/μsec during soft-start. When the output voltage rises to approximately 0.3 V, the output voltage becomes slew-rate controlled. If there is a short circuit at the output, and the output voltage does not increase above a 0.35-V level in 1 ms, the converter core is disabled, and interrupt is set. When the output voltage reaches the powergood threshold level the INT\_BUCK\_x.BUCKx\_PG\_INT interrupt flag is set. The powergood interrupt flag can be masked using BUCK\_x\_MASK.BUCKx\_PG\_MASK bit.

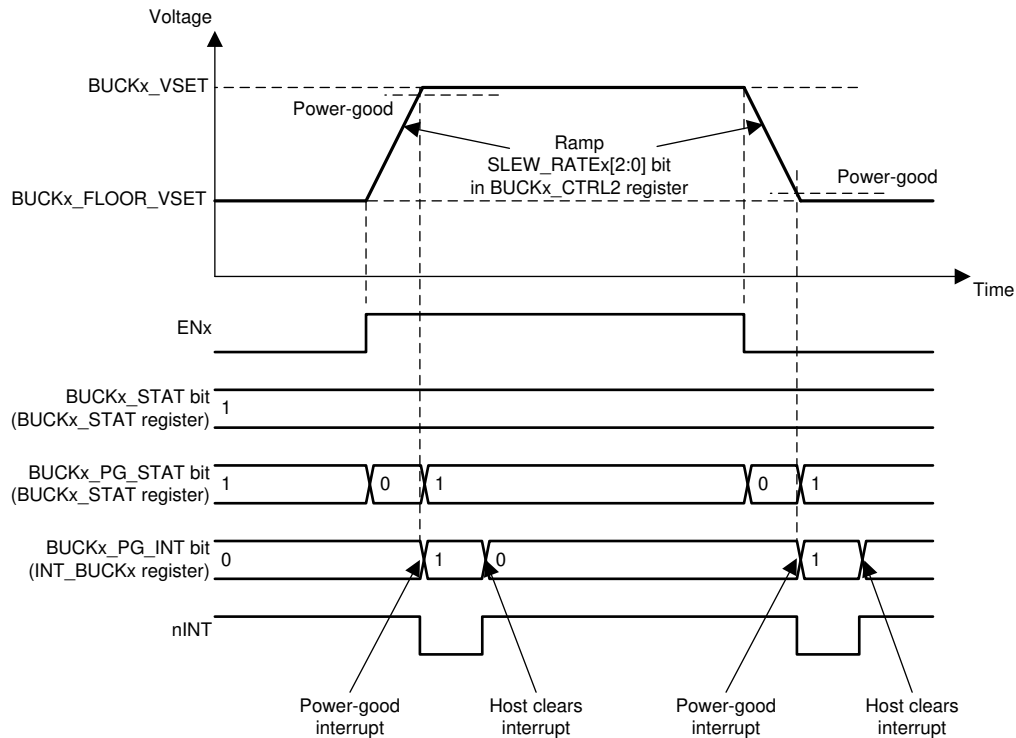
The ENx input pins have integrated pull-down resistors. The pull-down resistors are enabled by default and host can disable those with CONFIG.ENx\_PD bits.



**图 7-4. Converter Core Enable and Disable**

### 7.3.3.2 Changing Output Voltage

The converter core's output voltage can be changed by the ENx pin (voltage levels defined by the BUCKx\_VOUT and BUCKx\_FLOOR\_VOUT registers) or by writing to the BUCKx\_VOUT and BUCKx\_FLOOR\_VOUT registers. The voltage change is always slew-rate controlled, and the slew-rate is defined by the BUCKx\_CTRL2.SLEW\_RATEEx[2:0] bits. During voltage change the Forced PWM mode is used automatically. When the programmed output voltage is achieved, the mode becomes the one defined by load current, and the BUCKx\_CTRL1.BUCKx\_FPWM bit.



**7-5. Output Voltage Change**

### 7.3.4 Device Reset Scenarios

There are three reset methods implemented on the LP8758-EA:

- Software reset with RESET.SW\_RESET register bit;
- Reset from low logic level of NRST signal; and
- Undervoltage lockout (UVLO) reset from VANA supply.

A SW-reset occurs when RESET.SW\_RESET bit is written 1. The bit is automatically cleared after writing. This event disables all the buck converter cores immediately, resets all the register bits to the default values and OTP bits are loaded (see [7-7](#)). I<sup>2</sup>C interface is not reset during software reset.

If VANA supply voltage falls below UVLO threshold level or NRST signal is set low, then all the converter cores are disabled immediately, and all the register bits are reset to the default values. When the VANA supply voltage is above UVLO threshold level and NRST signal rises above threshold level an internal power-on reset (POR) occurs. OTP bits are loaded to the registers, and a start-up is initiated according to the register settings.

### 7.3.5 Diagnosis and Protection Features

The LP8758-EA is capable of providing three levels of protection features:

- Warnings for diagnosis which sets interrupt;
- Protection events which are disabling one or more converter cores; and
- Faults which are causing the device to shutdown.

When the device detects one or more warning or protection conditions, the LP8758-EA sets the flag bits indicating what protection or warning conditions have occurred, and the nINT pin is pulled low. nINT is released again after a clear of flags is complete. The nINT signal stays low until all the pending interrupts are cleared.

When a fault is detected, it is indicated by a INT\_TOP.RESET\_REG interrupt flag after next start-up.

**表 7-2. Summary of Interrupt Signals**

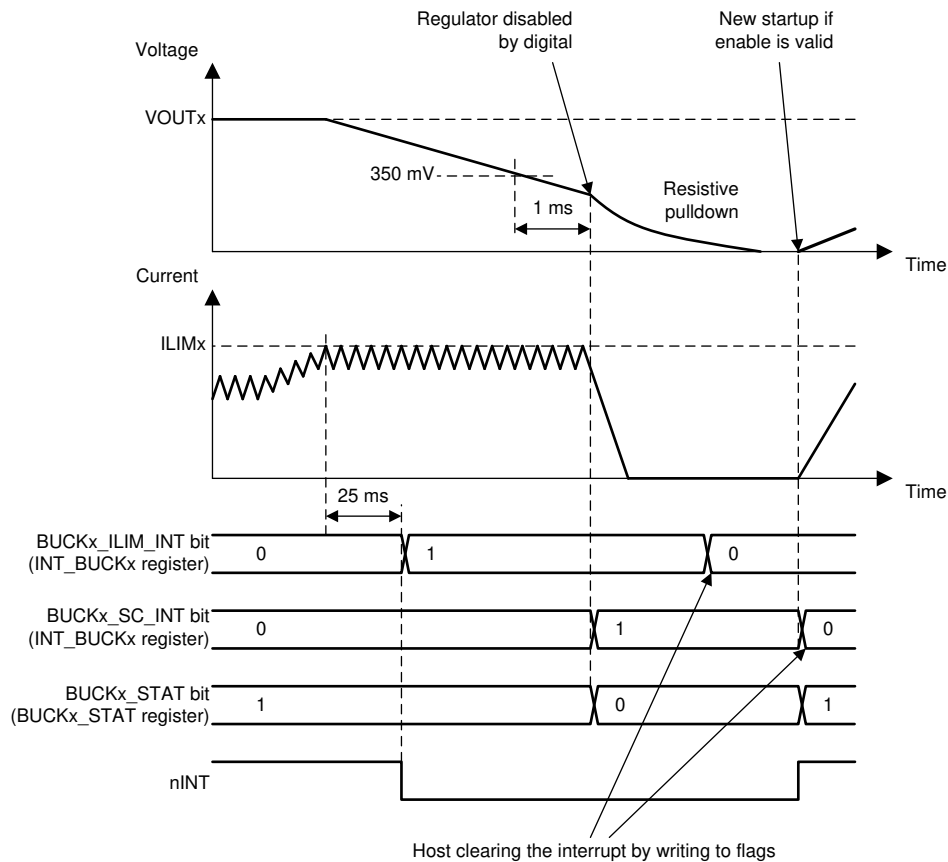
EVENT	RESULT	INTERRUPT REGISTER AND BIT	INTERRUPT MASK	STATUS BIT	RECOVERY / INTERRUPT CLEAR
Current limit triggered (20 $\mu$ s debounce)	No effect	INT_TOP.INT_BUCKx = 1 INT_BUCKx.BUCKx_ILIM_INT = 1	BUCKx_MASK.BUCKx_ILIM_MASK	BUCKx_STAT.BUCKx_ILIM_STAT	Write 1 to INT_BUCKx.BUCKx_ILIM_INT bit Interrupt is not cleared if current limit is active
Short circuit ( $V_{OUT} < 0.35$ V at 1 ms after enable) or overload ( $V_{OUT}$ decreasing below 0.35 V during operation, 1 ms debounce)	Converter core disable	INT_TOP.INT_BUCKx = 1 INT_BUCK_0_1.BUCKx_SC_INT = 1 or INT_BUCK_2_3.BUCKx_SC_INT = 1	N/A	N/A	Write 1 to INT_BUCK_0_1.BUCKx_SC_INT or to INT_BUCK_2_3.BUCKx_SC_INT bit
Thermal Warning	No effect	INT_TOP.TDIE_WARN = 1	TOP_MASK.TDIE_WARN_MASK	TOP_STAT.TDIE_WARN_STAT	Write 1 to INT_TOP.TDIE_WARN bit Interrupt is not cleared if temperature is above thermal warning level
Thermal Shutdown	All converter cores disabled	INT_TOP.TDIE_SD = 1	N/A	TOP_STAT.TDIE_SD_STAT	Write 1 to INT_TOP.TDIE_SD bit Interrupt is not cleared if temperature is above thermal shutdown level
Powergood, output voltage reaches the programmed value	No effect	INT_TOP.INT_BUCKx = 1 INT_BUCK_0_1.BUCKx_PG_INT = 1 or INT_BUCK_2_3.BUCKx_PG_INT = 1	BUCK_0_1_MASK.BUCKx_PG_MASK BUCK_2_3_MASK.BUCKx_PG_MASK	BUCK_0_1_STAT.BUCKx_PG_STAT BUCK_2_3_STAT.BUCKx_PG_STAT	Write 1 to INT_BUCK_0_1.BUCKx_PG_INT bit or to INT_BUCK_2_3.BUCKx_PG_INT bit
Load current measurement ready	No effect	INT_TOP.I_LOAD_READY = 1	TOP_MASK.I_LOAD_READY_MASK	N/A	Write 1 to INT_TOP.I_LOAD_READY bit
Start-up (NRST rising edge)	Device ready for operation, registers reset to default values	INT_TOP.RESET_REG = 1	TOP_MASK.RESET_REG_MASK	N/A	Write 1 to INT_TOP.RESET_REG bit
Glitch on supply voltage and UVLO triggered (VANA falling and rising)	Immediate shutdown followed by powerup, registers reset to default values	INT_TOP.RESET_REG = 1	TOP_MASK.RESET_REG_MASK	N/A	Write 1 to INT_TOP.RESET_REG bit
Software requested reset	Immediate shutdown followed by powerup, registers reset to default values	INT_TOP.RESET_REG = 1	TOP_MASK.RESET_REG_MASK	N/A	Write 1 to INT_TOP.RESET_REG bit

### 7.3.5.1 Warnings for Diagnosis (Interrupt)

#### 7.3.5.1.1 Output Current Limit

The converter cores have programmable output peak current limits. The limits are individually programmed for all buck converter cores with BUCKx\_CTRL2.ILIMx[2:0] bits. If the load current is increased so that the current limit is triggered, the regulator continues to regulate to the limit current level (current peak regulation). The voltage may decrease if the load current is higher than limit current. If the current regulation continues for 20  $\mu$ s, the LP8758-EA device sets the INT\_BUCKx.BUCKx\_ILIM\_INT bit and pulls the nINT pin low. The host processor can read BUCKx\_STAT.BUCKx\_ILIM\_STAT bits to see if the converter cores is still in peak current regulation mode.

For example, if the load on Buck0 output is so high that the output voltage  $V_{OUT}$  decreases below a 350-mV level, the LP8758-EA device disables the converter core Buck0 and sets the INT\_BUCK\_0\_1.BUCK0\_SC\_INT bit. In addition the BUCK\_0\_1\_STAT.BUCK0\_STAT bit is set to 0. The interrupt is cleared when the host processor writes 1 to INT\_BUCK\_0\_1.BUCK0\_SC\_INT bit. The overload situation is shown in [Figure 7-6](#).



**7-6. Overload Situation**

### 7.3.5.1.2 Thermal Warning

The LP8758-EA device includes protection features against overtemperature by setting an interrupt for host processor. The threshold level of the thermal warning is selected with CONFIG.TDIE\_WARN\_LEVEL bit.

If the LP8758-EA device temperature increases above the thermal warning level, the device sets INT\_TOP.TDIE\_WARN bit and pulls nINT pin low. The status of the thermal warning can be read from TOP\_STAT.TDIE\_WARN\_STAT bit, and the interrupt is cleared by writing 1 to INT\_TOP.TDIE\_WARN bit.

### 7.3.5.2 Protection (Regulator Disable)

If the regulator is disabled because of protection or fault (short-circuit protection, overload protection, thermal shutdown, or undervoltage lockout), the output power FETs are set to high-impedance mode, and the output pulldown resistor is enabled (if enabled with the BUCKx\_CTRL1.EN\_RDISx bits). The turnoff time of the output voltage is defined by the output capacitance, load current, and the resistance of the integrated pulldown resistor.

#### 7.3.5.2.1 Short-Circuit and Overload Protection

A short-circuit protection feature allows the LP8758-EA to protect itself and external components against short circuit at the output or against overload during start-up. The fault threshold is 350 mV, and the protection is triggered and the converter core is disabled if the output voltage is still below the threshold level 1 ms after the converter core was enabled.

