

# LMC7101Q-Q1

## レール ツー レール入出力、車載用、超小型、低消費電力オペアンプ

### 1 特長

- 車載アプリケーション用に AEC-Q100 認定済み:
  - 温度:  $-40^{\circ}\text{C} \sim +125^{\circ}\text{C}$ ,  $T_A$
- 超小型の 5 ピン SOT-23 パッケージによりスペースを削減できます。標準的な回路レイアウトは 8 ピン SOIC 設計の半分のスペースを占有します
- 2.7V、3V、5V、15V 電源について規定
- 電源電流 (標準値): 5V で 0.5mA
- 全高調波歪み (標準値): 5V で 0.01%
- 1MHz ゲイン帯域幅
- 一般的な LMC6482 および LMC6484 と類似
- レール ツー レール入出力

### 2 アプリケーション

- モバイル通信
- ノート PC および PDA
- バッテリー駆動製品
- センサ インターフェイス
- 車載用アプリケーション

### 3 概要

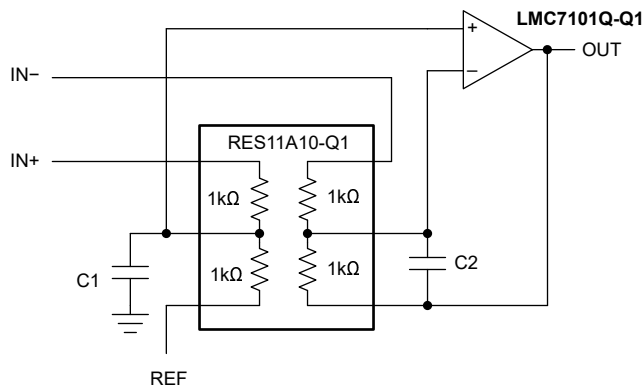
LMC7101Q-Q1 デバイスは高性能な車載用 CMOS オペアンプで、省スペースの 5 ピン SOT-23 小型パッケージで提供されます。この設計により、LMC7101Q-Q1 はスペースと重量の制約が厳しい設計にも最適です。性能は LMC6482 および LMC6484 のシングル アンプと同様で、レール ツー レールの入出力、高い開ループ ゲイン、低歪み、低消費電流を特長としています。

超小型パッケージの主な利点は、スペース制約が厳しいアプリケーションで最も明白です。超小型アンプは必要に応じて基板に配置できるため、基板レイアウトを簡素化できます。

#### パッケージ情報

部品番号	パッケージ <sup>(1)</sup>	パッケージ サイズ <sup>(2)</sup>
LMC7101Q-Q1	DBV (SOT-23, 5)	2.9mm × 2.8mm

- 詳細については、[セクション 10](#) を参照してください。
- パッケージ サイズ (長さ×幅) は公称値であり、該当する場合はピンも含まれます。



RES11A-Q1 を使った差動アンプのアプリケーション



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## 4 Pin Configuration and Functions

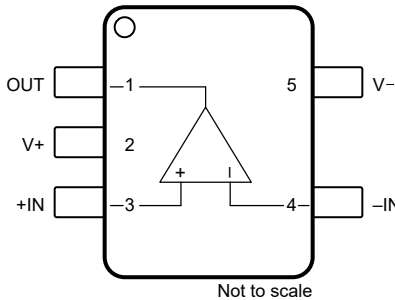


図 4-1. DBV Package, 5-Pin SOT-23 (Top View)

表 4-1. Pin Functions

PIN		TYPE	DESCRIPTION
NO.	NAME		
1	OUT	Output	Output
2	V+	Power	Positive supply
3	+IN	Input	Noninverting input
4	-IN	Input	Inverting input
5	V-	Power	Negative supply

## 5 Specifications

### 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup> <sup>(2)</sup>

		MIN	MAX	UNIT
	Difference Input voltage		±Supply voltage	V
	Voltage at input and output pins	(V-) – 0.3	(V+) + 0.3	V
V <sub>S</sub>	Supply voltage, V <sub>S</sub> = (V+) – (V-)		16	V
	Current at input pin	–5	5	mA
	Current at output pin <sup>(3)</sup>	–35	35	mA
	Current at power supply pin		35	mA
	Lead temperature (soldering, 10s)		260	°C
T <sub>J</sub>	Junction temperature <sup>(4)</sup>		150	°C
T <sub>stg</sub>	Storage temperature	–65	150	°C

- (1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) If Military/Aerospace specified devices are required, contact the TI Sales Office or Distributors for availability and specifications.
- (3) Applies to both single-supply and split-supply operation. Continuous short operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature at 150°C
- (4) The maximum power dissipation is a function of T<sub>J(MAX)</sub>, R<sub>θJA</sub> and T<sub>A</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> – T<sub>A</sub>) / R<sub>θJA</sub>. All numbers apply for packages soldered directly into a PC board.

### 5.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101	±1000	

- (1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

### 5.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>S</sub>	Supply voltage, V <sub>S</sub> = (V+) – (V-)	2.7		15.5	V
T <sub>A</sub>	Ambient temperature	–40		125	°C

### 5.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		LMC7101Q-Q1	UNIT
		DBV (SOT-23)	
		5 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	193.5	°C/W
R <sub>θJC(top)</sub>	Junction-to-case(top) thermal resistance	128.5	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	88.9	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	66.8	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	88.6	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case(bottom) thermal resistance	N/A	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 5.5 Electrical Characteristics for $V_S = 2.7V$ or $\pm 1.35V$

at  $T_A = 25^\circ C$ ,  $V_+ = 2.7V$ ,  $V_- = 0V$ ,  $V_{CM} = V_{OUT} = V_+ / 2$ , and  $R_L = 1M\Omega$  connected to  $V_+ / 2$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>OFFSET VOLTAGE</b>							
$V_{OS}$	Input offset voltage			$\pm 0.11$	$\pm 9$	mV	
$dV_{OS}/dT$	Input offset voltage drift	$T_A = -40^\circ C$ to $+125^\circ C$		1		$\mu V/^\circ C$	
PSRR	Power-supply rejection ratio	$V_+ = 1.35V$ to $1.65V$ , $V_- = -1.35V$ to $-1.65V$ , $V_{CM} = 0V$	45	60		dB	
<b>INPUT BIAS CURRENT</b>							
$I_B$	Input bias current	$T_A = -40^\circ C$ to $+125^\circ C$		$\pm 1$	$\pm 1000$	pA	
$I_{OS}$	Input offset current	$T_A = -40^\circ C$ to $+125^\circ C$		$\pm 0.5$	$\pm 2000$	pA	
<b>INPUT VOLTAGE</b>							
$V_{CM}$	Common-mode voltage	For $CMRR \geq 47dB$	Positive 2.7	3		V	
			Negative	0	0		
CMRR	Common-mode rejection	$0V \leq V_{CM} \leq 2.7V$	47	70		dB	
<b>INPUT IMPEDANCE</b>							
$R_{IN}$	Input resistance			$> 1$		$T\Omega$	
$C_{IN}$	Common-mode input capacitance			3		pF	
<b>FREQUENCY RESPONSE</b>							
GBW	Gain bandwidth product			0.6		MHz	
SR	Slew rate <sup>(1)</sup>	$V_+ = 15V$ , 10V step, $G = 1$ , $R_L = 100k\Omega$ to $7.5V$ , $V_{OUT} = 10V_{PP}$ , $f = 1kHz$		0.7		V/ $\mu s$	
<b>OUTPUT</b>							
$V_O$	Voltage output swing	Positive rail	$R_L = 2k\Omega$	2.15	2.45	V	
			$R_L = 10k\Omega$	2.64	2.68		
		Negative rail	$R_L = 2k\Omega$		0.25		0.5
			$R_L = 10k\Omega$		0.025		0.06
<b>POWER SUPPLY</b>							
$I_Q$	Quiescent current per amplifier	$T_A = -40^\circ C$ to $+125^\circ C$		500	810	$\mu A$	
				500	950		

(1) Number specified is the slower of the positive and negative slew rates.

## 5.6 Electrical Characteristics for $V_S = 3V$ or $\pm 1.5V$

at  $T_A = 25^\circ\text{C}$ ,  $V_+ = 3V$ ,  $V_- = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_+ / 2$ , and  $R_L = 1M\Omega$  connected to  $V_+ / 2$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>OFFSET VOLTAGE</b>							
$V_{OS}$	Input offset voltage			$\pm 0.11$	$\pm 7$	mV	
$dV_{OS}/dT$	Input offset voltage drift	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		1		$\mu\text{V}/^\circ\text{C}$	
PSRR	Power-supply rejection ratio	$V_+ = 1.5V$ to $7.5V$ , $V_- = -1.5V$ to $-7.5V$ , $V_{OUT} = V_{CM} = 0V$	60	80		dB	
<b>INPUT BIAS CURRENT</b>							
$I_B$	Input bias current	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		$\pm 1$	$\pm 1000$	pA	
$I_{OS}$	Input offset current	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		$\pm 0.5$	$\pm 2000$	pA	
<b>INPUT VOLTAGE</b>							
$V_{CM}$	Input common-mode voltage	For $CMRR \geq 47\text{dB}$	Positive 3	3.3		V	
			Negative	0	0		
CMRR	Common-mode rejection	$0V \leq V_{CM} \leq 3V$	47	70		dB	
<b>INPUT IMPEDANCE</b>							
$R_{IN}$	Input resistance			$> 1$		$T\Omega$	
$C_{IN}$	Common-mode input capacitance			3		pF	
<b>OUTPUT</b>							
$V_O$	Voltage output swing	Positive rail	$R_L = 2k\Omega$	2.6	2.8	V	
			$R_L = 600\Omega$	2.5	2.7		
		Negative rail	$R_L = 2k\Omega$		0.2		0.4
			$R_L = 600\Omega$		0.37		0.6
<b>POWER SUPPLY</b>							
$I_Q$	Quiescent current per amplifier	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		500	810	$\mu\text{A}$	
				500	950		

## 5.7 Electrical Characteristics for $V_S = 5V$ or $\pm 2.5V$

at  $T_A = 25^\circ\text{C}$ ,  $V_+ = 5V$ ,  $V_- = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_+ / 2$ , and  $R_L = 1M\Omega$  connected to  $V_+ / 2$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>OFFSET VOLTAGE</b>							
$V_{OS}$	Input offset voltage			$\pm 0.11$	$\pm 7$	mV	
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		$\pm 0.11$	$\pm 9$		
$dV_{OS}/dT$	Input offset voltage drift	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		1		$\mu\text{V}/^\circ\text{C}$	
PSRR	Power supply rejection ratio	Positive $V_+ = 5V$ to $15V$ $V_- = 0V$ , $V_{OUT} = 1.5V$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	65	82	dB	
				62	82		
		Negative $V_+ = -5V$ to $-15V$ $V_- = 0V$ , $V_{OUT} = -1.5V$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	65	82		
				62	82		
<b>INPUT BIAS CURRENT</b>							
$I_B$	Input bias current			$\pm 1$		pA	
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$			$\pm 1000$		
$I_{OS}$	Input offset current			$\pm 0.5$		pA	
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$			$\pm 2000$		
<b>NOISE</b>							
THD	Total harmonic distortion	$f = 10\text{kHz}$ , $G = -2V/V$ , $R_L = 10k\Omega$ , $V_{OUT} = 4V_{pp}$		0.01		%	
<b>INPUT VOLTAGE</b>							
$V_{CM}$	Input common-mode voltage	To positive rail CMRR > 50dB	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	5.2	5.3	V	
				4.8	5.3		
		To negative rail CMRR > 50dB	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		-0.3		-0.2
					-0.3		0.2
CMRR	Common-mode rejection ratio	$0V \leq V_{CM} \leq 5V$		52	75	dB	
		$0.2V \leq V_{CM} \leq 4.8V$ , $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		51	74		
<b>INPUT IMPEDANCE</b>							
$R_{IN}$	Input resistance			> 1		$T\Omega$	
$C_{IN}$	Input capacitance			3		pF	
<b>FREQUENCY RESPONSE</b>							
GBW	Gain bandwidth product			1		MHz	
SR	Slew rate			1		$V/\mu\text{s}$	
<b>OUTPUT</b>							
$V_O$	Voltage output swing	Positive rail $R_L = 2k\Omega$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	4.7	4.9	V	
				4.54	4.9		
		Negative rail $R_L = 2k\Omega$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		0.1		0.18
					0.1		0.28
		Positive rail $R_L = 600\Omega$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	4.5	4.7		
				4.28	4.7		
		Negative rail $R_L = 600\Omega$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		0.3		0.5
					0.3		0.8
$I_{SC}$	Short-circuit current	Sourcing $V_{OUT} = 0V$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	16	24	mA	
				9	24		
		Sinking $V_{OUT} = 5V$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	11	19		
				5.8	19		
<b>POWER SUPPLY</b>							
$I_Q$	Quiescent current per amplifier			0.5	0.85	mA	
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$			0.5		1

### 5.8 Electrical Characteristics for $V_S = 15V$ or $\pm 7.5V$

at  $T_A = 25^\circ C$ ,  $V_+ = 15V$ ,  $V_- = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_+ / 2$ , and  $R_L = 1M\Omega$  connected to  $V_+ / 2$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>OFFSET VOLTAGE</b>							
$V_{OS}$	Input offset voltage			$\pm 0.26$		mV	
$dV_{OS}/dT$	Input offset voltage drift	$T_A = -40^\circ C$ to $+125^\circ C$		1		$\mu V/^\circ C$	
PSRR	Power-supply rejection ratio	Positive $V_+ = 5V$ to $15V$ , $V_- = 0V$ , $V_{OUT} = 1.5V$	$T_A = -40^\circ C$ to $+125^\circ C$	62	82	dB	
		Negative $V_+ = -5V$ to $-15V$ , $V_- = 0V$ , $V_{OUT} = -1.5V$		65	82		
			$T_A = -40^\circ C$ to $+125^\circ C$	62	82		
<b>INPUT BIAS CURRENT</b>							
$I_B$	Input bias current			$\pm 1$		pA	
		$T_A = -40^\circ C$ to $+125^\circ C$			$\pm 1000$		
$I_{OS}$	Input offset current			$\pm 0.5$		pA	
		$T_A = -40^\circ C$ to $+125^\circ C$			$\pm 2000$		
<b>NOISE</b>							
$e_n$	Input voltage noise density	$f = 1kHz$ , $V_{CM} = 1V$		37		$nV/\sqrt{Hz}$	
$i_n$	Input current noise density	$f = 1kHz$		6.8		$fA/\sqrt{Hz}$	
THD	Total harmonic distortion	$f = 1kHz$ , $G = -2V/V$ , $R_L = 10k\Omega$ , $V_{OUT} = 8.5V_{pp}$		0.01		%	
<b>INPUT VOLTAGE</b>							
$V_{CM}$	Input common-mode voltage	To positive rail $V_+ = 15V$ , CMRR > 50dB	$T_A = -40^\circ C$ to $+125^\circ C$	15.2	15.3	V	
				14.8	15.3		
		To negative rail $V_+ = 15V$ , CMRR > 50dB	$T_A = -40^\circ C$ to $+125^\circ C$		-0.3		-0.2
					-0.3		0.2
CMRR	Common-mode rejection ratio	$0V \leq V_{CM} \leq 15V$		62	82	dB	
		$0.2V \leq V_{CM} \leq 14.8V$ , $T_A = -40^\circ C$ to $+125^\circ C$		60	82		
<b>INPUT IMPEDANCE</b>							
$R_{IN}$	Input resistance			> 1		T $\Omega$	
$C_{IN}$	Input capacitance			3		pF	
<b>OPEN-LOOP GAIN</b>							
$A_{OL}$	Open-loop voltage gain	Sourcing $7.5V < V_O < 12.5V$ , $V_{CM} = 1.5V$ $R_L = 2k\Omega$ to $7.5V$	$T_A = -40^\circ C$ to $+125^\circ C$	80	340	V/mV	
				30	340		
		Sinking $2.5V < V_O < 7.5V$ , $V_{CM} = 1.5V$ $R_L = 2k\Omega$ to $7.5V$	$T_A = -40^\circ C$ to $+125^\circ C$	15	24		
				4	24		
		Sourcing, $V_{CM} = 1.5V$ , $7.5V < V_O < 12.5V$ , $R_L = 600\Omega$		34	300		
Sinking, $V_{CM} = 1.5V$ , $2.5V < V_O < 7.5V$ , $R_L = 600\Omega$		6	15				

## 5.8 Electrical Characteristics for $V_S = 15V$ or $\pm 7.5V$ (続き)

at  $T_A = 25^\circ C$ ,  $V_+ = 15V$ ,  $V_- = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_+ / 2$ , and  $R_L = 1M\Omega$  connected to  $V_+ / 2$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT	
<b>FREQUENCY RESPONSE</b>								
GBW	Gain bandwidth product				1.1		MHz	
SR	Slew rate <sup>(1)</sup>	10V step, $R_L = 100k\Omega$ to 7.5V $V_{OUT} = 10V_{PP}$ , $f = 1kHz$		0.5	1.1		V/ $\mu s$	
			$T_A = -40^\circ C$ to $+125^\circ C$	0.4	1.1			
$\theta_m$	Phase margin				45		$^\circ$	
$G_m$	Gain margin				10		dB	
<b>OUTPUT</b>								
$V_O$	Voltage output swing	Positive rail $R_L = 2k\Omega$		14.4	14.7		V	
			$T_A = -40^\circ C$ to $+125^\circ C$	14.2	14.7			
		Negative rail $R_L = 2k\Omega$			0.16	0.32		
			$T_A = -40^\circ C$ to $+125^\circ C$			0.16		0.45
		Positive rail $R_L = 600\Omega$		13.4	14.1			
			$T_A = -40^\circ C$ to $+125^\circ C$	12.85	14.1			
$I_{SC}$	Short-circuit current <sup>(2)</sup>	Sourcing $V_{OUT} = 0V$		30	50		mA	
			$T_A = -40^\circ C$ to $+125^\circ C$	20	50			
		Sinking $V_{OUT} = 12V$		30	50			
			$T_A = -40^\circ C$ to $+125^\circ C$	20	50			
<b>POWER SUPPLY</b>								
$I_Q$	Quiescent current per amplifier				0.8	1.5	mA	
		$T_A = -40^\circ C$ to $+125^\circ C$				0.8		1.75

(1) Number specified is the slower of the positive and negative slew rates.

(2) Do not short circuit output to  $V_+$  when  $V_+$  is greater than 12V or reliability can be adversely affected.