In a similar way the overload situation is protected during normal operation. If a feedback-pin voltage falls below 0.35 V, and remains below the threshold level for 1 ms, the respective converter core is disabled.

For example, if the Buck core 0 output is overloaded, then the INT\_BUCK\_0\_1.BUCK0\_SC\_INT and the INT\_TOP.INT\_BUCK0 bits are set to 1, the BUCK\_0\_1\_STAT.BUCK0\_STAT bit is set to 0, and the nINT signal is pulled low. The host processor clears the interrupt by writing 1 to the INT\_BUCK\_0\_1.BUCK0\_SC\_INT bit. The

regulator makes a new start-up attempt (upon clearing the interrupt) if the enable register bits, ENx control signal, or both are valid.

### 7.3.5.2.2 Thermal Shutdown

The LP8758-EA has an over-temperature protection function that operates to protect itself from short-term misuse and overload conditions. When the junction temperature exceeds around 150°C, the cores are disabled, the INT\_TOP.TDIE\_SD bit is set to 1, the nINT signal is pulled low, and the device enters STANDBY. The nINT is cleared by writing 1 to the INT\_TOP.TDIE\_SD bit. If the temperature is above the thermal shutdown level, then the interrupt is not cleared. The host can read the status of the thermal shutdown from the TOP\_STAT.TDIE\_SD\_STAT bit. Converter cores cannot be enabled as long as the junction temperature is above the thermal shutdown level or the thermal shutdown interrupt is pending.

### 7.3.5.3 Fault (Power Down)

#### 7.3.5.3.1 Undervoltage Lockout

When the input voltage falls below  $VANA_{UVLO}$  at the VANA pin, the converter cores are disabled immediately, and the output capacitors are discharged using the pulldown resistors and the LP8758-EA device enters SHUTDOWN. When VANA voltage is above the UVLO threshold level and NRST signal is high, the device powers up to STANDBY state.

If the reset interrupt is unmasked by default ( $TOP\_MASK.RESET\_REG\_MASK = 0$ ) the INT\_TOP.RESET\_REG interrupt indicates that the device has been in SHUTDOWN. The host processor must clear the interrupt by writing 1 to the INT\_TOP.RESET\_REG bit. If the host processor reads the INT\_TOP.RESET\_REG flag after detecting an nINT low signal, it knows that the input supply voltage has been below UVLO level (or the host has requested reset), and the registers are reset to default values.

### 7.3.6 Digital Signal Filtering

The digital signals have debounce filtering. The signal or supply is sampled with a clock signal and a counter. This results as an accuracy of one clock period for the debounce window.

**表 7-3. Digital Signal Filtering**

EVENT	SIGNAL / SUPPLY	RISING EDGE LENGTH	FALLING EDGE LENGTH
Enable, disable, or voltage select for BUCKx	ENx	3 $\mu$ s <sup>(1)</sup>	3 $\mu$ s <sup>(1)</sup>
VANA undervoltage lockout	VANA	Immediate	Immediate
Thermal warning	TDIE_WARN	20 $\mu$ s	20 $\mu$ s
Thermal shutdown	TDIE_SD	20 $\mu$ s	20 $\mu$ s
Current limit	VOUTx_ILIM	20 $\mu$ s	20 $\mu$ s
Overload	FB_B0, FB_B1, FB_B2, FB_F3	1 ms	1 ms
Power-good	FB_B0, FB_B1, FB_B2, FB_F3	20 $\mu$ s	20 $\mu$ s

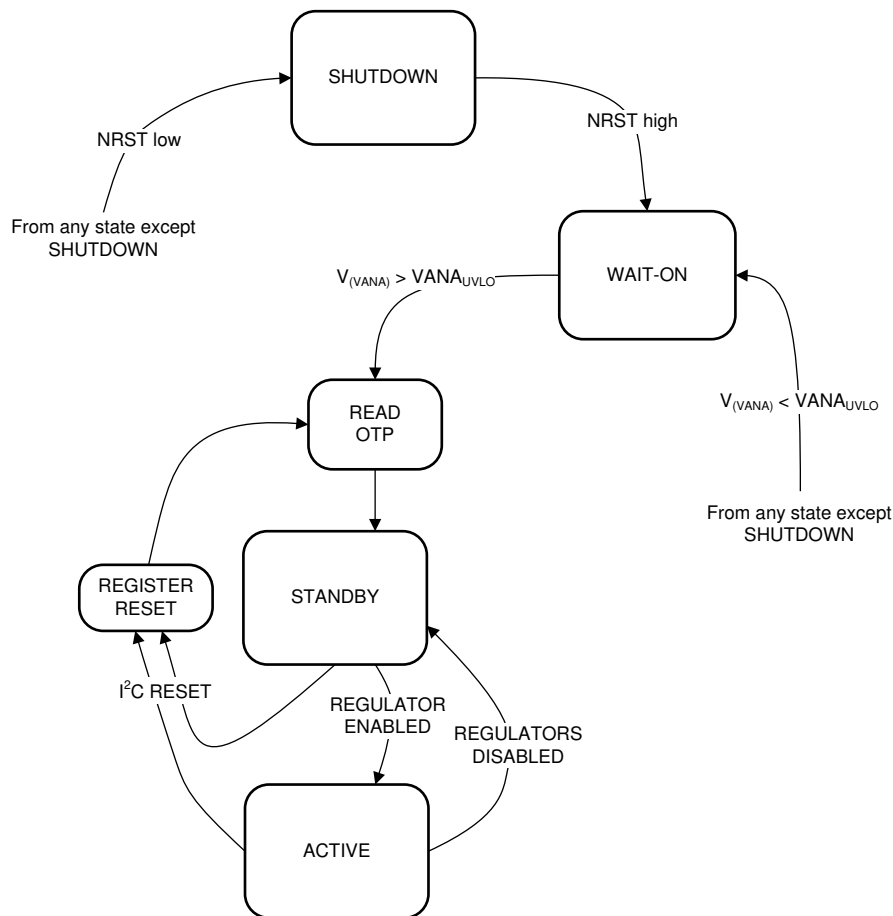
(1) No glitch filtering, only synchronization.

## 7.4 Device Functional Modes

### 7.4.1 Modes of Operation

- SHUTDOWN:** The  $V_{(NRST)}$  voltage is below threshold level. All switch, reference, control and bias circuitry of the LP8758-EA device are turned off.
- WAIT-ON:** The  $V_{(NRST)}$  voltage is above threshold level. The reference and bias circuitry are enabled. The converter cores of the LP8758-EA device are turned off.
- READ OTP:** The main supply voltage  $V_{(VANA)}$  is above  $VANA_{UVLO}$  level and  $V_{(NRST)}$  voltage is above threshold level. The converter cores are disabled and the reference and bias circuitry of the LP8758-EA are enabled. The OTP bits are loaded to registers.
- STANDBY:** The main supply voltage  $V_{(VANA)}$  is above  $VANA_{UVLO}$  level and  $V_{(NRST)}$  voltage is above threshold level. The converter cores are disabled and the reference, control and bias circuitry of the LP8758-EA are enabled. All registers can be read or written by the host processor through the system serial interface. The converter cores can be enabled if needed.
- ACTIVE:** The main supply voltage  $V_{(VANA)}$  is above  $VANA_{UVLO}$  level and  $V_{(NRST)}$  voltage is above threshold level. At least one converter core is enabled. All registers can be read or written by the host processor through the system serial interface.

The operating modes and transitions between the modes are shown in [Figure 7-7](#).



**Figure 7-7. Device Operation Modes**

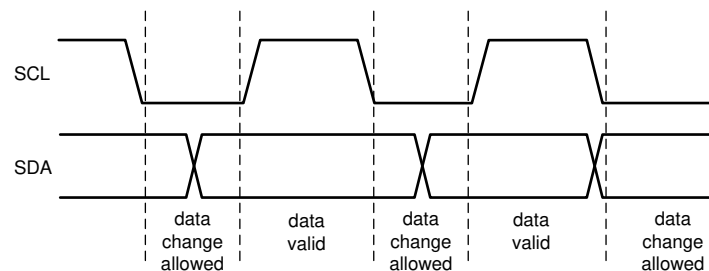
## 7.5 Programming

### 7.5.1 I<sup>2</sup>C-Compatible Interface

The I<sup>2</sup>C-compatible synchronous serial interface provides access to the programmable functions and registers on the device. This protocol uses a two-wire interface for bidirectional communications between the devices connected to the bus. The two interface lines are the Serial Data Line (SDA), and the Serial Clock Line (SCL). Every device on the bus is assigned a unique address and acts as either a master or a slave depending on whether it generates or receives the serial clock SCL. The SCL and SDA lines must each have a pullup resistor placed somewhere on the line and remain HIGH even when the bus is idle. The LP8758-EA supports standard mode (100 kHz), fast mode (400 kHz), fast mode plus (1 MHz), and high-speed mode (3.4 MHz).

#### 7.5.1.1 Data Validity

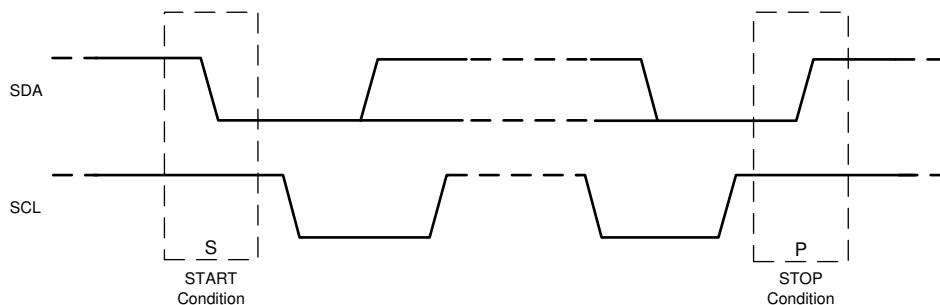
The data on the SDA line must be stable during the HIGH period of the clock signal (SCL). In other words, the state of the data line can only be changed when clock signal is LOW.



☒ 7-8. Data Validity Diagram

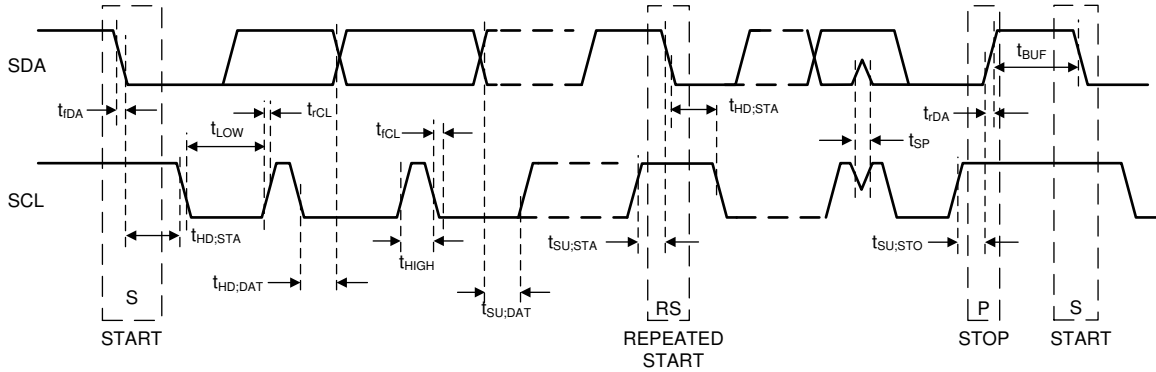
#### 7.5.1.2 Start and Stop Conditions

The LP8758-EA is controlled through an I<sup>2</sup>C-compatible interface. START and STOP conditions classify the beginning and end of the I<sup>2</sup>C session. A START condition is defined as SDA transitions from HIGH to LOW while SCL is HIGH. A STOP condition is defined as SDA transition from LOW to HIGH while SCL is HIGH. The I<sup>2</sup>C master always generates the START and STOP conditions.



☒ 7-9. Start and Stop Sequences

The I<sup>2</sup>C bus is considered busy after a START condition and free after a STOP condition. During data transmission the I<sup>2</sup>C master can generate repeated START conditions. A START and a repeated START condition are equivalent function-wise. The data on SDA must be stable during the HIGH period of the clock signal (SCL). In other words, the state of SDA can only be changed when SCL is LOW. ☒ 7-10 shows the SDA and SCL signal timing for the I<sup>2</sup>C-Compatible Bus. See the [セクション 6.6](#) for timing values.



**图 7-10. I<sup>2</sup>C-Compatible Timing**

### 7.5.1.3 Transferring Data

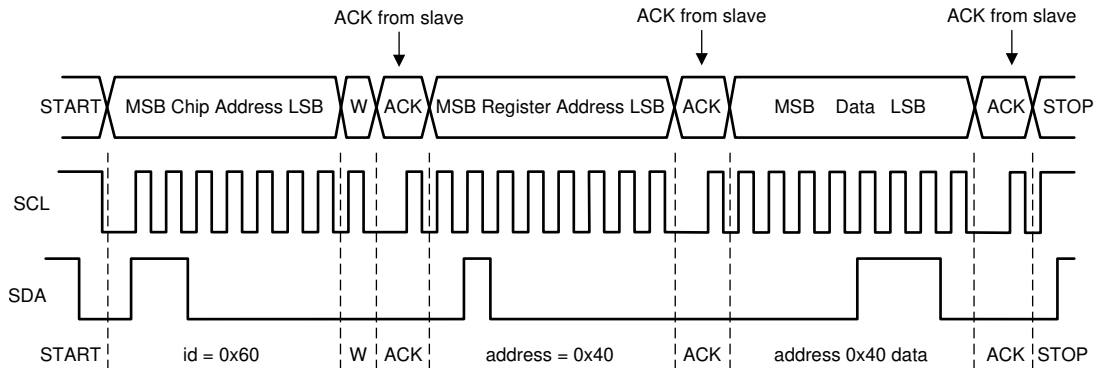
Every byte put on the SDA line must be eight bits long, with the most significant bit (MSB) being transferred first. Each byte of data has to be followed by an acknowledge bit. The acknowledge related clock pulse is generated by the master. The master releases the SDA line (HIGH) during the acknowledge clock pulse. The LP8758-EA pulls down the SDA line during the 9th clock pulse, signifying an acknowledge. The LP8758-EA generates an acknowledge after each byte has been received.