### 5.9 Typical Characteristics for $V_S = 2.7V$

at  $V_+ = 2.7V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)

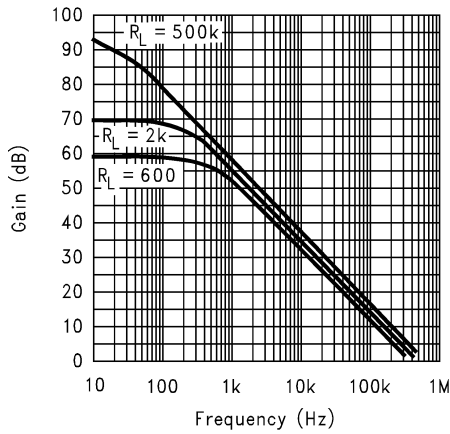


Figure 5-1. Open-Loop Frequency Response

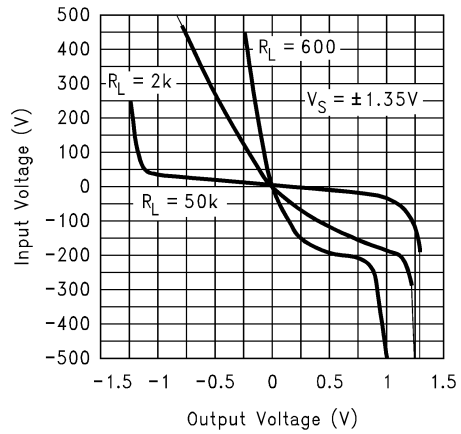


Figure 5-2. Input Voltage vs Output Voltage

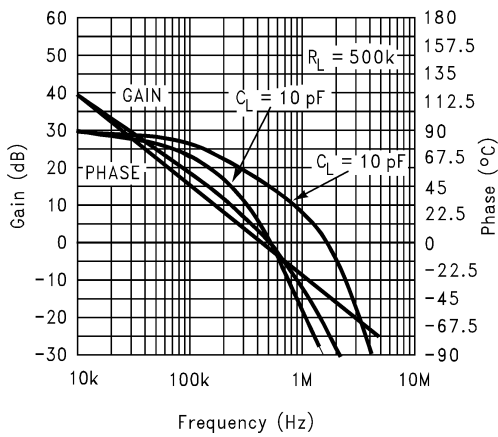


Figure 5-3. Gain and Phase vs Capacitance Load

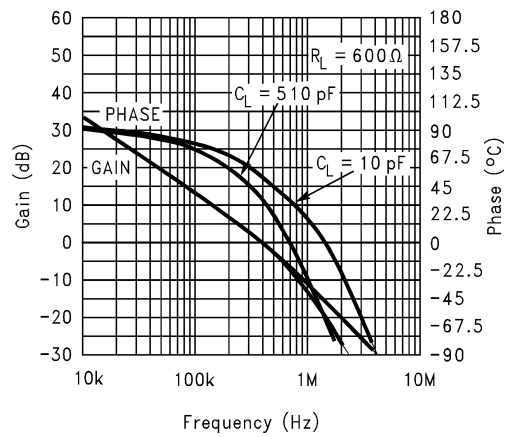


Figure 5-4. Gain and Phase vs Capacitance Load

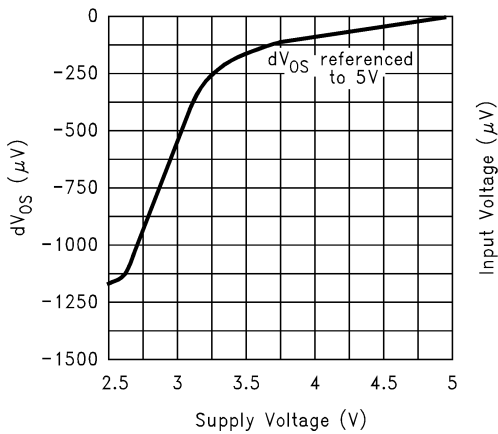


Figure 5-5.  $dV_{OS}$  vs Supply Voltage

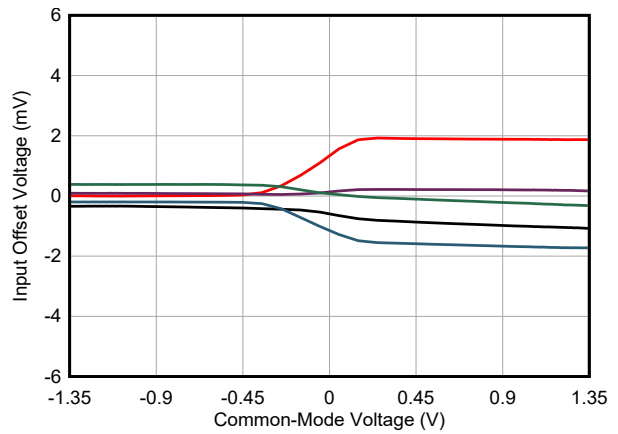
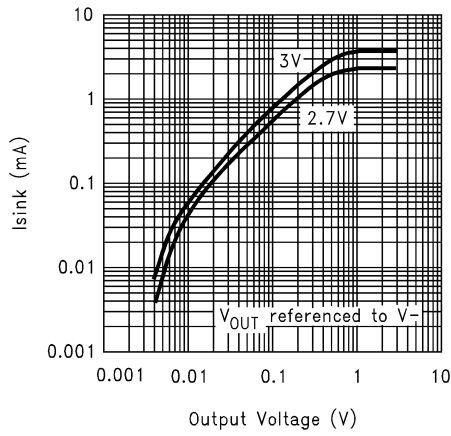


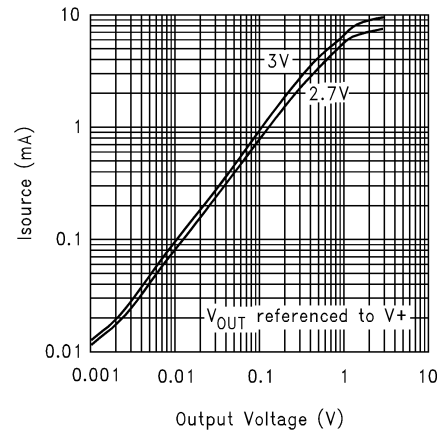
Figure 5-6. Input Offset Voltage vs Common-Mode Voltage

### 5.9 Typical Characteristics for $V_S = 2.7V$ (continued)

at  $V_+ = 2.7V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



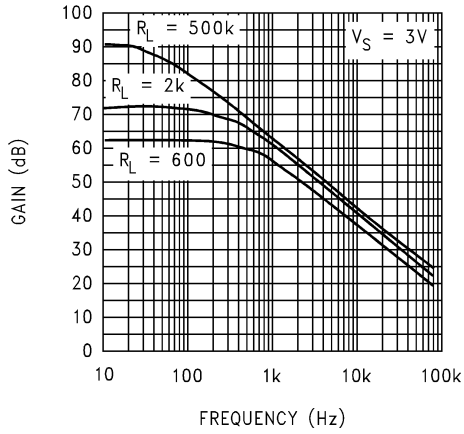
5-7. Sinking Current vs Output Voltage



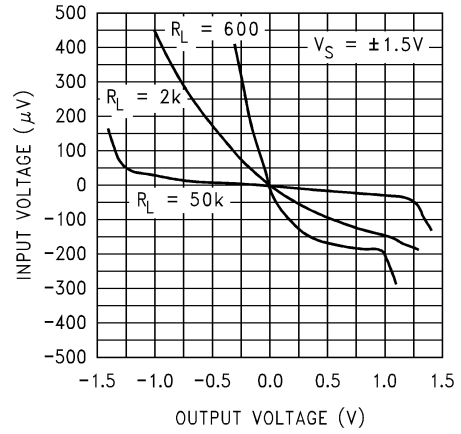
5-8. Sourcing Current vs Output Voltage

### 5.10 Typical Characteristics for $V_S = 3V$

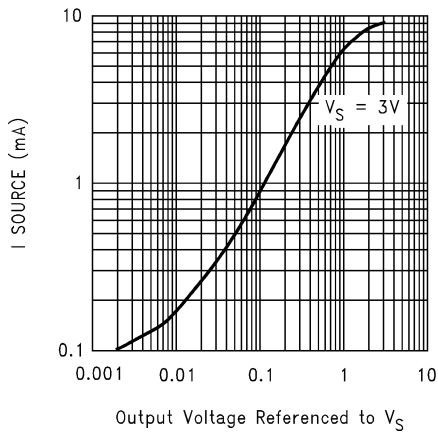
at  $V_+ = 3V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



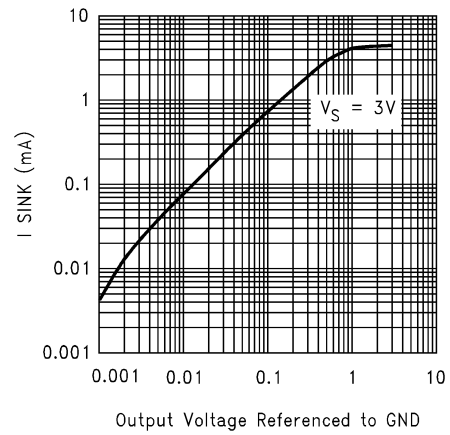
5-9. Open-Loop Frequency Response



5-10. Input Voltage vs Output Voltage



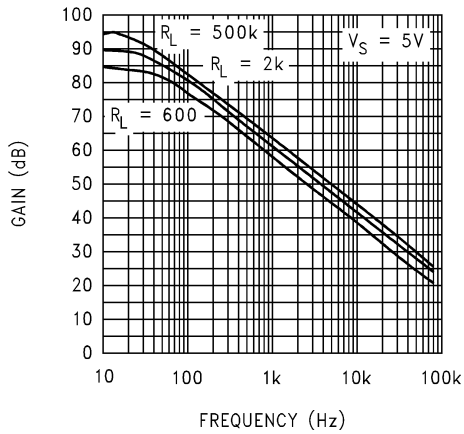
5-11. Sourcing Current vs Output Voltage



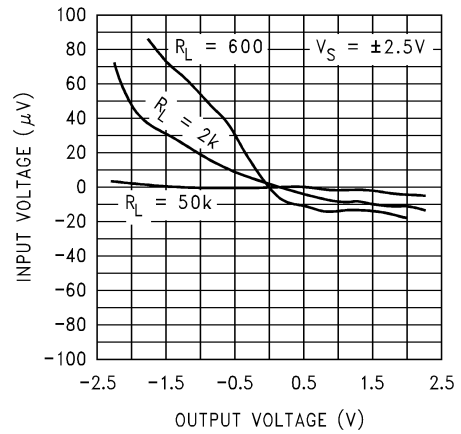
5-12. Sinking Current vs Output Voltage

### 5.11 Typical Characteristics for $V_S = 5V$

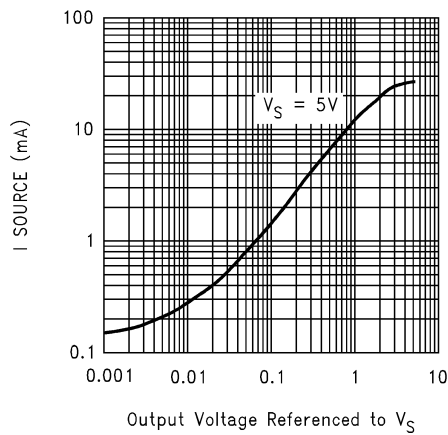
at  $V_+ = 5V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