There is one exception to the *acknowledge after every byte* rule. When the master is the receiver, it must indicate to the transmitter an end of data by not-acknowledging (*negative acknowledge*) the last byte clocked out of the slave. This *negative acknowledge* still includes the acknowledge clock pulse (generated by the master), but the SDA line is not pulled down.

注

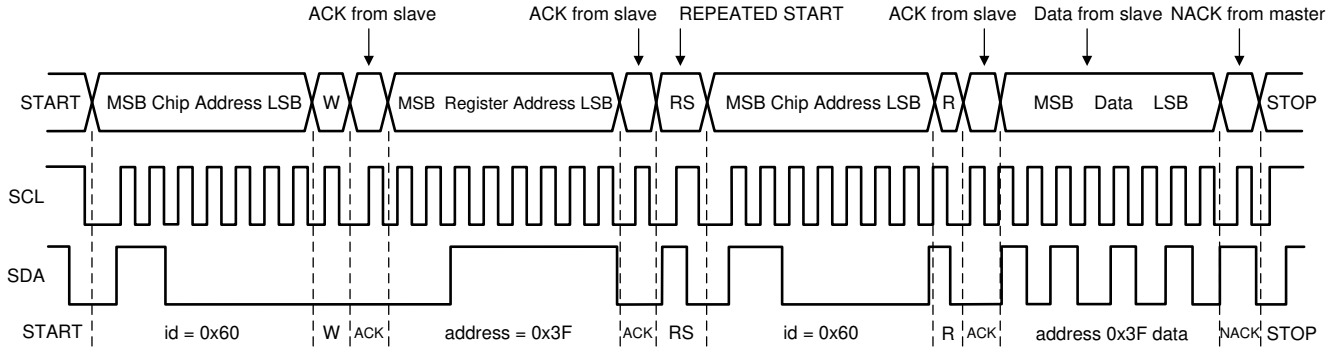
If the NRST signal is low during I<sup>2</sup>C communication the LP8758-EA device does not drive SDA line. The ACK signal and data transfer to the master is disabled at that time.

After the START condition, the bus master sends a chip address. This address is seven bits long followed by an eighth bit which is a data direction bit (READ or WRITE). For the eighth bit, a 0 indicates a WRITE, and a 1 indicates a READ. The second byte selects the register to which the data is written. The third byte contains data to write to the selected register.



**图 7-11. Write Cycle (w = write; SDA = 0), id = Device Address = 60Hex for LP8758-EA**



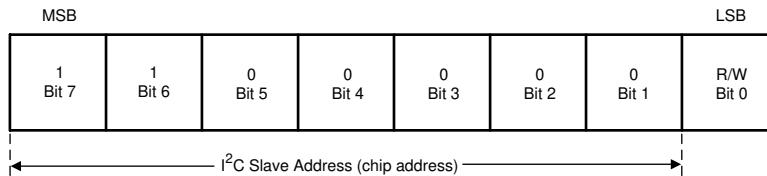


When READ function is to be accomplished, a WRITE function must precede the READ function as shown above.

图 7-12. Read Cycle ( r = read; SDA = 1), id = Device Address = 60Hex for LP8758-EA

### 7.5.1.4 I<sup>2</sup>C-Compatible Chip Address

The device address for the LP8758-EA is 0x60. After the START condition, the I<sup>2</sup>C master sends the 7-bit address followed by an eighth bit, read or write (R/W). R/W = 0 indicates a WRITE and R/W = 1 indicates a READ. The second byte following the device address selects the register address to which the data will be written. The third byte contains the data for the selected register.



Here device address is 110 0000Bin = .

图 7-13. Device Address

### 7.5.1.5 Auto Increment Feature

The auto-increment feature allows writing several consecutive registers within one transmission. Every time an 8-bit word is sent to the LP8758-EA, the internal address index counter is incremented by one and the next register is written. 表 7-4 below shows writing sequence to two consecutive registers. Note: the auto-increment feature does not work for read.

表 7-4. Auto-Increment Example

Master Action	Start	Device Address = 60H	Write	Register Address	Data	Data	Stop
LP8758-EA Action			ACK	ACK	ACK	ACK	

## 7.6 Register Maps

### 7.6.1 Register Descriptions

The LP8758-EA is controlled by a set of registers through the serial interface port. The device registers, their addresses and their abbreviations are listed in [表 7-5](#). A more detailed description is given in sections [セクション 7.6.1.1](#) to [セクション 7.6.1.35](#).

The asterisk (\*) marking indicates register bits which are updated from OTP memory during READ OTP state.

**表 7-5. Summary of LP8758-EA Control Registers**

Addr	Register	Read / Write	D7	D6	D5	D4	D3	D2	D1	D0
0x01	OTP_REV	R	OTP_ID[7:0]							
0x02	BUCK0_CTRL1	R/W	EN_BUCK0	EN_PIN_CTRL0	EN_PIN_SELECT0	EN_ROOF_FLOOR0	EN_RDIS0	Reserved	BUCK0_FPWM	Reserved
0x03	BUCK0_CTRL2	R/W	Reserved		ILIM0[2:0]			SLEW_RATE0[2:0]		
0x04	BUCK1_CTRL1	R/W	EN_BUCK1	EN_PIN_CTRL1	EN_PIN_SELECT1	EN_ROOF_FLOOR1	EN_RDIS1	Reserved	BUCK1_FPWM	Reserved
0x05	BUCK1_CTRL2	R/W	Reserved		ILIM1[2:0]			SLEW_RATE1[2:0]		
0x06	BUCK2_CTRL1	R/W	EN_BUCK2	EN_PIN_CTRL2	EN_PIN_SELECT2	EN_ROOF_FLOOR2	EN_RDIS2	Reserved	BUCK2_FPWM	Reserved
0x07	BUCK2_CTRL2	R/W	Reserved		ILIM2[2:0]			SLEW_RATE2[2:0]		
0x08	BUCK3_CTRL1	R/W	EN_BUCK3	EN_PIN_CTRL3	EN_PIN_SELECT3	EN_ROOF_FLOOR3	EN_RDIS3	Reserved	BUCK3_FPWM	Reserved
0x09	BUCK3_CTRL2	R/W	Reserved		ILIM3[2:0]			SLEW_RATE3[2:0]		
0x0A	BUCK0_VOUT	R/W	BUCK0_VSET[7:0]							
0x0B	BUCK0_FLOOR_VOUT	R/W	BUCK0_FLOOR_VSET[7:0]							
0x0C	BUCK1_VOUT	R/W	BUCK1_VSET[7:0]							
0x0D	BUCK1_FLOOR_VOUT	R/W	BUCK1_FLOOR_VSET[7:0]							
0x0E	BUCK2_VOUT	R/W	BUCK2_VSET[7:0]							
0x0F	BUCK2_FLOOR_VOUT	R/W	BUCK2_FLOOR_VSET[7:0]							
0x10	BUCK3_VOUT	R/W	BUCK3_VSET[7:0]							
0x11	BUCK3_FLOOR_VOUT	R/W	BUCK3_FLOOR_VSET[7:0]							
0x12	BUCK0_DELAY	R/W	BUCK0_SHUTDOWN_DELAY[3:0]				BUCK0_STARTUP_DELAY[3:0]			
0x13	BUCK1_DELAY	R/W	BUCK1_SHUTDOWN_DELAY[3:0]				BUCK1_STARTUP_DELAY[3:0]			
0x14	BUCK2_DELAY	R/W	BUCK2_SHUTDOWN_DELAY[3:0]				BUCK2_STARTUP_DELAY[3:0]			
0x15	BUCK3_DELAY	R/W	BUCK3_SHUTDOWN_DELAY[3:0]				BUCK3_STARTUP_DELAY[3:0]			
0x16	RESET	R/W	Reserved							SW_RESET
0x17	CONFIG	R/W	Reserved				TDIE_WARN_LEVEL	EN2_PD	EN1_PD	EN_SPREAD_SPEC

**表 7-5. Summary of LP8758-EA Control Registers (continued)**

Addr	Register	Read / Write	D7	D6	D5	D4	D3	D2	D1	D0	
0x18	INT_TOP	R/W	INT_BUCK3	INT_BUCK2	INT_BUCK1	INT_BUCK0	TDIE_SD	TDIE_WARN	RESET_REG	I_LOAD_READY	
0x19	INT_BUCK_0_1	R/W	Reserved	BUCK1_PG_INT	BUCK1_SC_INT	BUCK1_ILIM_INT	Reserved	BUCK0_PG_INT	BUCK0_SC_INT	BUCK0_ILIM_INT	
0x1A	INT_BUCK_2_3	R/W	Reserved	BUCK3_PG_INT	BUCK3_SC_INT	BUCK3_ILIM_INT	Reserved	BUCK2_PG_INT	BUCK2_SC_INT	BUCK2_ILIM_INT	
0x1B	TOP_STAT	R	Reserved				TDIE_SD_STAT	TDIE_WARN_STAT	Reserved		
0x1C	BUCK_0_1_STAT	R	BUCK1_STAT	BUCK1_PG_STAT	Reserved	BUCK1_ILIM_STAT	BUCK0_STAT	BUCK0_PG_STAT	Reserved	BUCK0_ILIM_STAT	
0x1D	BUCK_2_3_STAT	R	BUCK3_STAT	BUCK3_PG_STAT	Reserved	BUCK3_ILIM_STAT	BUCK2_STAT	BUCK2_PG_STAT	Reserved	BUCK2_ILIM_STAT	
0x1E	TOP_MASK	R/W	Reserved					TDIE_WARN_MASK	RESET_REG_MASK	I_LOAD_READY_MASK	
0x1F	BUCK_0_1_MASK	R/W	Reserved	BUCK1_PG_MASK	Reserved	BUCK1_ILIM_MASK	Reserved	BUCK0_PG_MASK	Reserved	BUCK0_ILIM_MASK	
0x20	BUCK_2_3_MASK	R/W	Reserved	BUCK3_PG_MASK	Reserved	BUCK3_ILIM_MASK	Reserved	BUCK2_PG_MASK	Reserved	BUCK2_ILIM_MASK	
0x21	SEL_I_LOAD	R/W	Reserved						LOAD_CURRENT_BUCK_SELECT[1:0]		
0x22	I_LOAD_2	R/W	Reserved						BUCK_LOAD_CURRENT[9:8]		
0x23	I_LOAD_1	R/W	BUCK_LOAD_CURRENT[7:0]								

### 7.6.1.1 OTP\_REV

Address: 0x01

D7	D6	D5	D4	D3	D2	D1	D0
OTP_ID[7:0]							
Bits	Field	Type	Default	Description			
7:0	OTP_ID[7:0]	R	0xEA *	Identification code of the OTP EPROM version.			

### 7.6.1.2 BUCK0\_CTRL1

Address: 0x02

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK0	EN_PIN_CTRL0	EN_PIN_SELECT0	EN_ROOF_FLOOR0	EN_RDIS0	Reserved	BUCK0_FPWM	Reserved
Bits	Field	Type	Default	Description			
7	EN_BUCK0	R/W	1 *	Enable BUCK0 converter core: 0 - BUCK0 converter core is disabled. 1 - BUCK0 converter core is enabled.			
6	EN_PIN_CTRL0	R/W	1 *	Enable EN1/2 pin control for BUCK0: 0 - only EN_BUCK0 bit controls BUCK0. 1 - EN_BUCK0 bit AND EN1/2 pin control BUCK0.			
5	EN_PIN_SELECT0	R/W	0 *	Select which ENx pin controls BUCK0 if EN_PIN_CTRL0 = 1: 0 - EN1 pin. 1 - EN2 pin.			
4	EN_ROOF_FLOOR0	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL0 = 1: 0 - Enable/Disable (1/0) control. 1 - Roof/Floor (1/0) control.			
3	EN_RDIS0	R/W	1	Enable output discharge resistor when BUCK0 is disabled: 0 - Discharge resistor disabled. 1 - Discharge resistor enabled.			
2	Reserved	R/W	0				
1	BUCK0_FPWM	R/W	0 *	Forces the BUCK0 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.			
0	Reserved	R/W	0				

### 7.6.1.3 BUCK0\_CTRL2

Address: 0x03

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM0[2:0]			SLEW_RATE0[2:0]		
Bits	Field	Type	Default	Description			
7:6	Reserved	R/W	00				
5:3	ILIM0[2:0]	R/W	0x6 *	Sets the switch current limit of BUCK0. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A			

Bits	Field	Type	Default	Description
2:0	SLEW_RATE0[2:0]	R/W	0x4 *	Sets the output voltage slew rate for BUCK0 converter core (rising and falling edges): 0x0 - 30 mV/μs 0x1 - 15 mV/μs 0x2 - 10 mV/μs 0x3 - 7.5 mV/μs 0x4 - 3.8 mV/μs 0x5 - 1.9 mV/μs 0x6 - 0.94 mV/μs 0x7 - 0.4 mV/μs

#### 7.6.1.4 BUCK1\_CTRL1

Address: 0x04

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK1	EN_PIN_CTRL1	EN_PIN_SELECT1	EN_ROOF_FLOOR1	EN_RDIS1	Reserved	BUCK1_FPWM	Reserved