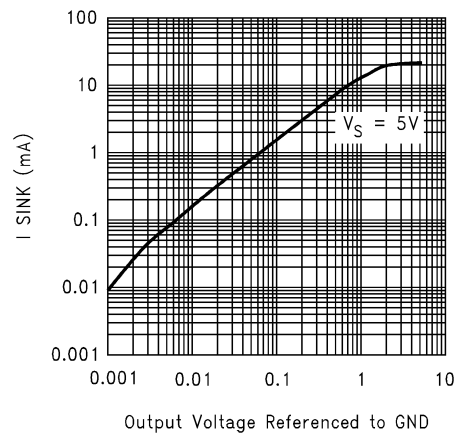
5-13. Open-Loop Frequency Response



5-14. Input Voltage vs Output Voltage



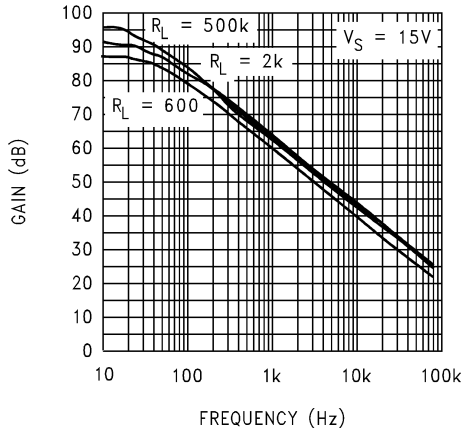
5-15. Sourcing Current vs Output Voltage



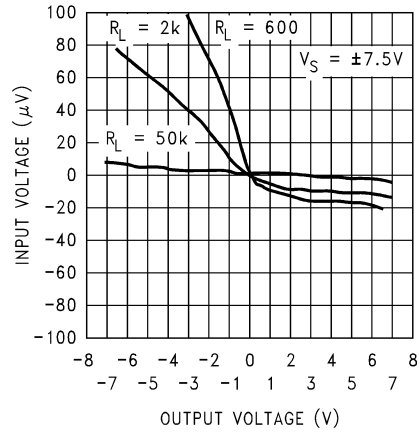
5-16. Sinking Current vs Output Voltage

### 5.12 Typical Characteristics for $V_S = 15V$

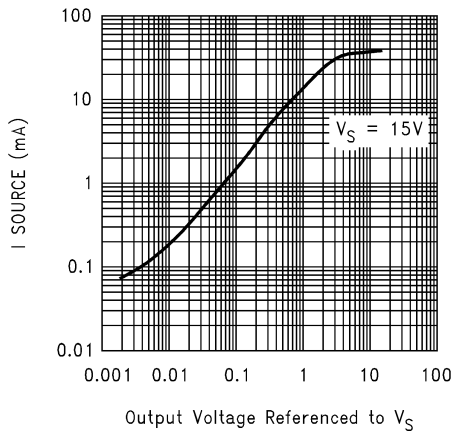
at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



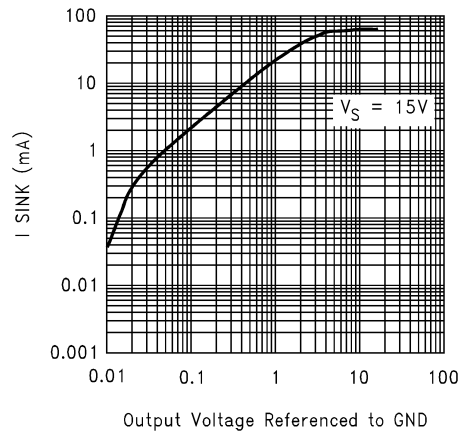
5-17. Open-Loop Frequency Response



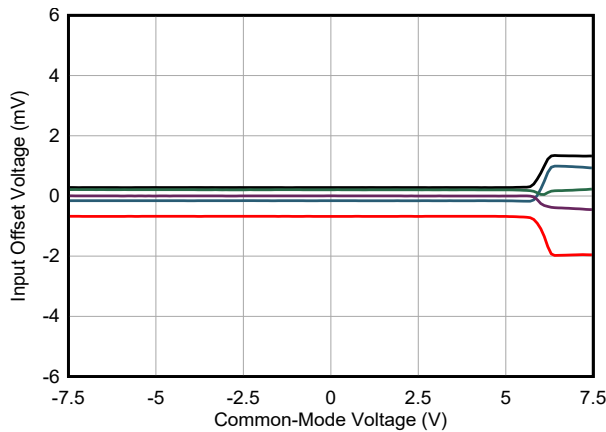
5-18. Input Voltage vs Output Voltage



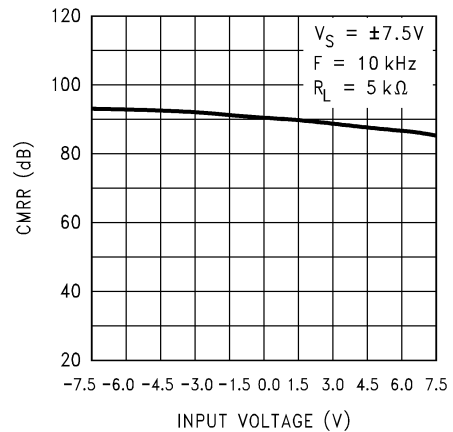
5-19. Sourcing Current vs Output Voltage



5-20. Sinking Current vs Output Voltage



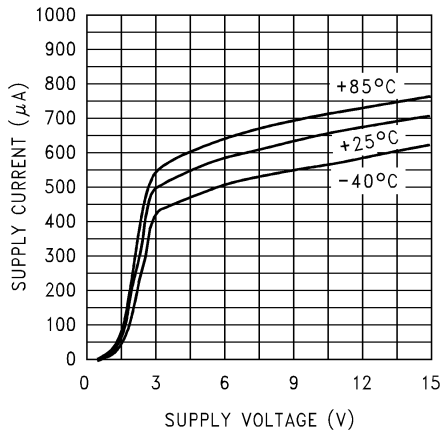
5-21. Input Offset Voltage vs Common-Mode Voltage



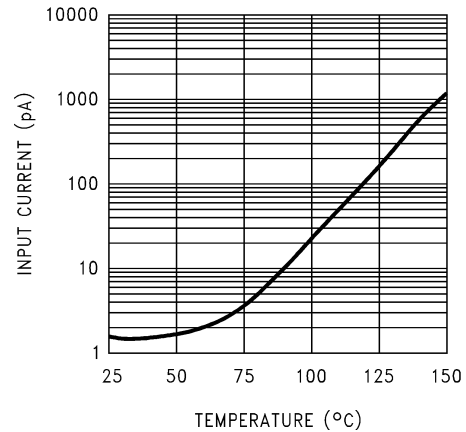
5-22. CMRR vs Input Voltage

### 5.12 Typical Characteristics for $V_S = 15V$ (continued)

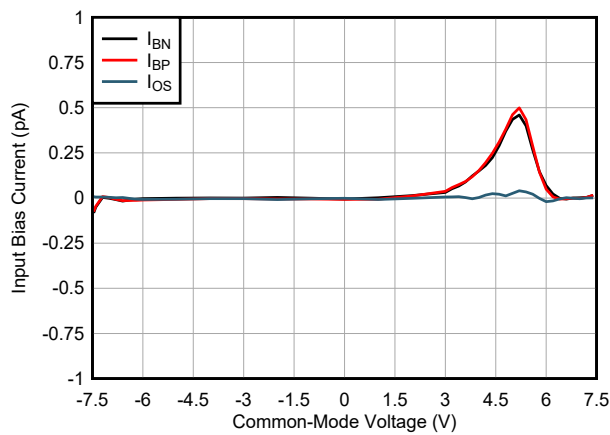
at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



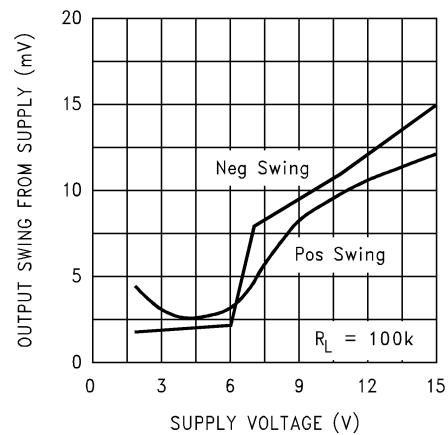
5-23. Supply Current vs Supply Voltage



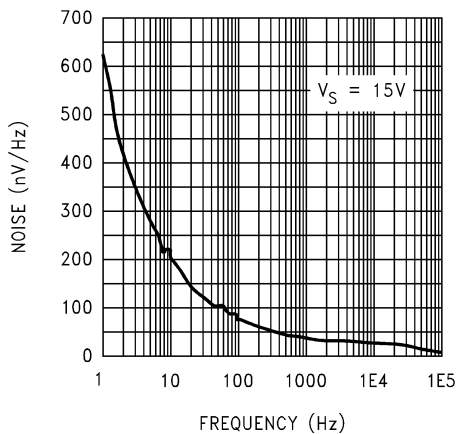
5-24. Input Current vs Temperature



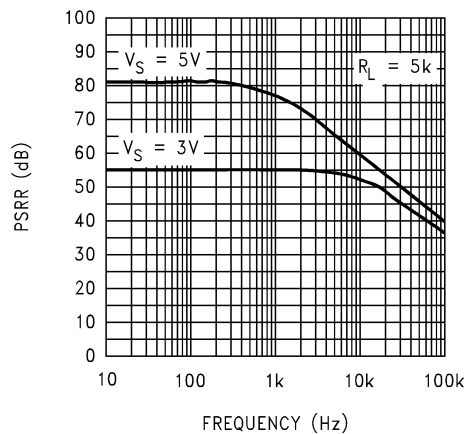
5-25. Input Bias Current vs Common-Mode Voltage