Bits	Field	Type	Default	Description
7	EN_BUCK1	R/W	1 *	Enable BUCK1 converter core: 0 - BUCK1 converter core is disabled. 1 - BUCK1 converter core is enabled.
6	EN_PIN_CTRL1	R/W	1 *	Enable EN1/2 pin control for BUCK1: 0 - only EN_BUCK1 bit controls BUCK1. 1 - EN_BUCK1 bit AND EN1/2 pin control BUCK1.
5	EN_PIN_SELECT1	R/W	0 *	Select which ENx pin controls BUCK1 if EN_PIN_CTRL1 = 1: 0 - EN1 pin 1 - EN2 pin.
4	EN_ROOF_FLOOR1	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL1 = 1: 0 - Enable/Disable (1/0) control. 1 - Roof/Floor (1/0) control.
3	EN_RDIS1	R/W	1	Enable output discharge resistor when BUCK1 is disabled: 0 - Discharge resistor is disabled. 1 - Discharge resistor is enabled.
2	Reserved	R/W	0	
1	BUCK1_FPWM	R/W	0 *	Forces the BUCK1 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.
0	Reserved	R/W	0	

### 7.6.1.5 BUCK1\_CTRL2

Address: 0x05

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM1[2:0]			SLEW_RATE1[2:0]		
Bits	Field	Type	Default	Description			
7:6	Reserved	R/W	00				
5:3	ILIM1[2:0]	R/W	0x6 *	Sets the switch current limit of BUCK1. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A			
2:0	SLEW_RATE1[2:0]	R/W	0x4 *	Sets the output voltage slew rate for BUCK1 converter core (rising and falling edges): 0x0 - 30 mV/μs 0x1 - 15 mV/μs 0x2 - 10 mV/μs 0x3 - 7.5 mV/μs 0x4 - 3.8 mV/μs 0x5 - 1.9 mV/μs 0x6 - 0.94 mV/μs 0x7 - 0.4 mV/μs			

### 7.6.1.6 BUCK2\_CTRL1

Address: 0x06

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK2	EN_PIN_CTRL2	EN_PIN_SELECT2	EN_ROOF_FLOOR2	EN_RDIS2	Reserved	BUCK2_FPWM	Reserved
Bits	Field	Type	Default	Description			
7	EN_BUCK2	R/W	1 *	Enable BUCK2 converter core: 0 - BUCK2 converter core is disabled. 1 - BUCK2 converter core is enabled.			
6	EN_PIN_CTRL2	R/W	1 *	Enable EN1/2 pin control for BUCK2: 0 - only EN_BUCK2 bit controls BUCK2. 1 - EN_BUCK2 bit AND EN1/2 pin control BUCK2.			
5	EN_PIN_SELECT2	R/W	1 *	Select which ENx pin controls BUCK2 if EN_PIN_CTRL2 = 1: 0 - EN1 pin 1 - EN2 pin.			
4	EN_ROOF_FLOOR2	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL2 = 1: 0 - Enable/Disable (1/0) control. 1 - Roof/Floor (1/0) control.			
3	EN_RDIS2	R/W	1	Enable output discharge resistor when BUCK2 is disabled: 0 - Discharge resistor is disabled. 1 - Discharge resistor is enabled.			
2	Reserved	R/W	0				
1	BUCK2_FPWM	R/W	0 *	Forces the BUCK2 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.			
0	Reserved	R/W	0				

### 7.6.1.7 BUCK2\_CTRL2

Address: 0x07

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM2[2:0]			SLEW_RATE2[2:0]		
Bits	Field	Type	Default	Description			
7:6	Reserved	R/W	00				
5:3	ILIM2[2:0]	R/W	0x6 *	Sets the switch current limit of BUCK2. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A			
2:0	SLEW_RATE2[2:0]	R/W	0x4 *	Sets the output voltage slew rate for BUCK2 converter core (rising and falling edges): 0x0 - 30 mV/μs 0x1 - 15 mV/μs 0x2 - 10 mV/μs 0x3 - 7.5 mV/μs 0x4 - 3.8 mV/μs 0x5 - 1.9 mV/μs 0x6 - 0.94 mV/μs 0x7 - 0.4 mV/μs			

### 7.6.1.8 BUCK3\_CTRL1

Address: 0x08

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK3	EN_PIN_CTRL3	EN_PIN_SELECT3	EN_ROOF_FLOOR3	EN_RDIS3	Reserved	BUCK3_FPWM	Reserved
Bits	Field	Type	Default	Description			
7	EN_BUCK3	R/W	1 *	Enable BUCK3 converter core: 0 - BUCK3 converter core is disabled. 1 - BUCK3 converter core is enabled.			
6	EN_PIN_CTRL3	R/W	1 *	Enable EN1/2 pin control for BUCK3: 0 - only EN_BUCK3 bit controls BUCK3 1 - EN_BUCK3 bit AND EN1/2 pin control BUCK3.			
5	EN_PIN_SELECT3	R/W	1 *	Select which ENx pin controls BUCK3 if EN_PIN_CTRL3 = 1: 0 - EN1 pin 1 - EN2 pin.			
4	EN_ROOF_FLOOR3	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL3 = 1: 0 - Enable/Disable (1/0) control 1 - Roof/Floor (1/0) control.			
3	EN_RDIS3	R/W	1	Enable output discharge resistor when BUCK3 is disabled: 0 - Discharge resistor is disabled. 1 - Discharge resistor is enabled.			
2	Reserved	R/W	0				
1	BUCK3_FPWM	R/W	0 *	Forces the BUCK3 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.			
0	Reserved	R/W	0				

### 7.6.1.9 BUCK3\_CTRL2

Address: 0x09

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM3[2:0]			SLEW_RATE3[2:0]		
Bits	Field	Type	Default	Description			
7:6	Reserved	R/W	00				
5:3	ILIM3[2:0]	R/W	0x6 *	Sets the switch current limit of BUCK3. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A			
2:0	SLEW_RATE3[2:0]	R/W	0x4 *	Sets the output voltage slew rate for BUCK3 converter core (rising and falling edges): 0x0 - 30 mV/μs 0x1 - 15 mV/μs 0x2 - 10 mV/μs 0x3 - 7.5 mV/μs 0x4 - 3.8 mV/μs 0x5 - 1.9 mV/μs 0x6 - 0.94 mV/μs 0x7 - 0.4 mV/μs			

### 7.6.1.10 BUCK0\_VOUT

Address: 0x0A

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_VSET[7:0]							
Bits	Field	Type	Default	Description			
7:0	BUCK0_VSET[7:0]	R/W	0x37 *	Sets the output voltage of BUCK0 converter core (Default 900 mV) <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5 V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V			



### 7.6.1.11 BUCK0\_FLOOR\_VOUT

Address: 0x0B

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_FLOOR_VSET[7:0]							
Bits	Field	Type	Default	Description			
7:0	BUCK0_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK0 converter core when Floor state is used: <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5 V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V			

### 7.6.1.12 BUCK1\_VOUT

Address: 0x0C

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_VSET[7:0]							
Bits	Field	Type	Default	Description			
7:0	BUCK1_VSET[7:0]	R/W	0x37 *	Sets the output voltage of BUCK1 converter core (Default 1200 mV): <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5 V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V			

### 7.6.1.13 BUCK1\_FLOOR\_VOUT

Address: 0x0D

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_FLOOR_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK1_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK1 converter core when the Floor state is used: <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V

#### 7.6.1.14 BUCK2\_VOUT

Address: 0x0E

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----

BUCK2_VSET[7:0]							
-----------------	--	--	--	--	--	--	--

Bits	Field	Type	Default	Description
7:0	BUCK2_VSET[7:0]	R/W	0x37 *	Sets the output voltage of BUCK2 converter core (Default 1800 mV): <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V

#### 7.6.1.15 BUCK2\_FLOOR\_VOUT

Address: 0x0F

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----

BUCK2_FLOOR_VSET[7:0]							
-----------------------	--	--	--	--	--	--	--

Bits	Field	Type	Default	Description
7:0	BUCK2_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK2 converter core when the Floor state is used: <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5 V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V

### 7.6.1.16 BUCK3\_VOUT

Address: 0x10

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_VSET[7:0]							
Bits	Field	Type	Default	Description			
7:0	BUCK3_VSET[7:0]	R/W	0x37 *	Sets the output voltage of BUCK3 converter core (Default 2700 mV) <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5 V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V			

### 7.6.1.17 BUCK3\_FLOOR\_VOUT

Address: 0x11

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_FLOOR_VSET[7:0]							
Bits	Field	Type	Default	Description			
7:0	BUCK3_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK3 converter core when Floor state is used: <b>0.5 V - 0.73 V, 10 mV steps</b> 0x00 - 0.5 V ... 0x17 - 0.73 V <b>0.73 V - 1.4 V, 5 mV steps</b> 0x18 - 0.735 V ... 0x9D - 1.4 V <b>1.4 V - 3.36 V, 20 mV steps</b> 0x9E - 1.42 V ... 0xFF - 3.36 V			

### 7.6.1.18 BUCK0\_DELAY

Address: 0x12

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_SHUTDOWN_DELAY[3:0]				BUCK0_STARTUP_DELAY[3:0]			
Bits	Field	Type	Default	Description			
7:4	BUCK0_SHUTDOWN_DELAY[3:0]	R/W	0x0 *	Shutdown delay of BUCK0 from falling edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms			

Bits	Field	Type	Default	Description
3:0	BUCK0_STARTUP_DELAY[3:0]	R/W	0x0 *	Startup delay of BUCK0 from rising edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

### 7.6.1.19 BUCK1\_DELAY

Address: 0x13

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_SHUTDOWN_DELAY[3:0]				BUCK1_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK1_SHUTDOWN_DELAY[3:0]	R/W	0x0 *	Shutdown delay of BUCK1 from falling edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms
3:0	BUCK1_STARTUP_DELAY[3:0]	R/W	0x0 *	Startup delay of BUCK1 from rising edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

### 7.6.1.20 BUCK2\_DELAY

Address: 0x14

D7	D6	D5	D4	D3	D2	D1	D0
BUCK2_SHUTDOWN_DELAY[3:0]				BUCK2_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK2_SHUTDOWN_DELAY[3:0]	R/W	0x0 *	Shutdown delay of BUCK2 from falling edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms
3:0	BUCK2_STARTUP_DELAY[3:0]	R/W	0x0 *	Start-up delay of BUCK2 from rising edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

### 7.6.1.21 BUCK3\_DELAY

Address: 0x15

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_SHUTDOWN_DELAY[3:0]				BUCK3_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK3_SHUTDOWN_DELAY[3:0]	R/W	0x0 *	Shutdown delay of BUCK3 from falling edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

Bits	Field	Type	Default	Description
3:0	BUCK3_STARTUP_DELAY[3:0]	R/W	0x0 *	Start-up delay of BUCK3 from rising edge of the ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

### 7.6.1.22 RESET

Address: 0x16

D7	D6	D5	D4	D3	D2	D1	D0
Reserved							SW_RESET

Bits	Field	Type	Default	Description
7:1	Reserved	R/W	0000 000	
0	SW_RESET	R/W	0	Software commanded reset. When written to 1, the registers are reset to default values, OTP memory is read, and the I <sup>2</sup> C interface is reset. The bit is automatically cleared.

### 7.6.1.23 CONFIG

Address: 0x17

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				TDIE_WARN_LEVEL	EN2_PD	EN1_PD	EN_SPREAD_SPEC

Bits	Field	Type	Default	Description
7:4	Reserved	R/W	0000	
3	TDIE_WARN_LEVEL	R/W	0	Thermal warning threshold level. 0 - 125°C 1 - 105°C
2	EN2_PD	R/W	1	Selects the pulldown resistor on the EN2 input pin. 0 - Pulldown resistor is disabled. 1 - Pulldown resistor is enabled.
1	EN1_PD	R/W	1	Selects the pull down resistor on the EN1 input pin. 0 - Pulldown resistor is disabled. 1 - Pulldown resistor is enabled.
0	EN_SPREAD_SPEC	R/W	0	Enable spread-spectrum feature: 0 - Disabled 1 - Enabled

### 7.6.1.24 INT\_TOP

Address: 0x18

D7	D6	D5	D4	D3	D2	D1	D0
INT_BUCK3	INT_BUCK2	INT_BUCK1	INT_BUCK0	TDIE_SD	TDIE_WARN	RESET_REG	I_LOAD_READY

Bits	Field	Type	Default	Description
7	INT_BUCK3	R	0	Interrupt indicating that output BUCK3 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK3 register. This bit is cleared automatically when INT_BUCK3 register is cleared to 0x00.
6	INT_BUCK2	R	0	Interrupt indicating that output BUCK2 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK2 register. This bit is cleared automatically when INT_BUCK2 register is cleared to 0x00.
5	INT_BUCK1	R	0	Interrupt indicating that output BUCK1 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK1 register. This bit is cleared automatically when INT_BUCK1 register is cleared to 0x00.
4	INT_BUCK0	R	0	Interrupt indicating that output BUCK0 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK0 register. This bit is cleared automatically when INT_BUCK0 register is cleared to 0x00.
3	TDIE_SD	R/W	0	Latched status bit indicating that the die junction temperature has exceeded the thermal shutdown level. The converter cores have been disabled if they were enabled. The converter cores cannot be enabled if this bit is active. The actual status of the thermal warning is indicated by the TOP_STAT.TDIE_SD_STAT bit. Write 1 to clear interrupt.
2	TDIE_WARN	R/W	0	Latched status bit indicating that the die junction temperature has exceeded the thermal warning level. The actual status of the thermal warning is indicated by TOP_STAT.TDIE_WARN_STAT bit. Write 1 to clear interrupt.
1	RESET_REG	R/W	0	Latched status bit indicating that either startup (NRST rising edge) has done, VANA supply voltage has been below undervoltage threshold level or the host has requested a reset (RESET.SW_RESET). The converter cores have been disabled, and registers are reset to default values and the normal startup procedure is done. Write 1 to clear interrupt.

Bits	Field	Type	Default	Description
0	I_LOAD_READY	R/W	0	Latched status bit indicating that the load current measurement result is available in I_LOAD_1 and I_LOAD_2 registers. Write 1 to clear interrupt.

### 7.6.1.25 INT\_BUCK\_0\_1

Address: 0x19

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK1_PG_INT	BUCK1_SC_INT	BUCK1_ILIM_INT	Reserved	BUCK0_PG_INT	BUCK0_SC_INT	BUCK0_ILIM_INT

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK1_PG_INT	R/W	0	Latched status bit indicating that BUCK1 output voltage has reached power-good threshold level. Write 1 to clear.
5	BUCK1_SC_INT	R/W	0	Latched status bit indicating that the BUCK1 output voltage has fallen below 0.35-V level during operation or BUCK1 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
4	BUCK1_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.
3	Reserved	R/W	0	
2	BUCK0_PG_INT	R/W	0	Latched status bit indicating that BUCK0 output voltage has reached powergood threshold level. Write 1 to clear.
1	BUCK0_SC_INT	R/W	0	Latched status bit indicating that the BUCK0 output voltage has fallen below 0.35-V level during operation or BUCK0 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
0	BUCK0_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.

### 7.6.1.26 INT\_BUCK\_2\_3

Address: 0x1A

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK3_PG_INT	BUCK3_SC_INT	BUCK3_ILIM_INT	Reserved	BUCK2_PG_INT	BUCK2_SC_INT	BUCK2_ILIM_INT

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK3_PG_INT	R/W	0	Latched status bit indicating that BUCK3 output voltage has reached power-good threshold level. Write 1 to clear.
5	BUCK3_SC_INT	R/W	0	Latched status bit indicating that the BUCK3 output voltage has fallen below 0.35-V level during operation or BUCK3 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
4	BUCK3_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.
3	Reserved	R/W	0	
2	BUCK2_PG_INT	R/W	0	Latched status bit indicating that BUCK2 output voltage has reached powergood threshold level. Write 1 to clear.
1	BUCK2_SC_INT	R/W	0	Latched status bit indicating that the BUCK2 output voltage has fallen below 0.35 V level during operation or BUCK2 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
0	BUCK2_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.



### 7.6.1.27 TOP\_STAT

Address: 0x1B

D7	D6	D5	D4	D3	D2	D1	D0
Reserved			TDIE_SD_STAT	TDIE_WARN_STAT	Reserved		
Bits	Field	Type	Default	Description			
7:4	Reserved	R	0000				
3	TDIE_SD_STAT	R	0	Status bit indicating the status of thermal shutdown: 0 - Die temperature below the thermal shutdown level. 1 - Die temperature above the thermal shutdown level.			
2	TDIE_WARN_STAT	R	0	Status bit indicating the status of thermal warning: 0 - Die temperature below the thermal warning level. 1 - Die temperature above the thermal warning level.			
1:0	Reserved	R	00				

### 7.6.1.28 BUCK\_0\_1\_STAT

Address: 0x1C

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_STAT	BUCK1_PG_STAT	Reserved	BUCK1_ILIM_STAT	BUCK0_STAT	BUCK0_PG_STAT	Reserved	BUCK0_ILIM_STAT
Bits	Field	Type	Default	Description			
7	BUCK1_STAT	R	0	Status bit indicating the enable or disable status of BUCK1: 0 - BUCK1 converter core is disabled. 1 - BUCK1 converter core is enabled.			
6	BUCK1_PG_STAT	R	0	Status bit indicating BUCK1 output voltage validity (raw status): 0 - BUCK1 output is above power-good threshold level 1 - BUCK1 output is below power-good threshold level.			
5	Reserved	R	0				
4	BUCK1_ILIM_STAT	R	0	Status bit indicating BUCK1 current limit status (raw status): 0 - BUCK1 output current is below current limit level. 1 - BUCK1 output current limit is active.			
3	BUCK0_STAT	R	0	Status bit indicating the enable or disable status of BUCK0: 0 - BUCK0 converter core is disabled. 1 - BUCK0 converter core is enabled.			
2	BUCK0_PG_STAT	R	0	Status bit indicating BUCK0 output voltage validity (raw status): 0 - BUCK0 output is above the power-good threshold level. 1 - BUCK0 output is below the power-good threshold level.			
1	Reserved	R	0				
0	BUCK0_ILIM_STAT	R	0	Status bit indicating BUCK0 current limit status (raw status): 0 - BUCK0 output current is below the current limit level. 1 - BUCK0 output current limit is active.			

### 7.6.1.29 BUCK\_2\_3\_STAT

Address: 0x1D

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_STAT	BUCK3_PG_STAT	Reserved	BUCK3_ILIM_STAT	BUCK2_STAT	BUCK2_PG_STAT	Reserved	BUCK2_ILIM_STAT
Bits	Field	Type	Default	Description			
7	BUCK3_STAT	R	0	Status bit indicating the enable or disable status of BUCK3: 0 - BUCK3 converter core is disabled. 1 - BUCK3 converter core is enabled.			
6	BUCK3_PG_STAT	R	0	Status bit indicating BUCK3 output voltage validity (raw status): 0 - BUCK3 output is above power-good threshold level. 1 - BUCK3 output is below power-good threshold level.			
5	Reserved	R	0				
4	BUCK3_ILIM_STAT	R	0	Status bit indicating BUCK3 current limit status (raw status): 0 - BUCK3 output current is below current limit level. 1 - BUCK3 output current limit is active.			
3	BUCK2_STAT	R	0	Status bit indicating the enable or disable status of BUCK2: 0 - BUCK2 converter core is disabled. 1 - BUCK2 converter core is enabled.			
2	BUCK2_PG_STAT	R	0	Status bit indicating BUCK2 output voltage validity (raw status): 0 - BUCK2 output is above power-good threshold level. 1 - BUCK2 output is below power-good threshold level.			
1	Reserved	R	0				
0	BUCK2_ILIM_STAT	R	0	Status bit indicating BUCK2 current limit status (raw status): 0 - BUCK2 output current is below current limit level. 1 - BUCK2 output current limit is active.			

### 7.6.1.30 TOP\_MASK

Address: 0x1E

D7	D6	D5	D4	D3	D2	D1	D0
Reserved					TDIE_WARN_MASK	RESET_REG_MASK	I_LOAD_READY_MASK
Bits	Field	Type	Default	Description			
7:3	Reserved	R/W	0000 0				
2	TDIE_WARN_MASK	R/W	0 *	Masking for thermal warning interrupt INT_TOP.TDIE_WARN: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect TOP_STAT.TDIE_WARN_STAT status bit.			
1	RESET_REG_MASK	R/W	1 *	Masking for register reset interrupt INT_TOP.RESET_REG: 0 - Interrupt is generated. 1 - Interrupt is not generated.			
0	I_LOAD_READY_MASK	R/W	1 *	Masking for load current measurement ready interrupt INT_TOP.I_LOAD_READY: 0 - Interrupt is generated. 1 - Interrupt is not generated.			

### 7.6.1.31 BUCK\_0\_1\_MASK

Address: 0x1F

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK1_PG_MASK	Reserved	BUCK1_ILIM_MASK	Reserved	BUCK0_PG_MASK	Reserved	BUCK0_ILIM_MASK

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK1_PG_MASK	R/W	1 *	Masking for BUCK1 power-good interrupt INT_BUCK_0_1.BUCK1_PG_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_0_1_STAT.BUCK1_PG_STAT status bit.
5	Reserved	R	0	
4	BUCK1_ILIM_MASK	R/W	1 *	Masking for BUCK1 current limit detection interrupt INT_BUCK_0_1.BUCK1_ILIM_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_0_1_STAT.BUCK1_ILIM_STAT status bit.
3	Reserved	R/W	0	
2	BUCK0_PG_MASK	R/W	1 *	Masking for BUCK0 power-good interrupt INT_BUCK_0_1.BUCK0_PG_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_0_1_STAT.BUCK1_PG_STAT status bit.
1	Reserved	R	0	
0	BUCK0_ILIM_MASK	R/W	1 *	Masking for BUCK0 current limit detection interrupt INT_BUCK_0_1.BUCK0_ILIM_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_0_1_STAT.BUCK1_ILIM_STAT status bit.

### 7.6.1.32 BUCK\_2\_3\_MASK

Address: 0x20

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK3_PG_MASK	Reserved	BUCK3_ILIM_MASK	Reserved	BUCK2_PG_MASK	Reserved	BUCK2_ILIM_MASK

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK3_PG_MASK	R/W	1 *	Masking for BUCK3 power-good interrupt INT_BUCK_2_3.BUCK3_PG_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_2_3_STAT.BUCK3_PG_STAT status bit.
5	Reserved	R	0	
4	BUCK3_ILIM_MASK	R/W	1 *	Masking for BUCK3 current limit detection interrupt INT_BUCK_2_3.BUCK3_ILIM_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_2_3_STAT.BUCK3_ILIM_STAT status bit.
3	Reserved	R/W	0	
2	BUCK2_PG_MASK	R/W	1 *	Masking for BUCK2 power-good interrupt INT_BUCK_2_3.BUCK2_PG_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_2_3_STAT.BUCK1_PG_STAT status bit.
1	Reserved	R	0	

Bits	Field	Type	Default	Description
0	BUCK2_ILIM_MASK	R/W	1 *	Masking for BUCK2 current limit detection interrupt INT_BUCK_2_3.BUCK2_ILIM_INT: 0 - Interrupt is generated. 1 - Interrupt is not generated. This bit does not affect the BUCK_2_3_STAT.BUCK1_ILIM_STAT status bit.

### 7.6.1.33 SEL\_I\_LOAD

Address: 0x21

D7	D6	D5	D4	D3	D2	D1	D0
Reserved						LOAD_CURRENT_BUCK_SELECT[1:0]	
Bits	Field	Type	Default	Description			
7:2	Reserved	R/W	00 0000				
1:0	LOAD_CURRENT_BUCK_SELECT [1:0]	R/W	0x0	Start the current measurement on the selected converter core: 0x0 - BUCK0 0x1 - BUCK1 0x2 - BUCK2 0x3 - BUCK3 The measurement is started when this register is written.			

### 7.6.1.34 I\_LOAD\_2

Address: 0x22

D7	D6	D5	D4	D3	D2	D1	D0
Reserved						BUCK_LOAD_CURRENT[9:8]	
Bits	Field	Type	Default	Description			
7:2	Reserved	R	00 0000				
1:0	BUCK_LOAD_CURRENT[9:8]	R	0x0	This register describes 2 MSB bits of the average load current on the selected converter core with a resolution of 20 mA per LSB and a maximum 20 A current.			

### 7.6.1.35 I\_LOAD\_1

Address: 0x23

D7	D6	D5	D4	D3	D2	D1	D0
BUCK_LOAD_CURRENT[7:0]							
Bits	Field	Type	Default	Description			
7:0	BUCK_LOAD_CURRENT[7:0]	R	0x0	This register describes 8 LSB bits of the average load current on selected converter core with a resolution of 20 mA per LSB and maximum 20-A current.			

## 8 Application and Implementation

### 注

以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくこととなります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

### 8.1 Application Information

The LP8758-EA is designed for applications powered from a 2.5-V to 5.5-V input supply that require multiple power rails. The device provides four step-down converters. All the step-down converters support dynamic voltage scaling through I<sup>2</sup>C interface to provide optimum power savings. The power sequencing of the four output voltage rails is programmable.

### 8.2 Typical Application

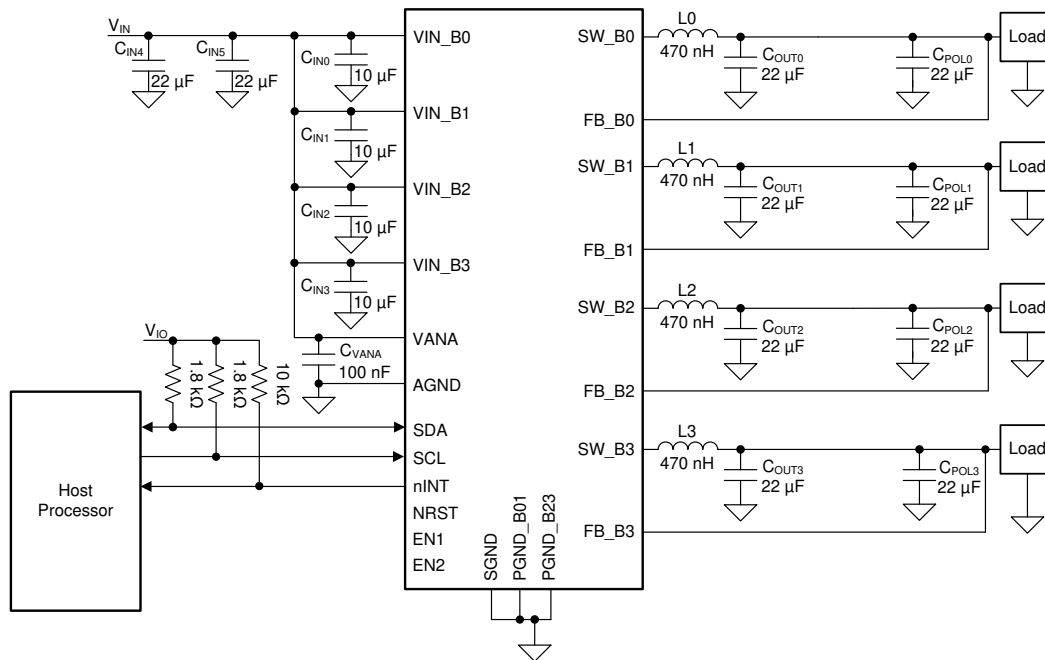


図 8-1. LP8758-EA Typical Application Circuit

#### 8.2.1 Design Requirements

表 8-1. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage	3.3 V
Output voltages	1000 mV, 1200 mV, 1800 mV, and 2500 mV
Converter operation mode	Auto mode (PWM-PFM)
Maximum load currents	1.5 A, 2.25 A, 3 A, and 3 A
Inductor current limits	2.5 A, 3.5 A, 4.5 A, and 4.5 A

#### 8.2.2 Detailed Design Procedure

The performance of the LP8758-EA device depends greatly on the care taken in designing the printed circuit board (PCB). The use of low-inductance and low serial-resistance ceramic capacitors is strongly recommended, while proper grounding is crucial. Attention must be given to decoupling the power supplies. Decoupling capacitors must be connected close to the device and between the power and ground pins to support high peak

currents being drawn from system power rail during turnon of the switching MOSFETs. Keep input and output traces as short as possible, because trace inductance, resistance, and capacitance can easily become the performance limiting items. The separate power pins VIN\_Bx are not connected together internally. The VIN\_Bx power connections must be connected together outside the package using power plane construction.