5-26. Output Voltage Swing vs Supply Voltage



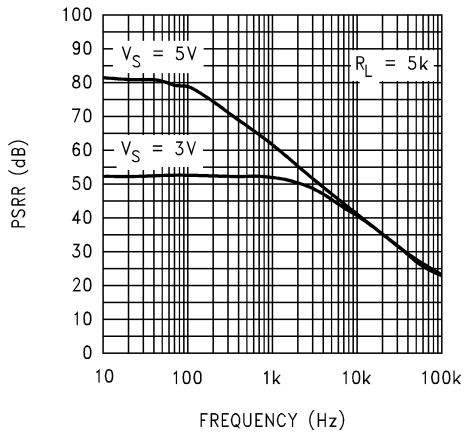
5-27. Input Voltage Noise vs Frequency



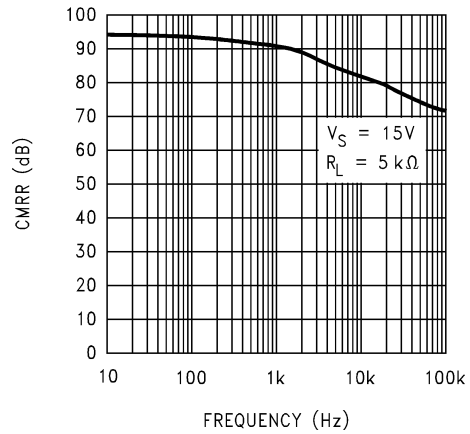
5-28. Positive PSRR vs Frequency

### 5.12 Typical Characteristics for $V_S = 15V$ (continued)

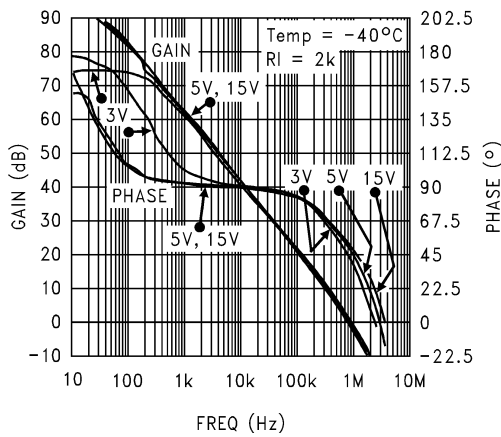
at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



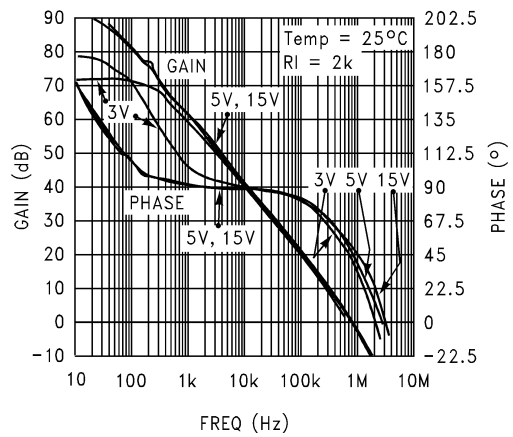
5-29. Negative PSRR vs Frequency



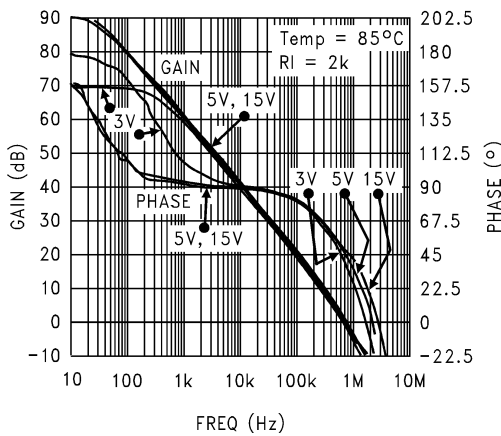
5-30. CMRR vs Frequency



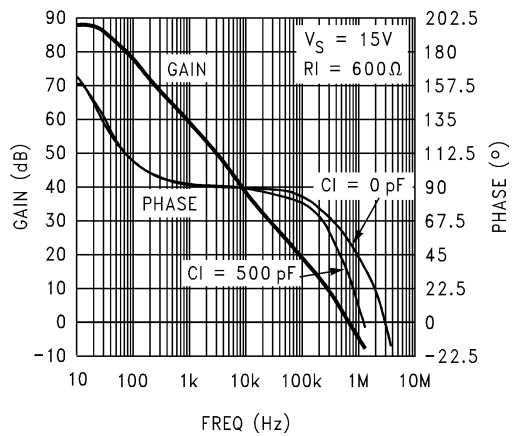
5-31. Open-Loop Frequency Response at  $-40^\circ C$



5-32. Open-Loop Frequency Response at  $25^\circ C$



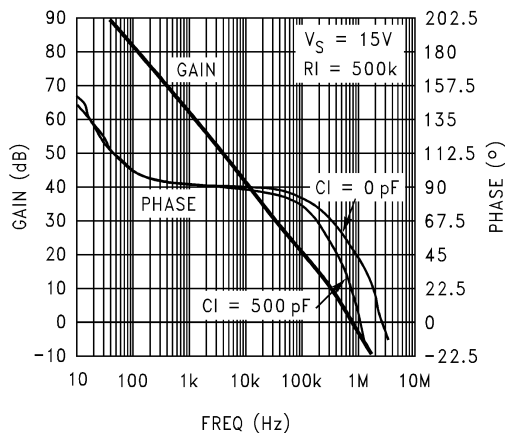
5-33. Open-Loop Frequency Response at  $85^\circ C$



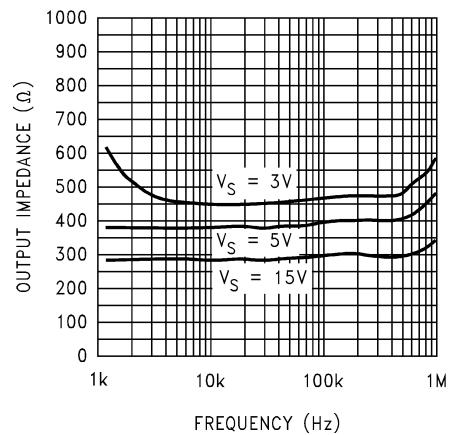
5-34. Gain and Phase vs Capacitive Load

### 5.12 Typical Characteristics for $V_S = 15V$ (continued)

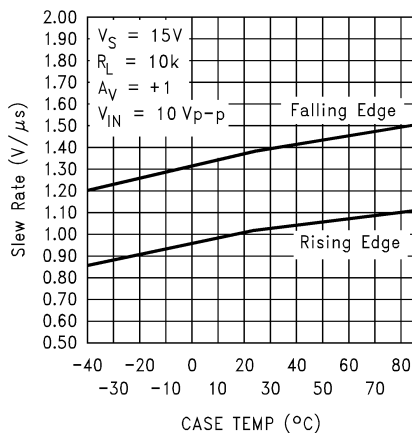
at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



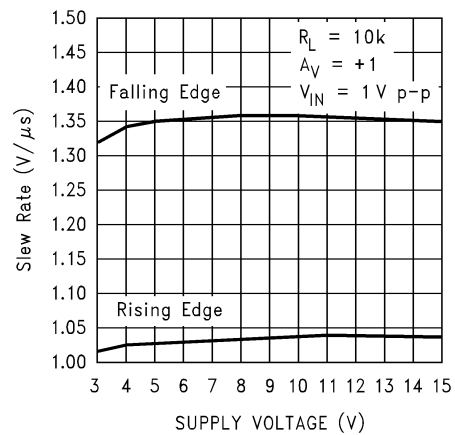
5-35. Gain and Phase vs Capacitive Load



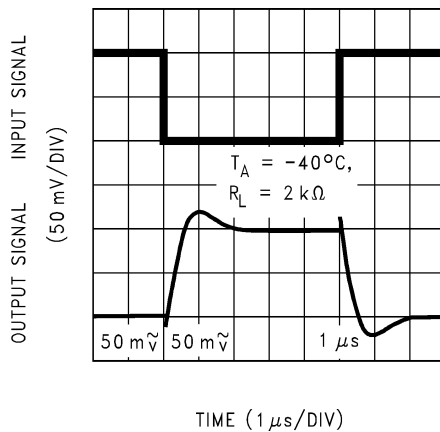
5-36. Output Impedance vs Frequency



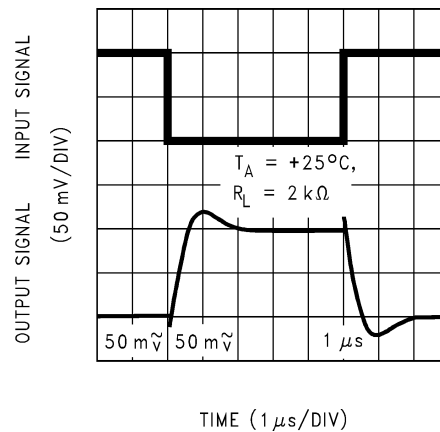
5-37. Slew Rate vs Temperature



5-38. Slew Rate vs Supply Voltage



5-39. Inverting Small-Signal Pulse Response

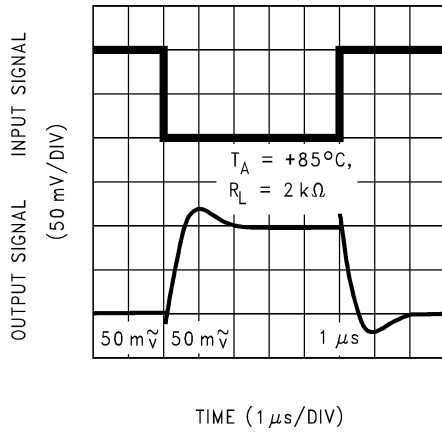


5-40. Inverting Small-Signal Pulse Response

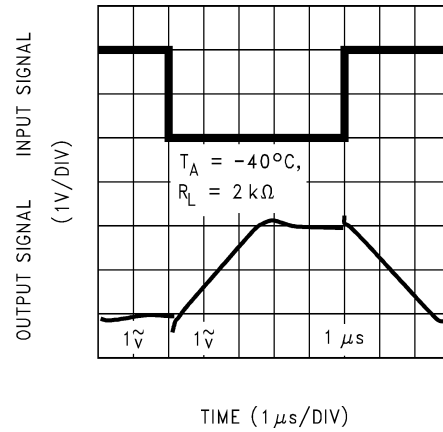


## 5.12 Typical Characteristics for $V_S = 15V$ (continued)

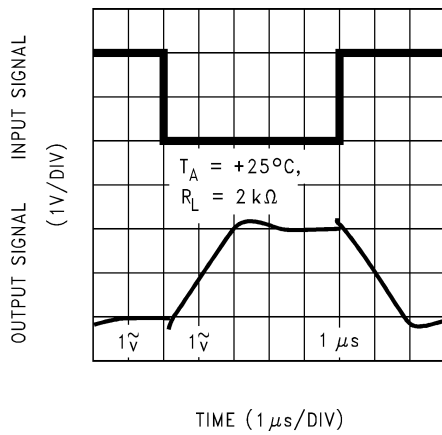
at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