### 8.2.2.1 Application Components

#### 8.2.2.1.1 Inductor Selection

DC bias current characteristics of inductors must be considered. Different manufacturers follow different saturation current rating specifications, so attention must be given to details. DC bias curves should be requested from manufacturers as part of the inductor selection process. Minimum effective value of inductance to ensure good performance is 0.33  $\mu\text{H}$  at maximum load current over the operating temperature range of the inductor. The DC resistance of the inductor must be less than 0.05  $\Omega$  for good efficiency at high-current condition. The inductor AC loss (resistance) also affects conversion efficiency. Higher Q factor at switching frequency usually gives better efficiency at light load to middle load. See [表 8-2](#). Shielded inductors are preferred as they radiate less noise.

**表 8-2. Recommended Inductors**

MANUFACTURER	PART NUMBER	VALUE ( $\mu\text{H}$ )	DIMENSIONS L $\times$ W $\times$ H (mm)	DCR (m $\Omega$ )
MURATA	DFE201610E-R47M=P2	0.47	2 $\times$ 1.6 $\times$ 1	26 (typical), 32 (maximum)
TDK	VLS252010HBX-R47M	0.47	2.5 $\times$ 2 $\times$ 1	29 (typical), 35 (maximum)
TDK	TFM2016GHM-0R47M	0.47	2 $\times$ 1.6 $\times$ 1	46 (maximum)
TOKO	DFE322512C R47	0.47	3.2 $\times$ 2.5 $\times$ 1.2	21 (typical), 31 (maximum)

#### 8.2.2.1.2 Input Capacitor Selection

A ceramic input capacitor of 10  $\mu\text{F}$ , 6.3 V is sufficient for most applications. Place the power input capacitor as close as possible to the VIN\_Bx pin and PGND\_Bx pin of the device. A larger value or higher voltage rating may be used to improve input voltage filtering. Use X7R or X5R types; *do not use Y5V or F*. DC bias characteristics of ceramic capacitors must be considered when selecting case sizes like 0402. Minimum effective input capacitance to ensure good performance is 1.9  $\mu\text{F}$  per buck input at maximum input voltage DC bias including tolerances and over ambient temp range, assuming that there are at least 22  $\mu\text{F}$  of additional capacitance common for all the power input pins on the system power rail. See [表 8-3](#).

The input filter capacitor supplies current to the high-side FET switch in the first half of each cycle and reduces voltage ripple imposed on the input power source. A ceramic capacitor's low equivalent series resistance (ESR) provides the best noise filtering of the input voltage spikes due to this rapidly changing current. Select an input filter capacitor with sufficient ripple current rating.

The VANA input is used to supply analog and digital circuits in the device. See recommended components from [表 8-4](#) for VANA input supply filtering.

**表 8-3. Recommended Power Input Capacitors (X5R Dielectric)**

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L $\times$ W $\times$ H (mm)	VOLTAGE RATING (V)
Murata	GRM188R60J106ME47	10 $\mu\text{F}$ (20%)	0603	1.6 $\times$ 0.8 $\times$ 0.8	6.3

**表 8-4. Recommended VANA Supply Filtering Components**

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L $\times$ W $\times$ H (mm)	VOLTAGE RATING (V)
Samsung	CL03A104KP3NNNC	100 nF (10%)	0201	0.6 $\times$ 0.3 $\times$ 0.3	10
Murata	GRM033R61A104KE84	100 nF (10%)	0201	0.6 $\times$ 0.3 $\times$ 0.3	6.3

#### 8.2.2.1.3 Output Capacitor Selection

Use ceramic capacitors, X7R or X5R types; do not use Y5V or F. DC bias voltage characteristics of ceramic capacitors must be considered. DC bias characteristics vary from manufacturer to manufacturer, and DC bias curves should be requested from them as part of the capacitor selection process. The output filter capacitor smooths out current flow from the inductor to the load, helps maintain a steady output voltage during transient

load changes and reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and sufficiently low ESR and ESL to perform these functions. The minimum effective output capacitance to ensure good performance is 10  $\mu\text{F}$  per output voltage rail at the output voltage DC bias, including tolerances and over ambient temperature range.

The output voltage ripple is caused by the charging and discharging of the output capacitor and also due to its  $R_{\text{ESR}}$ . The  $R_{\text{ESR}}$  is frequency dependent (as well as temperature dependent); make sure the value used for selection process is at the switching frequency of the part. See [表 8-5](#).

A higher output capacitance improves the load step behavior and reduces the output voltage ripple as well as decreases the PFM switching frequency. For most applications one 22- $\mu\text{F}$  0603 capacitor for  $C_{\text{OUT}}$  per voltage rail is suitable. A point-of-load (POL) capacitance  $C_{\text{POL}}$  can be added as shown in [图 8-1](#). Although the loop compensation of the converter can be programmed to adapt to virtually several hundreds of microfarads  $C_{\text{OUT}}$ , it is preferable for  $C_{\text{OUT}}$  to be < 50  $\mu\text{F}$ . Choosing higher than that is not necessarily of any benefit. Note: the output capacitor may be the limiting factor in the output voltage ramp, especially for very large (> 100  $\mu\text{F}$ ) output capacitors. For large output capacitors, the output voltage might be slower than the programmed ramp rate at voltage transitions, because of the higher energy stored on the output capacitance. Also at start-up, the time required to charge the output capacitor to target value might be longer. At shutdown, if the output capacitor is discharged by the internal discharge resistor, more time is required to settle  $V_{\text{OUT}}$  down as a consequence of the increased time constant.

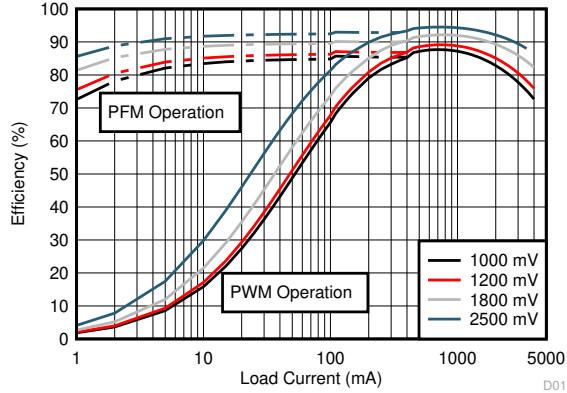
**表 8-5. Recommended Output Capacitors (X5R Dielectric)**

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L × W × H (mm)	VOLTAGE RATING (V)
Samsung	CL10A226MP8NUNE	22 $\mu\text{F}$ (20%)	0603	1.6 × 0.8 × 0.8	10
Murata	GRM188R60J226MEA0	22 $\mu\text{F}$ (20%)	0603	1.6 × 0.8 × 0.8	6.3



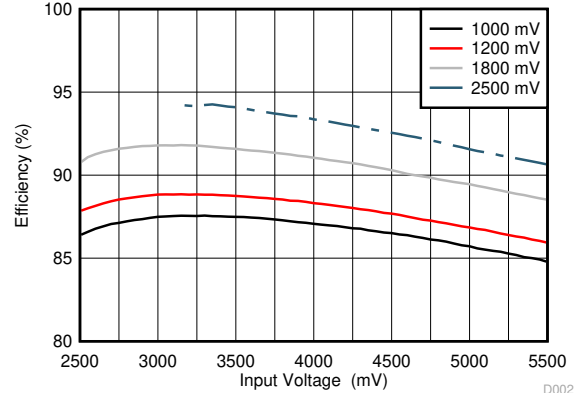
### 8.2.3 Application Curves

Measurements are done using typical application set up with connections shown in [8-1](#). Graphs may not reflect the OTP default settings. Unless otherwise specified:  $V_{IN} = 3.7\text{ V}$ ,  $V_{(NRST)} = 1.8\text{ V}$ ,  $T_A = 25\text{ }^\circ\text{C}$ ,  $f_{SW} = 3\text{ MHz}$ ,  $L = 470\text{ nH}$  (TDK VLS252010HBX-R47M),  $I_{LIM\ FWD}$  set to maximum 5 A.



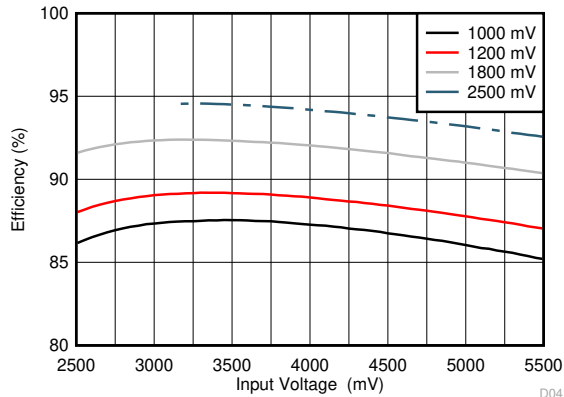
$V_{IN} = 3.7\text{ V}$   
 $V_{OUT}$  settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

**8-2. Efficiency vs Load Current**



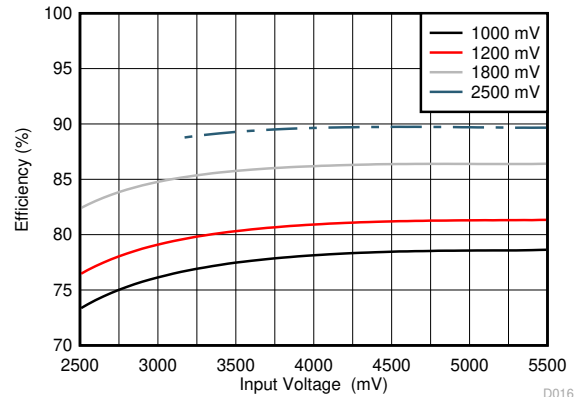
Load = 100 mA  
 $V_{OUT}$  settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

**8-3. Efficiency vs Input Voltage in PFM Mode**



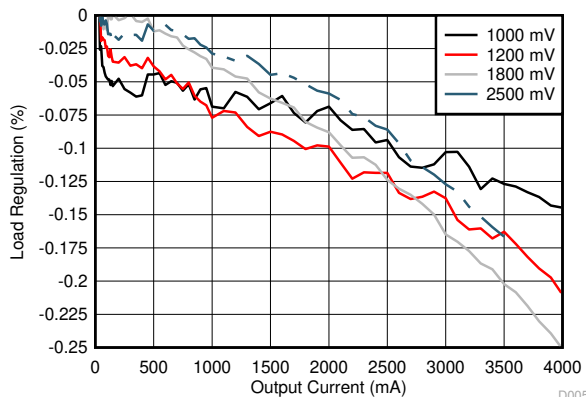
Load = 1A  
 $V_{OUT}$  settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

**8-4. Efficiency vs Input Voltage in PWM Mode**



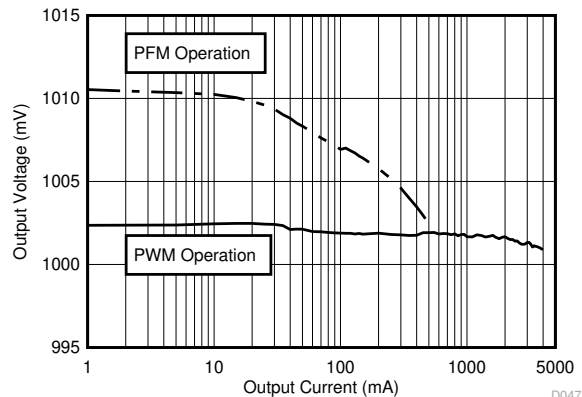
Load = 3A  
 $V_{OUT}$  settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

**8-5. Efficiency vs Input Voltage in PWM Mode**



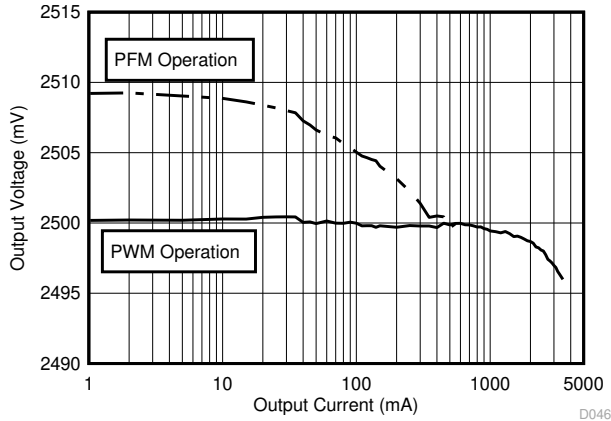
Change in Output Voltage from Zero Load (%)  
 $V_{OUT}$  settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