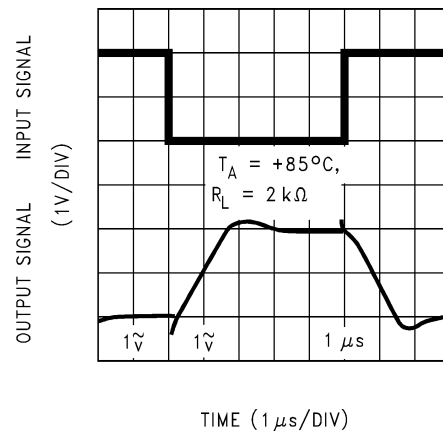
5-41. Inverting Small-Signal Pulse Response



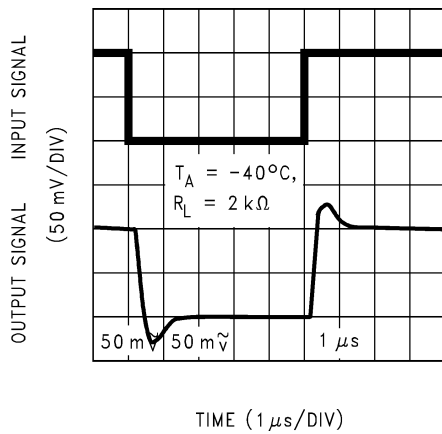
5-42. Inverting Large-Signal Pulse Response



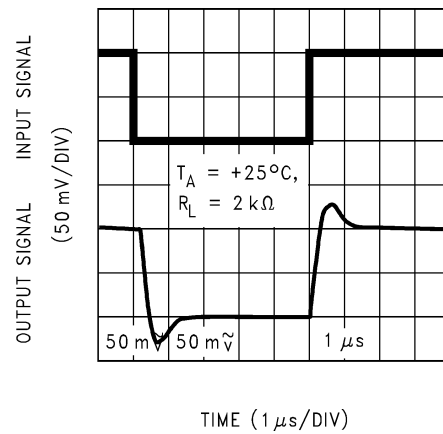
5-43. Inverting Large-Signal Pulse Response



5-44. Inverting Large-Signal Pulse Response



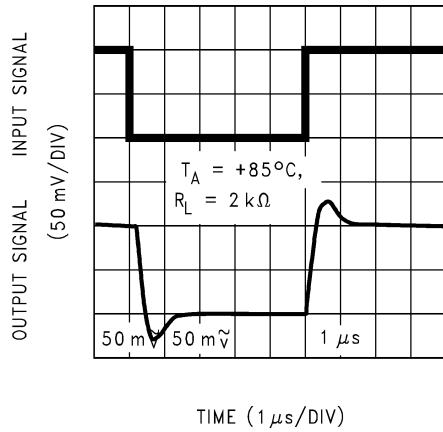
5-45. Noninverting Small-Signal Pulse Response



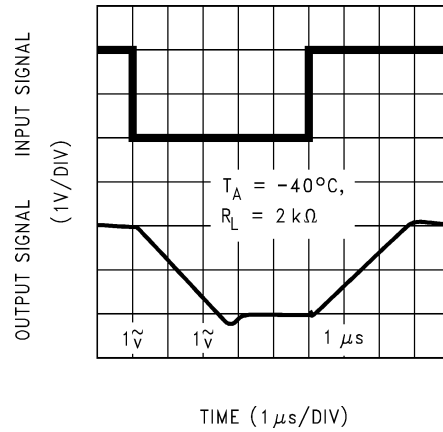
5-46. Noninverting Small-Signal Pulse Response

### 5.12 Typical Characteristics for $V_S = 15V$ (continued)

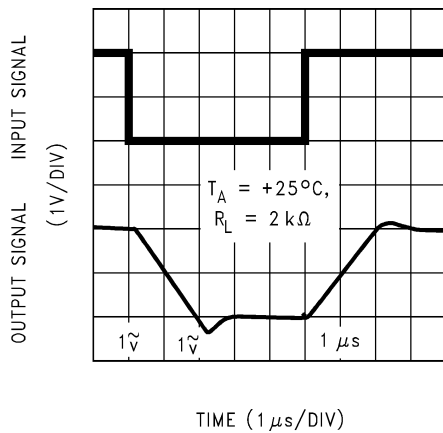
at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)



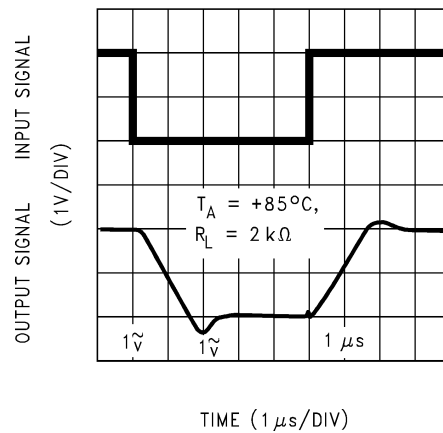
5-47. Noninverting Small-Signal Pulse Response



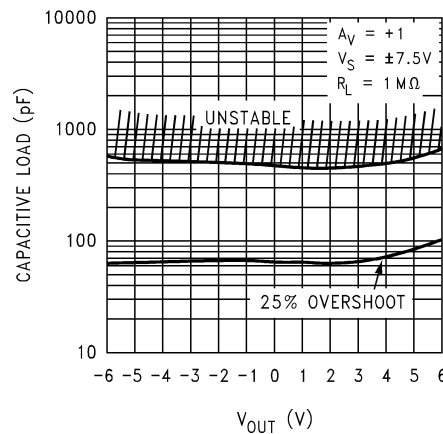
5-48. Noninverting Large-Signal Pulse Response



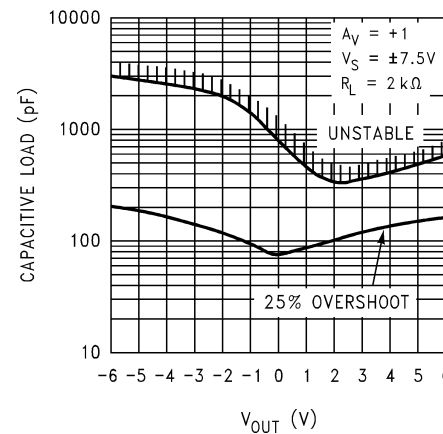
5-49. Noninverting Large-Signal Pulse Response



5-50. Noninverting Large-Signal Pulse Response



5-51. Stability vs Capacitive Load



5-52. Stability vs Capacitive Load

## 5.12 Typical Characteristics for $V_S = 15V$ (continued)

at  $V_+ = 15V$ ,  $V_- = 0V$ , and  $T_A = 25^\circ C$  (unless otherwise specified)

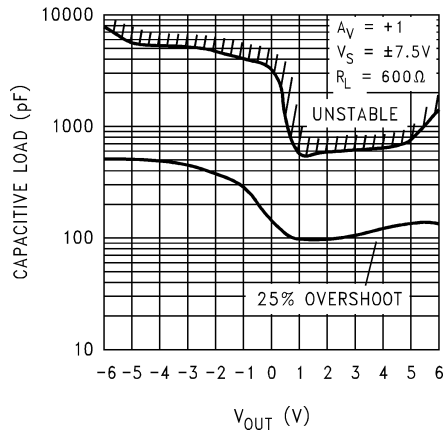


图 5-53. Stability vs Capacitive Load

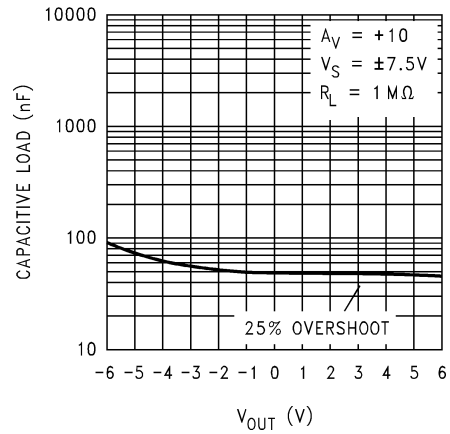


图 5-54. Stability vs Capacitive Load

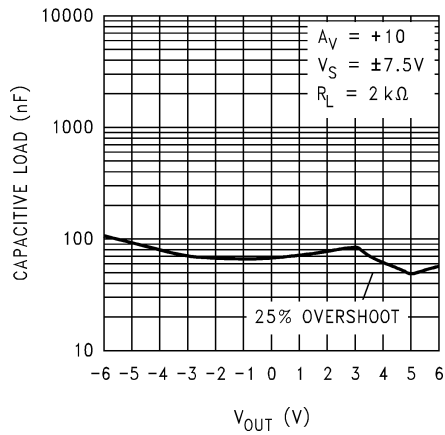


图 5-55. Stability vs Capacitive Load

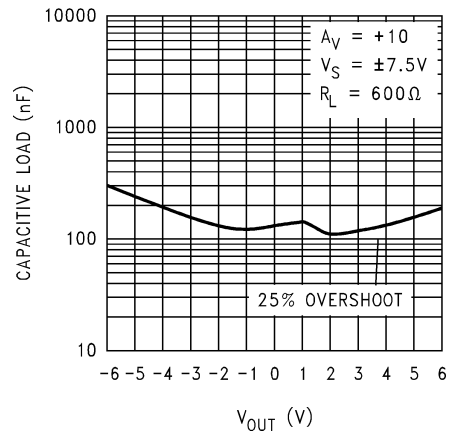


图 5-56. Stability vs Capacitive Load

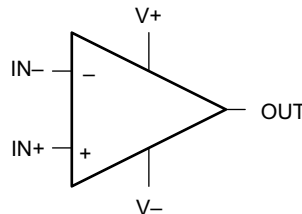
## 6 Detailed Description

### 6.1 Overview

The LMC7101Q-Q1 is a single-channel, low-power operational amplifier available in a space-saving SOT-23 package, offering rail-to-rail input and output operation across a wide range of power-supply configurations.