**8-6. DC Load Regulation in PWM mode**



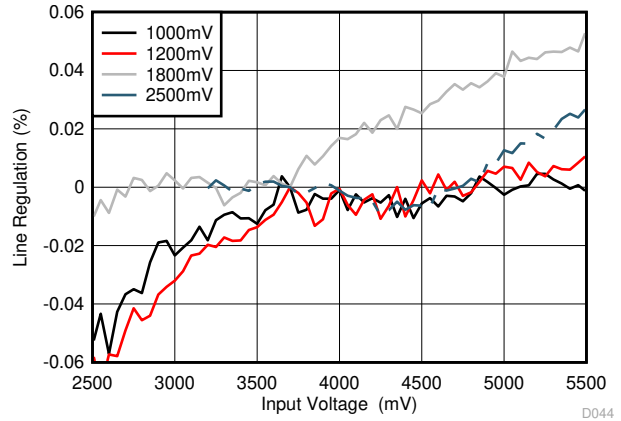
$V_{OUT}$  setting = 1000 mV

**8-7. Output Voltage vs Load Current in PWM-PFM Mode**



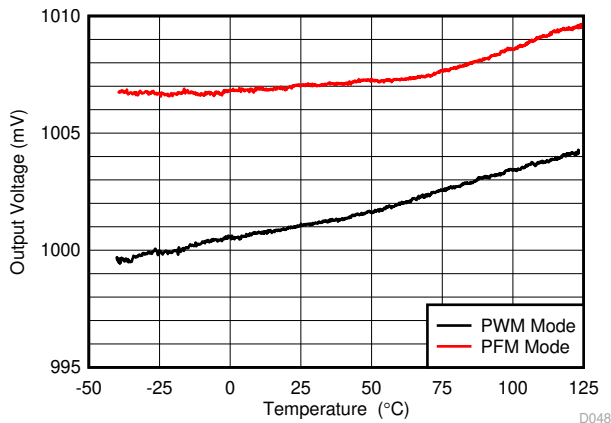
$V_{OUT}$  setting = 2500 mV

**8-8. Output Voltage vs Load Current in PWM-PFM Mode**



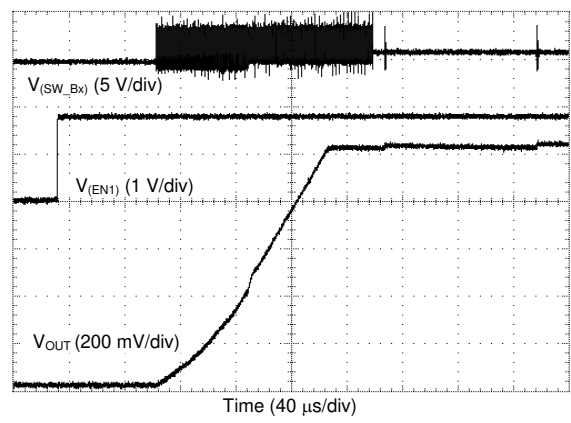
Change in Output Voltage from  $V_{IN} = 3.7$  V (%) Load = 1 A  
 $V_{OUT}$  settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

**8-9. DC Line Regulation in PWM Mode**



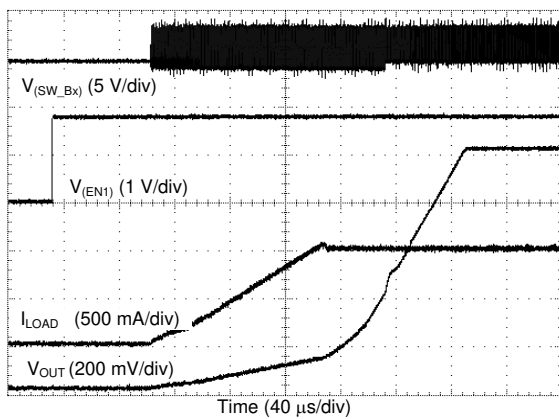
$V_{OUT}$  setting = 1000 mV  
 Load = 1 A (PWM Mode) and 100 mA (PFM Mode)

**8-10. Output Voltage vs Temperature**



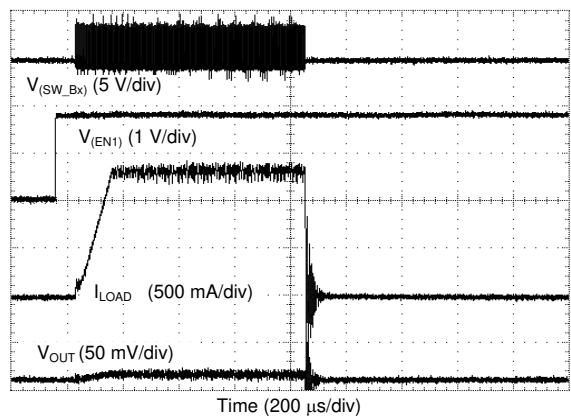
Load = 0 A

**8-11. Start-up with EN1**

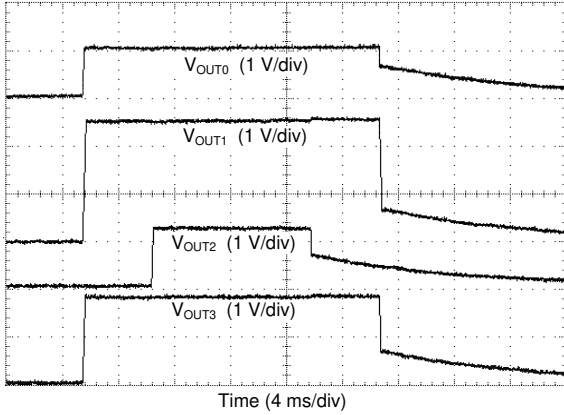


Load = 1 A

**8-12. Start-up with EN1**

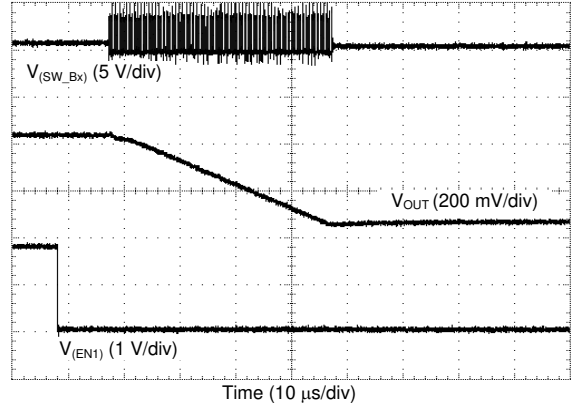


**8-13. Start-up With Short on Output**



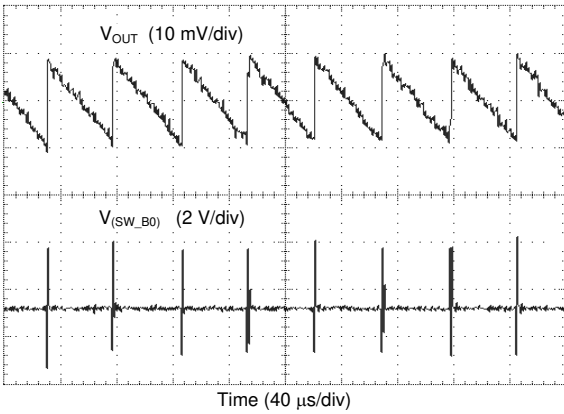
Load = 0 A      Enable and disable delays = default  
 V<sub>OUT</sub> settings = default

**8-14. V<sub>OUT0,1,2,3</sub>: Start-up and Shutdown with Default Register Settings, triggered by EN1.**



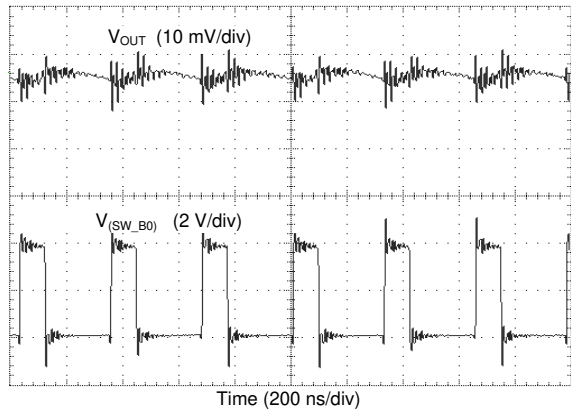
Load = 0 A

**8-15. Shutdown with EN1**



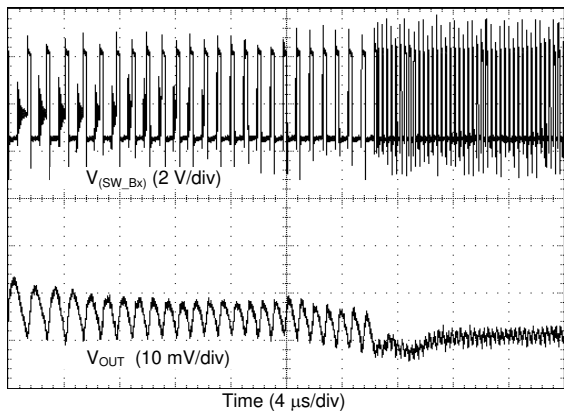
Load = 10 mA

**8-16. Output Voltage Ripple, PFM Mode**

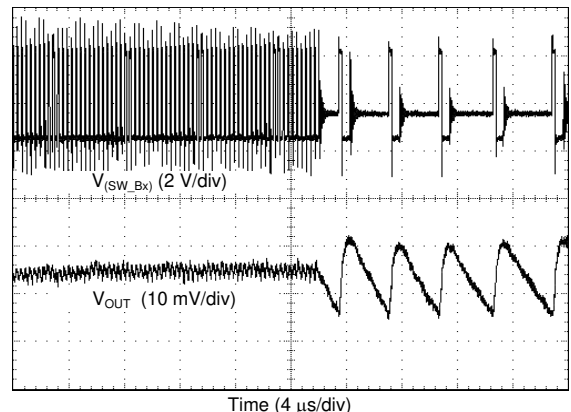


Load = 200 mA

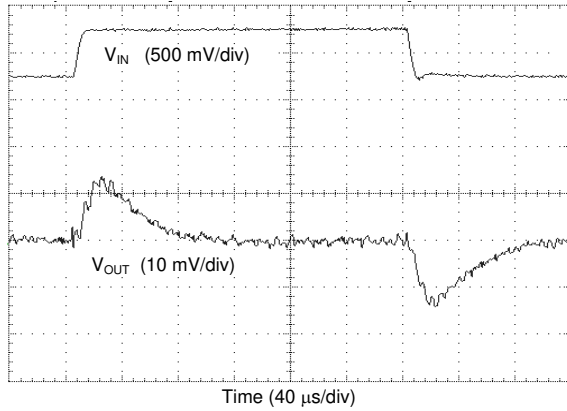
**8-17. Output Voltage Ripple, Forced PWM Mode**



**8-18. Transient from PFM-to-PWM Mode**

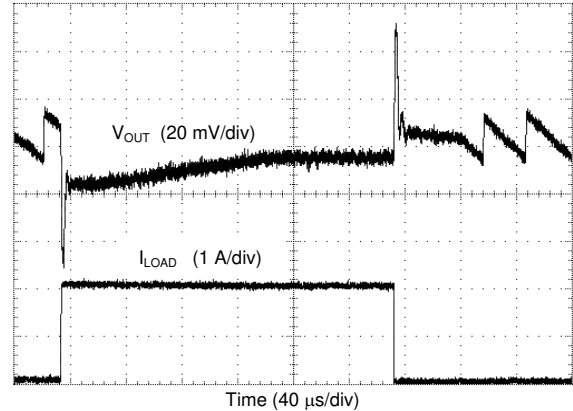


**8-19. Transient from PWM-to-PFM Mode**



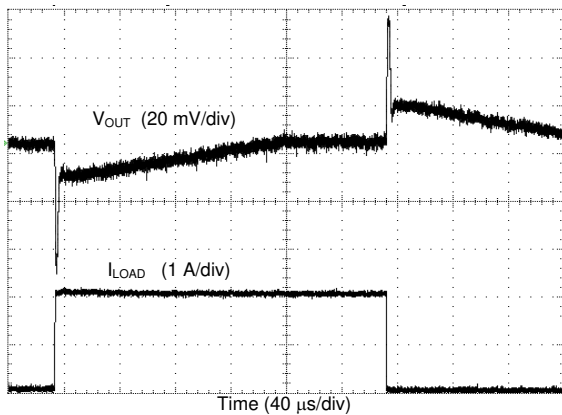
Load = 4 A  $V_{OUT} = 1000$  mV  
 $V_{IN}$  stepping 3.3 V  $\leftrightarrow$  3.8 V,  $T_R = T_F = 10$   $\mu$ s

**8-20. Transient Line Response**



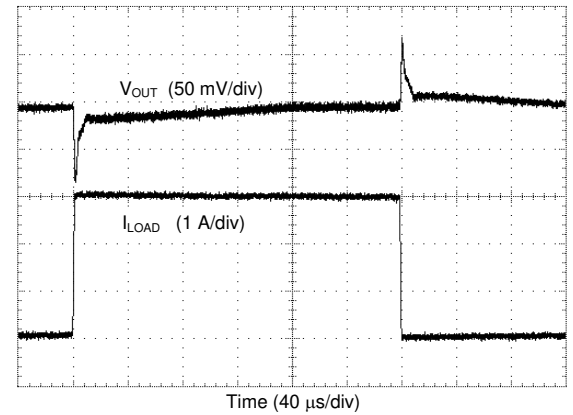
Load = 0 A  $\rightarrow$  2 A  $\rightarrow$  0 A  $T_R = T_F = 400$  ns  $V_{OUT} = 1$  V