The LMC7101Q-Q1 is also available in a commercial-grade variant, see LMC7101.

### 6.2 Functional Block Diagram



### 6.3 Feature Description

#### 6.3.1 Benefits of the LMC7101 Tiny Amplifier

##### 6.3.1.1 Size

The small footprint of the SOT-23-5 packaged tiny amplifier, (0.12in × 0.118in, 3.05mm × 3mm) saves space on printed circuit boards, and enable the design of smaller electronic products. Many customers prefer smaller and lighter products because the designs can contribute to overall weight reduction in vehicles.

##### 6.3.1.2 Height

The 0.056 inches (1.43mm) height of the tiny LMC7101Q-Q1 amplifier makes the device an excellent choice for use in a wide range of circuit boards in which a thin profile is required.

##### 6.3.1.3 Signal Integrity

Signals can pick up noise between the signal source and the amplifier. By using a physically smaller amplifier package, the tiny amplifier can be placed closer to the signal source, thus reducing noise pickup and increasing signal integrity. The tiny amplifier can also be placed next to the signal destination, such as a buffer, for the reference of an analog-to-digital converter.

##### 6.3.1.4 Simplified Board Layout

The tiny LMC7101Q-Q1 amplifier can simplify board layout in several ways. Avoid long PCB traces by correctly placing amplifiers instead of routing signals to a dual or quad device. By using multiple tiny amplifiers instead of duals or quads, complex signal routing and possibly crosstalk can be reduced.

##### 6.3.1.5 Low THD

The high open-loop gain of the LMC7101Q-Q1 amplifier helps to achieve very low audio distortion—typically 0.01% at 10kHz with a 10kΩ load at 5V supplies. This makes the tiny amplifier an excellent choice for automotive audio and low-frequency signal-processing applications.

##### 6.3.1.6 Low Supply Current

The typical 0.5mA supply current of the LMC7101Q-Q1 can help improve thermal performance on high density circuit boards, and can allow the reduction of the overall board size in some applications.

##### 6.3.1.7 Wide Voltage Range

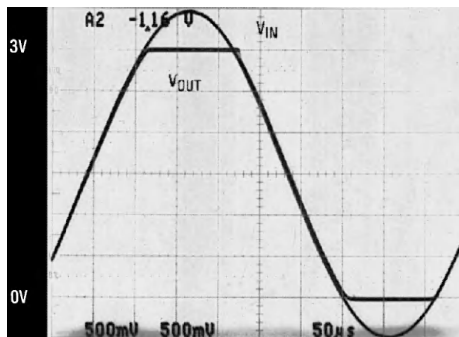
The LMC7101 is characterized at 15V, 5V and 3V. Performance data is provided at these popular voltages. This wide voltage range makes the LMC7101Q-Q1 a good choice for devices where the supply voltage can vary.

## 6.4 Device Functional Modes

### 6.4.1 Input Common-Mode Voltage Range

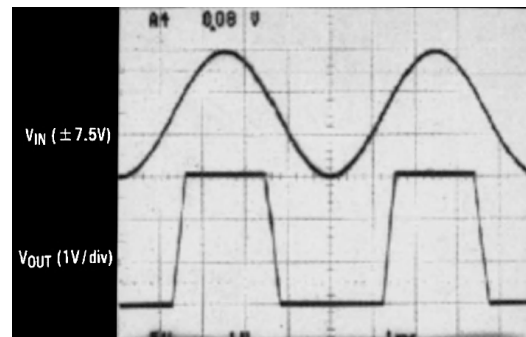
The LMC7101Q-Q1 does not exhibit phase inversion when an input voltage exceeds the negative supply voltage. [Figure 6-1](#) shows an input voltage exceeding both supplies with no resulting phase inversion of the output.

The absolute maximum input voltage is 300mV beyond either rail at room temperature. Voltages greatly exceeding this maximum rating, as in [Figure 6-2](#), can cause excessive current to flow in or out of the input pins, thus adversely affecting reliability.



The input voltage signal exceeds the amplifier power supply voltage with no output phase inversion.

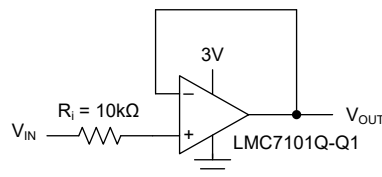
**Figure 6-1. Input Voltage**



The  $\pm 7.5\text{V}$  input signal greatly exceeds the 3V supply in [Figure 6-3](#) causing no phase inversion due to  $R_i$ .

**Figure 6-2. Input Signal**

Applications that exceed this rating must externally limit the maximum input current to  $\pm 5\text{mA}$  with an input resistor as shown in [Figure 6-3](#).



**Figure 6-3.  $R_i$  Input Current Protection for Voltages Exceeding the Supply Voltage**

## 7 Application and Implementation

### 注

以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくこととなります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

### 7.1 Application Information

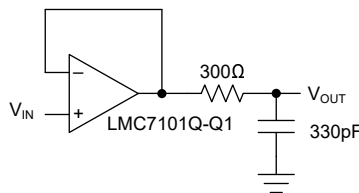
#### 7.1.1 Rail-to-Rail Output

The approximate output resistance of the LMC7101Q-Q1 is  $180\Omega$  sourcing and  $130\Omega$  sinking at  $V_S = 3V$  and  $110\Omega$  sourcing and  $80\Omega$  sinking at  $V_S = 5V$ . Using the calculated output resistance, maximum output voltage swing can be estimated as a function of load.

#### 7.1.2 Capacitive Load Tolerance

The LMC7101Q-Q1 can typically directly drive a  $100\text{pF}$  load with  $V_S = 15V$  at unity gain without oscillating. The unity gain follower is the most sensitive configuration. Direct capacitive loading reduces the phase margin of operational amplifiers. The combination of the output impedance and the capacitive load of the operational amplifier induces phase lag, which results in either an underdamped pulse response or oscillation.

Capacitive load compensation can be accomplished using resistive isolation as shown in [Figure 7-1](#). This simple technique is useful for isolating the capacitive input of multiplexers and A/D converters.



**Figure 7-1. Resistive Isolation of a 330pF Capacitive Load**

### 7.1.3 Compensating for Input Capacitance When Using Large Value Feedback Resistors

When using very large value feedback resistors, (usually >500 kΩ) the large feedback resistance can react with the input capacitance due to transducers, photo diodes, and circuit board parasitics to reduce phase margins.

The effect of input capacitance can be compensated for by adding a feedback capacitor. The feedback capacitor (as in Figure 7-2),  $C_f$  is first estimated by Equation 1 and Equation 2, which typically provides significant overcompensation.

$$\frac{1}{2\pi R_1 C_{IN}} \geq \frac{1}{2\pi R_2 C_f} \quad (1)$$

$$2\pi R_1 C_{IN} \leq 2\pi R_2 C_f \quad (2)$$

Printed circuit board stray capacitance can be larger or smaller than that of a breadboard, so the actual optimum value for  $C_f$  can be different. The values of  $C_f$  must be checked on the actual circuit.

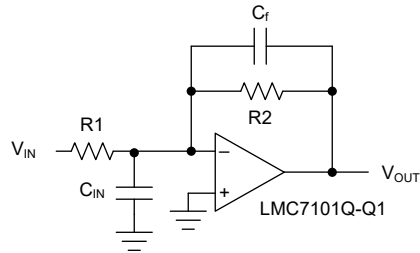


Figure 7-2. Canceling the Effect of Input Capacitance

## 7.2 Typical Application

Figure 7-3 shows a high input impedance noninverting circuit. This circuit gives a closed-loop gain equal to the ratio of the sum of  $R_1$  and  $R_2$  to  $R_1$  and a closed-loop 3dB bandwidth equal to the amplifier unity-gain frequency divided by the closed-loop gain. This design has the benefit of a very high input impedance, which is equal to the differential input impedance multiplied by loop gain (open loop gain / closed loop gain). In dc-coupled applications, input impedance is not as important as input current and the voltage drop across the source resistance. The amplifier output can go into saturation if the input is allowed to float, which can be important if the amplifier must be switched from source to source.

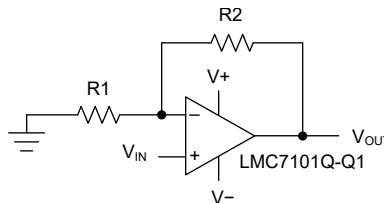


Figure 7-3. Example Application

### 7.2.1 Design Requirements

For this example application, the supply voltage is 5V, and  $100 \times \pm 5\%$  of noninverting gain is necessary. The signal input impedance is approximately 10k $\Omega$ .