**8-21. Transient Load Step Response, AUTO Mode**



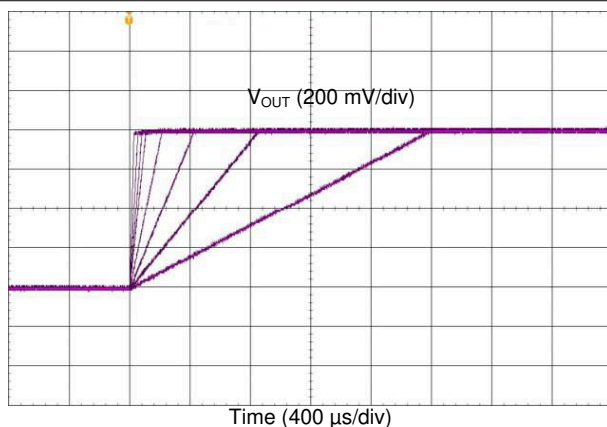
Load = 0 A  $\rightarrow$  2 A  $\rightarrow$  0 A  $T_R = T_F = 400$  ns  $V_{OUT} = 1$  V

**8-22. Transient Load Step Response, Forced PWM Mode**

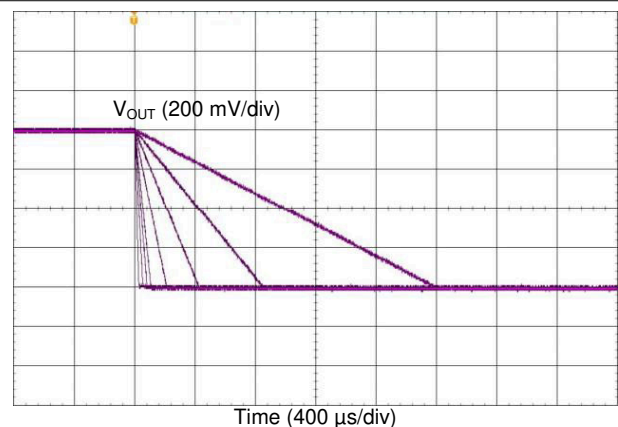


Load = 1A  $\rightarrow$  4 A  $\rightarrow$  1A  $T_R = T_F = 1$   $\mu$ s  $V_{OUT} = 1$  V

**8-23. Transient Load Step Response, Forced PWM Mode**



**8-24.  $V_{OUT}$  Transition From 0.6 V to 1.4 V With Different Slew Rate Settings**



**8-25.  $V_{OUT}$  Transition From 1.4 V to 0.6 V With Different Slew Rate Settings**

## 9 Power Supply Recommendations

The device is designed to operate from an input voltage supply range between 2.5 V and 5.5 V. This input supply must be well-regulated and able to withstand maximum input current and maintain stable voltage without voltage

drop even at load transition condition. The resistance of the input supply rail must be low enough that the input current transient does not cause too high drop in the LP8758-EA supply voltage that can cause false UVLO fault triggering. If the input supply is located more than a few inches from the LP8758-EA additional bulk capacitance may be required in addition to the ceramic bypass capacitors.

## 10 Layout

### 10.1 Layout Guidelines

The high frequency and large switching currents of the LP8758-EA make the choice of layout important. Good power supply results only occur when care is given to proper design and layout. Layout affects noise pickup and generation and can cause a good design to perform with less-than-expected results. With a range of output currents from milliamps to 4 A per converter core, good power supply layout is much more difficult than most general PCB design. The following steps should be used as a reference to ensure the device is stable and maintains proper voltage and current regulation across its intended operating voltage and current range.

1. Place  $C_{IN}$  as close as possible to the VIN\_Bx pin and the PGND\_Bxx pin. Route the  $V_{IN}$  trace wide and thick to avoid IR drops. The trace between the positive node of the input capacitor and the LP8758-EA VIN\_Bx pin(s), as well as the trace between the input capacitor's negative node and power PGND\_Bxx pin(s), must be kept as short as possible. The input capacitance provides a low-impedance voltage source for the switching converter. The inductance of the connection is the most important parameter of a local decoupling capacitor — parasitic inductance on these traces must be kept as tiny as possible for proper device operation.
2. The output filter, consisting of  $L_x$  and  $C_{OUTx}$ , converts the switching signal at SW\_Bx to the noiseless output voltage. It must be placed as close as possible to the device keeping the switch node small, for best EMI behavior. Route the traces between the output capacitors of the device and the load (or input capacitors of the load) direct and wide to avoid losses due to the IR drop.
3. Input for analog blocks (VANA and AGND) must be isolated from noisy signals. Connect VANA directly to a quiet system voltage node and AGND to a quiet ground point where no IR drop occurs. Place the decoupling capacitor as close to the VANA pin as possible. VANA must be connected to the same power node as VIN\_Bx pins.
4. If the load supports remote voltage sensing, connect the feedback pins FB\_Bx of the device to the respective sense pins on the load. The sense lines are susceptible to noise. They must be kept away from noisy signals such as PGND\_Bxx, VIN\_Bx, and SW\_Bx, as well as high bandwidth signals such as the  $I^2C$ . Avoid both capacitive as well as inductive coupling by keeping the sense lines short and direct. Run the lines in a quiet layer. Isolate them from noisy signals by a voltage or ground plane if possible.
5. PGND\_Bxx, VIN\_Bx and SW\_Bx must be routed on thick layers. They must not surround inner signal layers which are not able to withstand interference from noisy PGND\_Bxx, VIN\_Bx and SW\_Bx.

Due to the small package of this converter and the overall small solution size, the thermal performance of the PCB layout is important. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the power dissipation limits of a given component. Proper PCB layout, focusing on thermal performance, results in lower die temperatures. Wide power traces come with the ability to sink dissipated heat. This can be improved further on multi-layer PCB designs with vias to different planes. This results in reduced junction-to-ambient ( $R_{\theta JA}$ ) and junction-to-board ( $R_{\theta JB}$ ) thermal resistances and thereby reduces the device junction temperature,  $T_J$ . Performing a careful system-level 2D or full 3D dynamic thermal analysis at the beginning product design process is strongly recommended, using a thermal modeling analysis software.

## 10.2 Layout Example

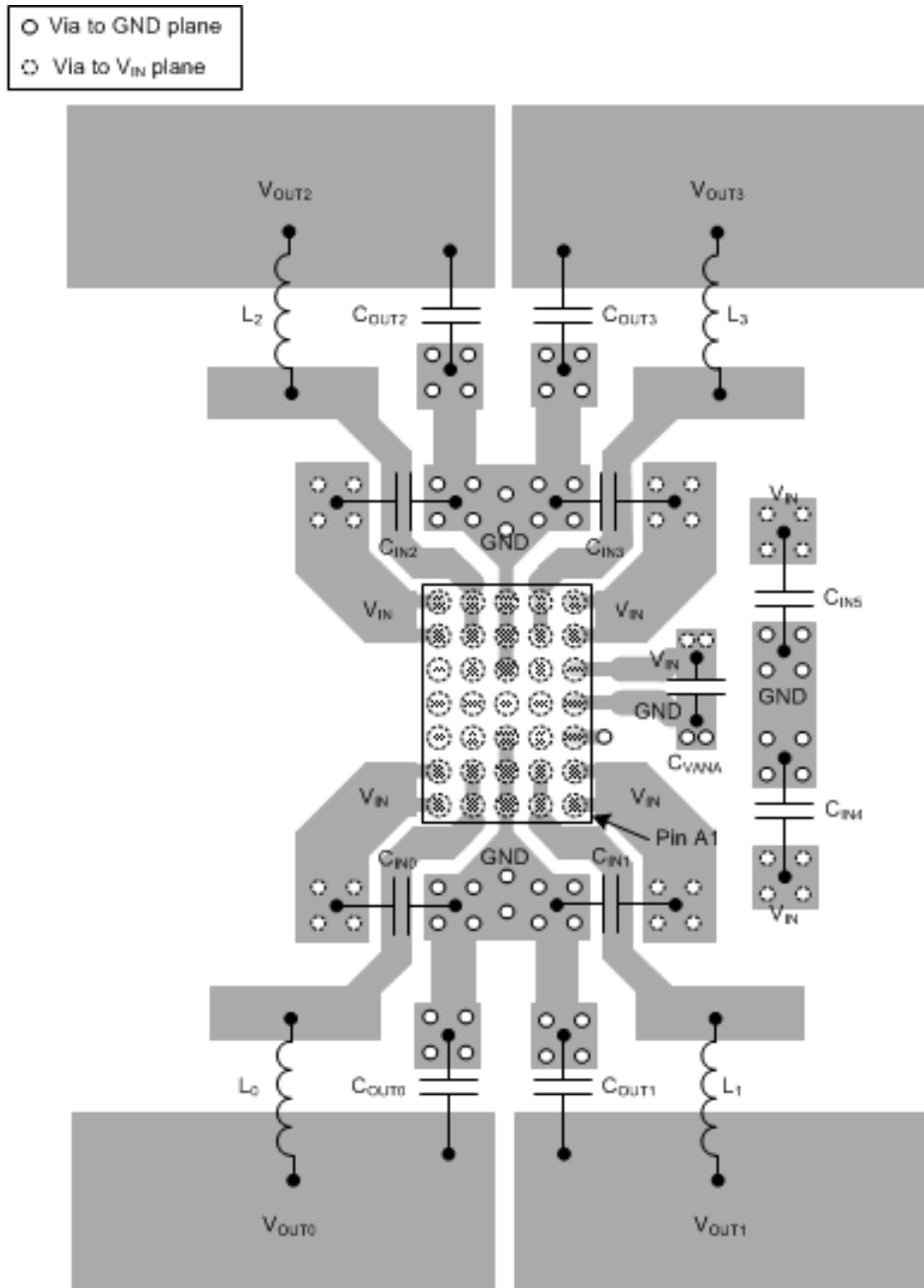


图 10-1. LP8758-EA Board Layout

## 11 Device and Documentation Support

### 11.1 Device Support

### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, [DSBGA Wafer Level Chip Scale Package application report](#)
- Texas instruments, [Using the LP8758EVM Evaluation Module user's guide](#)

#### 11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](#). Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 11.4 サポート・リソース

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#### 11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 11.7 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

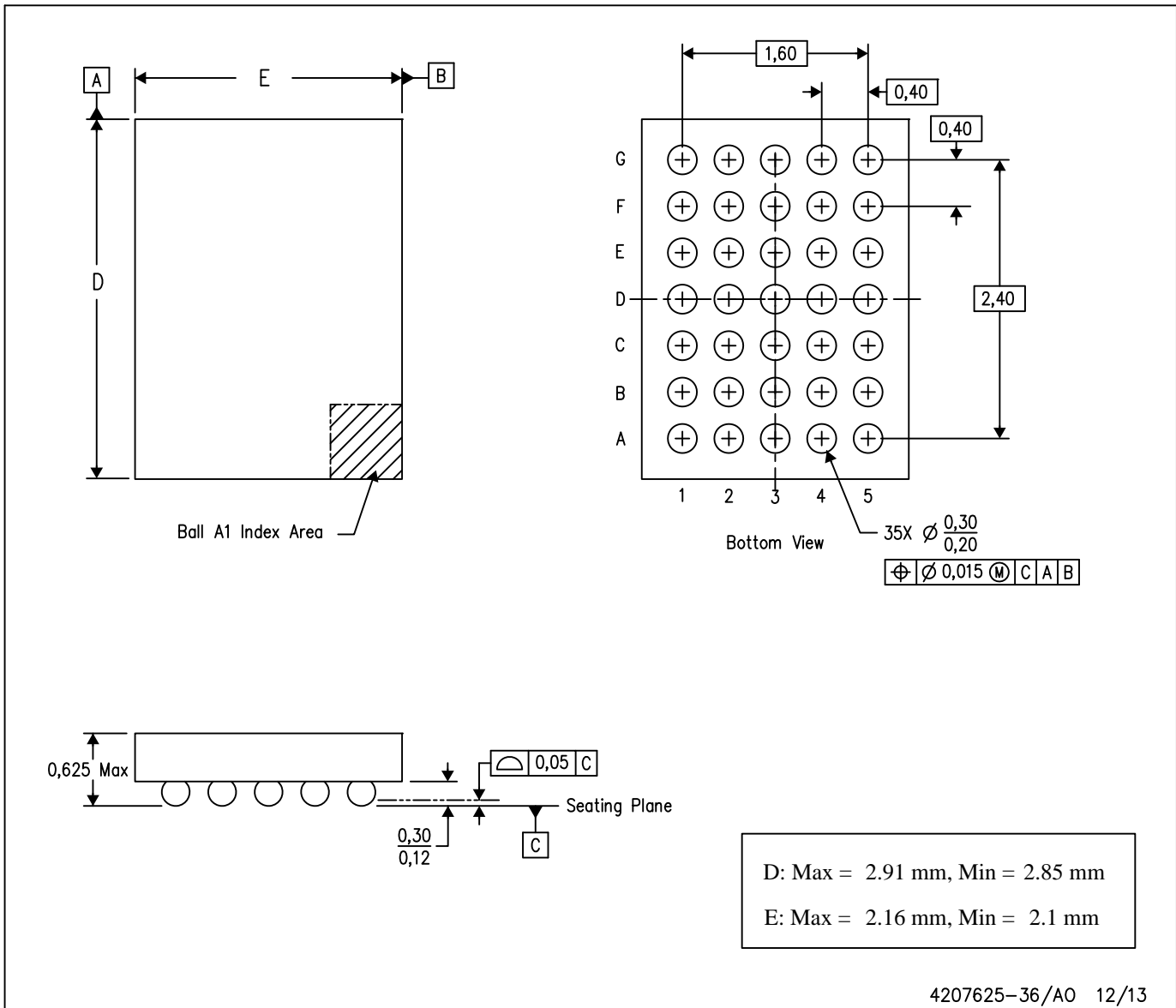


## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

YFF (R-XBGA-N35)

DIE-SIZE BALL GRID ARRAY



- NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.  
 B. This drawing is subject to change without notice.  
 C. NanoFree™ package configuration.

NanoFree is a trademark of Texas Instruments.

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