### 7.2.2 Detailed Design Procedure

Use the equation for a noninverting amplifier configuration;  $G = 1 + R_2 / R_1$ , set  $R_1$  to 10k $\Omega$ , and  $R_2$  to  $99 \times R_1$ , which is 990k $\Omega$ . Replacing the 990k $\Omega$  resistor with a more readily available 1M $\Omega$  resistor results in a gain of 101, which is within the desired gain tolerance. The gain-frequency characteristic of the amplifier and the feedback network must be such that oscillation does not occur. To meet this condition, the phase shift through amplifier and feedback network must never exceed 180° for any frequency where the gain of the amplifier and the feedback network is greater than unity. In practical applications, the phase shift must not approach 180° because this is the situation of conditional stability. The most critical case occurs when the attenuation of the feedback network is zero.

### 7.2.3 Application Curve

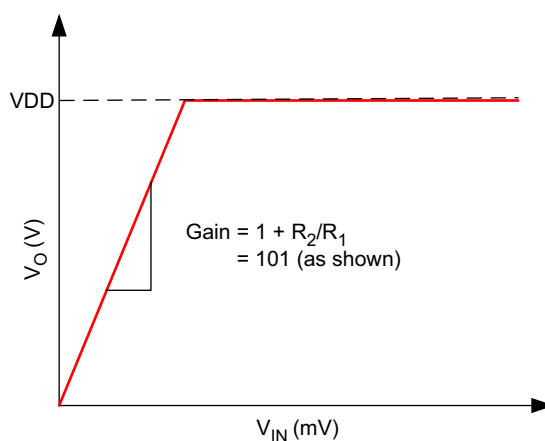


图 7-4. Output Response



### 7.3 Power Supply Recommendations

For proper operation, the power supplies must be decoupled. For supply decoupling, TI recommends placing 10nF to 1μF capacitors as close as possible to the operational-amplifier power supply pins. For single supply configurations, place a capacitor between the V+ and V– supply pins. For dual supply configurations, place one capacitor between V+ and ground, and place a second capacitor between V– and ground. Bypass capacitors must have a low ESR of less than 0.1Ω.

### 7.4 Layout

#### 7.4.1 Layout Guidelines

Care must be taken to minimize the loop area formed by the bypass capacitor connection between supply pins and ground. A ground plane underneath the device is recommended; any bypass components to ground must have a nearby via to the ground plane. The optimum bypass capacitor placement is closest to the corresponding supply pin. Use of thicker traces from the bypass capacitors to the corresponding supply pins can lower the power-supply inductance and provide a more stable power supply.

The feedback components must be placed as close as possible to the device to minimize stray parasitics.

#### 7.4.2 Layout Example

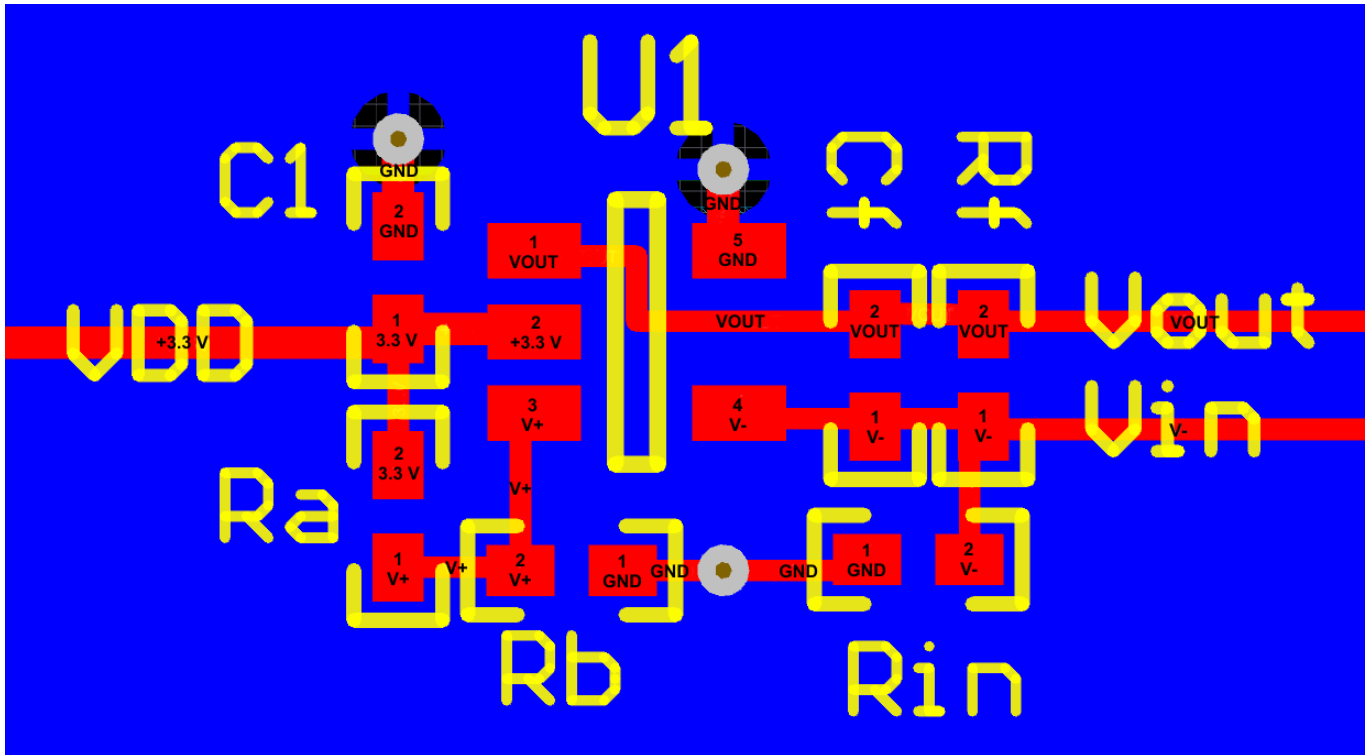


図 7-5. LMC7101Q-Q1 Example Layout

## 8 Device and Documentation Support

### 8.1 Documentation Support

#### 8.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, [LMC66x CMOS Dual Operational Amplifiers data sheet](#)
- Texas Instruments, [RES11A Matched, Thin-Film Resistor Dividers With 1kΩ Inputs data sheet](#)

### 8.2 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、[www.tij.co.jp](http://www.tij.co.jp) のデバイス製品フォルダを開いてください。[通知] をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取ることができます。変更の詳細については、改訂されたドキュメントに含まれている改訂履歴をご覧ください。

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### 8.6 用語集

[テキサス・インスツルメンツ用語集](#) この用語集には、用語や略語の一覧および定義が記載されています。

## 9 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision G (September 2015) to Revision H (January 2025)	Page
• LMC7101 商用デバイスを新しい SBOSAL2 データシートに移動.....	1
• 「特長」を更新 .....	1
• 「概要」を更新 .....	1
• Updated pin diagram figure and pin names in <i>Pin Configuration and Functions</i> .....	2
• Deleted Machine model (MM) from <i>ESD Ratings</i> .....	3
• Changed temperature test conditions from junction temperature, $T_J$ to ambient temperature, $T_A$ throughout...	3
• Updated <i>Thermal Information</i> .....	3
• Updated formatting across all <i>Electrical Characteristics</i> .....	4
• Updated parameter names to be consistent with modern data sheets.....	4
• Added missing input offset voltage drift temperature condition in all <i>Electrical Characteristics</i> .....	4
• Updated temperature range conditions in input bias current and input offset current in all Electrical Characteristics.....	4

• Changed input common-mode voltage condition from CMRR ≥ 50dB to CMRR ≥ 47dB.....	4
• Changed CMRR MIN from 50dB to 47dB.....	4
• Deleted footnotes 1 and 2 in all <i>Electrical Characteristics</i> .....	4
• Changed input common-mode voltage condition from CMRR > 50dB to CMRR > 47dB.....	5
• Changed CMRR MIN from 60dB to 47dB and TYP from 74dB to 70dB .....	5
• Changed CMRR MIN from 60dB to 52dB and TYP from 82dB to 75dB.....	6
• Changed CMRR MIN for T <sub>A</sub> = –40°C to +125°C from 60dB to 51dB and TYP from 82dB to 74dB.....	6
• Changed input common-mode voltage test condition from (V+) = 5V to (V+) = 15V.....	7
• Changed CMRR MIN from 65dB to 62dB.....	7
• Deleted Figures 6, 11, 14, 17, 20, 23, and 37.....	9
• Added Figure 5-6.....	9
• Added Figures 5-21 and 5-25.....	13
• Updated description text in <i>Size</i> .....	20
• Updated Figure 7-3, <i>Example Application</i> to show correct noninverting circuit.....	23

**Changes from Revision F (March 2013) to Revision G (September 2015) Page**

• 「ピン構成および機能」、「ESD 定格」、「機能説明」、「デバイスの機能モード」、「アプリケーションと実装」、「電源に関する推奨事項」、「レイアウト」、「デバイスおよびドキュメントのサポート」、「メカニカル、パッケージ、および注文情報」の各セクションを追加 .....	1
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**Changes from Revision E (March 2013) to Revision F (March 2013) Page**

• Changed layout of National Semiconductor Data Sheet to TI format.....	23
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## 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LMC7101QM5/NOPB	OBSOLETE	SOT-23	DBV	5		TBD	Call TI	Call TI	-40 to 125	AT6A	
LMC7101QM5X/NOPB	ACTIVE	SOT-23	DBV	5	3000	RoHS & Green	Call TI   SN	Level-1-260C-UNLIM	-40 to 125	AT6A	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

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**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

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(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMC7101QM5X/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMC7101QM5X/NOPB	SOT-23	DBV	5	3000	208.0	191.0	35.0

DBV0005A



PACKAGE OUTLINE

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



4214839/K 08/2024

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
5. Support pin may differ or may not be present.



# EXAMPLE BOARD LAYOUT

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

4214839/K 08/2024

NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:15X

4214839/K 08/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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